

## LINEAR-TIME TEMPORAL LOGIC

We are interested in temporal properties of program behaviour, i.e. properties over state sequences, like that some "bad" state (expressed as a state property) is never reached, or that some state property holds until some other state property becomes true, etc.

Our theoretical set-up will be:

Models :	transition systems $\mathcal{M}$
Specs :	LTL formulas $\phi$
Correctness :	$\mathcal{M}, s \models \phi$
Verification :	automata-based, language inclusion

On the practical side we will use the Spin model checker.

### LTL Syntax

The logic is built on top of a set of atomic propositions

Atoms, used to denote state properties. The logic uses  
 propositional constants:  $\top, \perp$       atoms:  $p \in \text{Atoms}$

propositional connectives:  $\neg, \wedge, \vee, \rightarrow$

temporal connectives:  $X, G, F, U$   
                                   next                    globally                    future                    until

Example formulas:

$Fp, GFp, G(p \rightarrow Fq), pUq$

The formulas of LTL are defined inductively as follows:

$$\begin{aligned} \phi ::= & \top \mid \perp \mid p \mid (\neg\phi) \mid (\phi \wedge \phi) \mid (\phi \vee \phi) \mid (\phi \rightarrow \phi) \mid \\ & (X\phi) \mid (F\phi) \mid (G\phi) \mid (\phi U \phi) \\ & \quad \circ \quad \diamond \quad \square \end{aligned}$$

Binding convention:

strongest:  $\neg, X, F, G$

next:  $U$

then:  $\wedge, \vee$

weakest:  $\rightarrow$

So,  $GFp \rightarrow F(qvs)$  abbreviates  $((G(Fp)) \rightarrow (F(qvs)))$ .

The notions of parse tree and subformula are standard.

## LTL Semantics

Models for LTL-formulas are structures called transition systems, or Kripke structures, or just models.

Definition A transition system is a tuple  $\mathcal{M} = (S, \rightarrow, L)$

(i)  $S$  is a set of states,

(ii)  $\rightarrow \subseteq S \times S$  is a transition relation,

(iii)  $L: S \rightarrow 2^{\text{Atoms}}$  is a labelling function.

In the context of LTL we usually require every state to have at least one successor state, since we are only considering infinite state sequences.

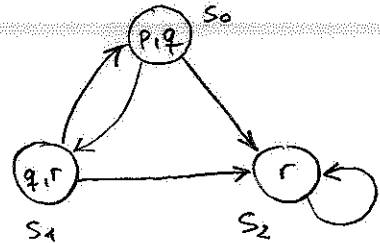
Models with a small number of states are easily presented graphically; for example:

$$\text{Atoms} = \{p, q, r\}$$

$$S = \{s_0, s_1, s_2\}$$

$$\rightarrow = \{(s_0, s_1), (s_0, s_2), (s_1, s_0), (s_1, s_2), (s_2, s_2)\}$$

$$L = \{(s_0, \{p, q\}), (s_1, \{q, r\}), (s_2, \{r\})\}$$



A path of  $\mathcal{M} = (S, \rightarrow, L)$  is an infinite sequence of states

$$\pi = s_0 s_1 s_2 \dots \text{ such that } s_i \rightarrow s_{i+1} \text{ for all } i \geq 0.$$

We denote by  $\pi(i)$  the  $i$ -th element  $s_i$  of  $\pi$ ,

and by  $\pi^i$  the  $i$ -th suffix  $s_i s_{i+1} s_{i+2} \dots$  of  $\pi$ .

How do the paths / runs / executions of the above example model look like, starting from  $s_0$ ? SCCs.

The formal semantics of LTL is given in terms of a satisfaction relation  $\mathcal{M}, \pi \models \phi$  inducing another satisfaction relation  $\mathcal{M}, s \models \phi$ .

Definition Let  $\mathcal{M} = (S, \rightarrow, L)$  be a model, and

let  $\pi = s_0 s_1 s_2 \dots$  be a path of  $\mathcal{M}$ . The satisfaction relation

$\pi \models \phi$  is defined inductively as follows: (incomplete)

$$\pi \models p \stackrel{\text{def}}{\iff} p \in L(\pi(0))$$

$$\pi \models X\phi \stackrel{\text{def}}{\iff} \pi^1 \models \phi$$

$$\pi \models G\phi \stackrel{\text{def}}{\iff} \forall i \geq 0. \pi^i \models \phi$$

$$\pi \models F\phi \stackrel{\text{def}}{\iff} \exists i \geq 0. \pi^i \models \phi$$

$$\pi \models \phi \cup \psi \stackrel{\text{def}}{\iff} \exists i \geq 0. (\pi^i \models \psi \text{ and } \forall j < i. \pi^j \models \phi)$$

We say that model  $\mathcal{M}$  satisfies formula  $\phi$  at state  $s \in S$ , denoted  $\mathcal{M}, s \models \phi$ , if all paths  $\pi$  of  $\mathcal{M}$  starting at  $s$  satisfy  $\phi$ , i.e.  $\mathcal{M}, \pi \models \phi$  whenever  $\pi(0) = s$ .

As an example, consider the model above, and the formulas

$$q, r, Xq, Xr, Gq, G(q \vee r), Fq, Fr,$$

$$G(r \rightarrow Gr), Gq \vee Gr, GF(p \vee r), pUr, qUr$$

all at  $s_0$ . Find counter-examples in the form of paths.

An important observation about the semantics is that the significant information of a path is the sequence of state valuations rather than the states themselves. So, we can define the notions valuation  $v \subseteq \text{Atoms}$  and valuation

sequence  $p = v_0 v_1 v_2 \dots$  and define satisfaction  $\mathcal{M}, p \models \phi$  as:

$$p \models p \stackrel{\text{def}}{\iff} p \in p(0) \quad (\text{only difference})$$

Then, satisfaction  $\mathcal{M}, \pi \models \phi$  can be viewed as a derived notion:

$$\mathcal{M}, \pi \models \phi \stackrel{\text{def}}{\iff} \mathcal{M}, p_\pi \models \phi$$

where  $p_\pi$  is the valuation sequence induced by  $\pi$  via  $L$ .

Here are some practical specification patterns:

$G(\text{request} \rightarrow F\text{response})$

every request is eventually served

$GF \text{ enabled}$

infinitely often enabled

$FG \text{ deadlock}$

eventually stable deadlock

$GF \text{ enabled} \rightarrow GF \text{ running}$

$G(\text{start} \rightarrow X(\text{running} \cup \text{stop}))$

LTL equivalences

We say that two LTL formulas  $\phi$  and  $\psi$  are semantically equivalent, denoted  $\phi \equiv \psi$ , if

$$\mathcal{M}, \pi \models \phi \Leftrightarrow \mathcal{M}, \pi \models \psi$$

in every path  $\pi$  of every model  $\mathcal{M}$ .

$$\neg G\phi \equiv F\neg\phi \quad \neg F\phi \equiv G\neg\phi \quad \neg X\phi \equiv X\neg\phi$$

$$G(\phi \wedge \psi) \equiv G\phi \wedge G\psi \quad F(\phi \vee \psi) \equiv F\phi \vee F\psi$$

$$G\phi \equiv \neg(TU\neg\phi) \quad F\phi \equiv TU\phi$$

Here is a proof of  $G\phi \equiv \neg(TU\neg\phi)$  by referring to the formal semantics of LTL: Let  $\pi$  be an arbitrary path of an arbitrary model  $\mathcal{M}$ . Then

$$\begin{aligned} \pi \models \neg(TU\neg\phi) &\Leftrightarrow \text{not } \pi \models TU\neg\phi \\ &\Leftrightarrow \text{not } \exists i \geq 0. (\pi^i \models \neg\phi \text{ and } \forall j < i. \pi^j \models T) \\ &\Leftrightarrow \text{not } \exists i \geq 0. \pi^i \models \neg\phi \\ &\Leftrightarrow \text{not } \exists i \geq 0. (\text{not } \pi^i \models \phi) \\ &\Leftrightarrow \forall i \geq 0. \pi^i \models \phi \\ &\Leftrightarrow \pi \models G\phi \end{aligned}$$

Minimal presentation of LTL:  $\phi, \neg, \wedge, \vee, X, U$

$$G\phi \equiv \phi \wedge XG\phi \quad F\phi \equiv \phi \vee XF\phi \quad \phi U \psi \equiv \psi \vee (\phi \wedge X(\phi U \psi))$$