Let's say that we have to programs A and B. If they behave in the same way on all input it is natural to say that they are equivalent.

A model of computation is an abstract and usually simplified way of describing algorithms. The idea is that, given any algorithm A in any programming language or any other way of presenting algorithms, there should be an algorithm A' in the computational model such that A and A' are equivalent.

Even if two algorithms are equivalent they can have different running times.

A model of computation will be useful when we:

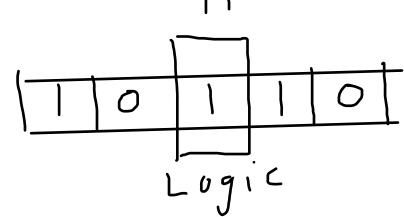
- *Want to define exactly what the complexity for an algorithm is.
- *Want to find the limits for what algorithms can do.
- .*Prove Cook's theorem.

One of the oldest but still most useful models of computation is the Turing Machine.

The Turing Machine

We will use a very simplified model of computation. It's the *Turing Machine*.

We will consider data as a semi-finite tape with 0 and 1 written: \square

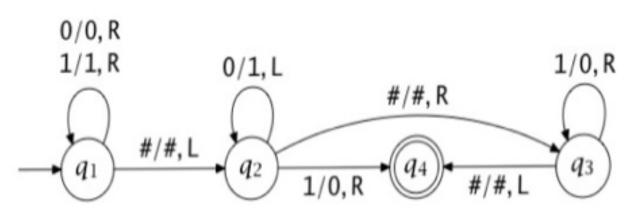


Reading and writing can be done one digit at a time. The ''Head'' can be moved just one step to the right or left at a time.

The logic tells us how the head should be moved and what should be written on the tape. The logic consists of a finite set of states and a finite set of transition rules.

Example of a Turing Machine

The following TM reads the number x on binary form from the tape and changes it to max(x-1,0).



Notation:

- Circles correspond to states
- Dubble circles correspond to accepting states
- Arrows indicates transition rules:
- a/b, L means "if the head reads a, do the transition, write b and move the head one to the left"

(in a/b, R R means move to the right)

The arrow with no starting node indicates the state the machine starts in.

Rules for the Turing Machine

- The machine starts in the starting state.
- At start the head reads the first symbol to the left in the input string. The input is marked off by empty positions (indicated by #).
- There must not be several different transitions from the same state reading the same symbol (determinism).
- If the machine gets into an accepting state the computation ends and the machine returns "Yes".
- If the machine gets into a state and reads a symbol with no matching transition the computation ends and the machine returns "No".

The previous rules describe computations when the answer is yes/no. Turing Machines can do other computations as well. The first example shows this. (The algorithm that computes max(x-1,O).) This is an algorithm of the form A(n) = m, where n and m are integers. As we have seen, Turing Machines can handle them in a rather natural way.

Formal description

- A Turing Machine is defined by
 - The alphabet Σ (must be finite)
 - The set Q of states (must be finite)
 - The start state $q_0 \in Q$
 - The set $F \subseteq Q$ of accepting states
 - The transition relation $\Delta \subseteq Q \times \Sigma \times Q \times \Sigma \times \{L, R, S\}$

Church's thesis

Any algorithmic problem that can be solved by any program written in any language and run on any computer can be solved by a Turing Machine.

- The Halting Problem is undecidable even for Turing Machines.
- The Turing Machine can be used as a computational model for reasoning about uncomputability.
- The Halting Problem is undecidable in any computational model powerful enough to simulate a Turing Machine.

The computational model RAM is Turing Equivalent as are all modern programming languages.

Equally powerful variants of the Turing Machine

- A different (finite) alphabet.
- Separate tap for output.
- Several different tapes.
- Several different heads.
- Half-infinite tape (infinite in just one direction).

All these variants are equivalent yo to normal Turing Machine in the sense that the running time differ by at most a polynomial factor.

Non-deterministic Turing Machines

- In the non-deterministic case there can be several possible transitions from a state and a given symbol. In that case, the machine makes a non-deterministic choice.
- If there is a sequence of choices leading to an accepting state we say that the machine accepts.
- If there is no sequence of choices leading to an accepting state we say that the machine *rejects*.

Non-determinism cont.

Non-deterministic Turing Machines can be used to define NP:

This class contains exactly the problems (or rather their languages) to which there is an non-deterministic TM that accepts in polynomial time.

NP = Non-deterministic Polynomial time

One believes that non-deterministic machines are more powerful than deterministic ones in the sense that:

$\mathbf{P} \neq \mathbf{NP}$.

Cook's Theorem

Cook's Theorem says that the problem SAT is NP-Complete.

Input to SAT is a propositional logic formula Φ and the problem is to decide if the formula is satisfiable or not.

Proof of Cook's Theorem (Sketch):

SAT \in **NP** since, given an variable assignment, we can check in polynomial time if the formula is satisfied or not.

We must show that SAT Is NP-Hard, i.e. if om $Q' \in \mathbf{NP}$ then $Q' \leq_P SAT$.

Since $Q' \in \mathbf{NP}$ there is a non-deterministic Turing Machine M that accepts the language Q' in at most kn^c steps where n is the number of variables. Proof idea:

Construct a formula such that it is satisfied if and only if M accepts the input string.

We assume that M has an input tape that is infinite to the right and uses the alphabet $\{0, 1, \#\}$.

We enumerate M:s time steps from 1 to kn^c . At each time step t the computation is described by

- the position of the head
- the state q
- the content of the tape in positions $1 kn^c$

In our formula we use the following variables:

 $\begin{array}{ll} x_{qt} & q \in Q, \ 1 \leq t \leq kn^c \\ y_{ijt} & i \in \{0, 1, \#\}, 1 \leq j \leq kn^c, 1 \leq t \leq kn^c \\ z_{jt} & 1 \leq j \leq kn^c, 1 \leq t \leq kn^c \end{array}$

Interpretation:

 $\begin{array}{ll} x_{qt} = 1 & \text{iff } M \text{ is in state } q \text{ at time } t \\ y_{ijt} = 1 & \text{iff the symbol } i \text{ is in position } j \text{ at time } t \\ z_{jt} = 1 & \text{iff the head stands in position } j \text{ at time } t \end{array}$

If there is an accepting computation for $M(a_1, \ldots, a_n)$ running kn^c steps, then this corresponds to:

- 1. The computation starts with a_1, \ldots, a_n
- 2. x, y, z describes a correct computation
- The computation ends in an accepting state.

All these constraints can be expressed by a single SAT-Formula of size polynomial in n.

This gives us an reduction $Q \leq_P SAT$ for every NP-Problem Q and this shows that SAT is NP-Complete.

To every Turing Machine T we can associate the code k(T) of the machine. If we have input x we say that T(x) is the result of the computation whatever form i might have. It is possible to construct a Turing Machine U that take two strings as input such that

U(k(T), x) = T(x) for all Turing Machines T.

This means that U can simulate every Turing Machine.

It little informal, we can write U(T, x) = T(x).