

Chapter 10: Boosting and Additive Trees

DD3364

November 20, 2012

Boosting Methods

- Boosting is a procedure to combine the output of many **weak** classifiers to produce a powerful **committee**.
- A weak classifier is one whose error rate is only slightly better than random guessing.
- Boosting produces a sequence of weak classifiers $G_m(x)$ for $m = 1, \dots, M$ whose predictions are then combined

$$G(x) = \text{sgn} \left(\sum_{m=1}^M \alpha_m G_m(x) \right)$$

through a weighted majority to produce the final prediction.

- Each $\alpha_m > 0$ is computed by the boosting algorithm and reflects how accurately G_m classified the data.

Most popular boosting algorithm: AdaBoost.M1

“**AdaBoost.M1**” algorithm of *Freund and Schapire* (1997)

- Have training data $(x_i, y_i), i = 1, 2, \dots, n$
- Introduce a weight $w_i = 1/n$ for each training example.
- for $m = 1, \dots, M$
 - ★ Let G_m be the weak classifier with minimum error:

$$\text{err}_m = \sum_{i=1}^n w_i \text{Ind}(y_i \neq G_m(x_i))$$

★ Set $\alpha_m = \log((1 - \text{err}_m)/\text{err}_m)$.

★ Set

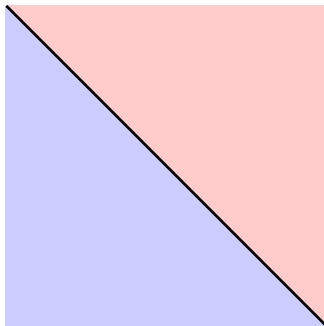
$$w_i \leftarrow w_i e^{\alpha_m \text{Ind}(y_i \neq G_m(x_i))} \quad \text{for } i = 1, \dots, n$$

This increases (decreases) w_i for x_i misclassified (correctly classified) by G_m

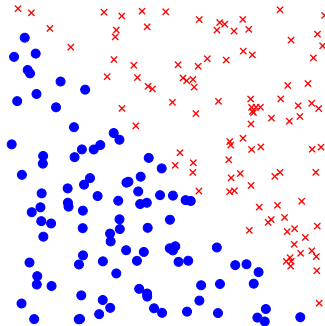
★ Normalize the w_i 's so that they sum to one.

- As iterations proceed, observations difficult to classify correctly receive more influence.
- Each successive classifier is forced to concentrate on training observations missed by previous ones in the sequence

Binary classification example



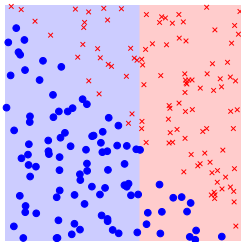
True decision boundary



Training data

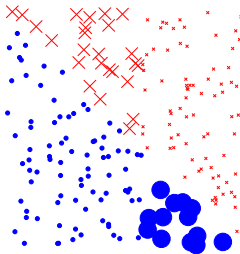
\mathcal{H} is the set of all possible oriented vertical and horizontal lines.

Round 1



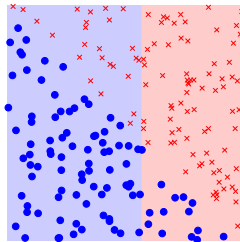
Chosen weak classifier

$$\epsilon_1 = 0.19, \alpha_1 = 1.45$$



Re-weight training points

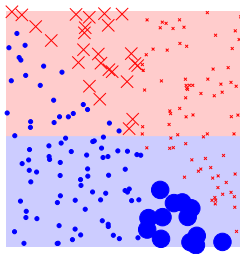
$$w_i^{(2)}, \mathbf{s}$$



Current strong classifier

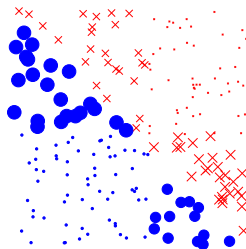
$$G(\mathbf{x})$$

Round 2



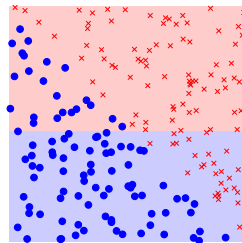
Chosen weak classifier

$$\epsilon_2 = 0.1512, \alpha_2 = 1.725$$



Re-weight training points

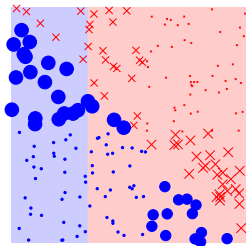
$$w_i^{(3)}\text{'s}$$



Current strong classifier

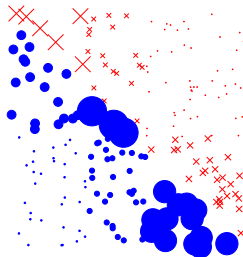
$$G(\mathbf{x})$$

Round 3



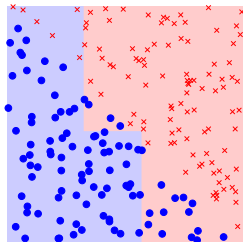
Chosen weak classifier

$$\epsilon_3 = 0.2324, \alpha_3 = 1.1946$$



Re-weight training points

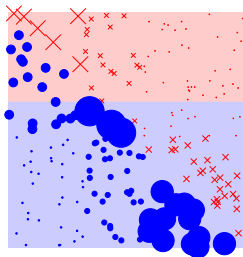
$$w_i^{(4)}, \mathbf{s}$$



Current strong classifier

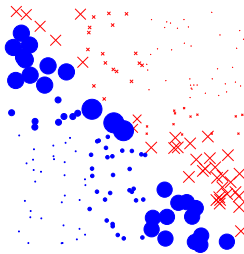
$$G(\mathbf{x})$$

Round 4



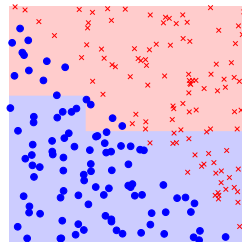
Chosen weak classifier

$$\epsilon_4 = 0.2714, \alpha_4 = 0.9874$$



Re-weight training points

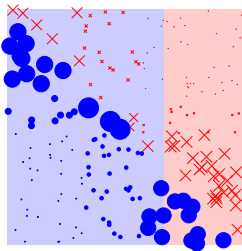
$$w_i^{(5)}, s$$



Current strong classifier

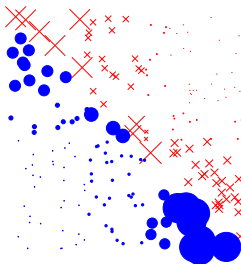
$$G(\mathbf{x})$$

Round 5



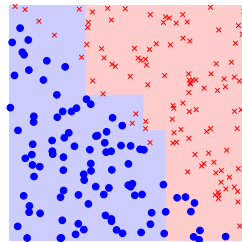
Chosen weak classifier

$$\epsilon_5 = 0.2616, \alpha_5 = 1.0375$$



Re-weight training points

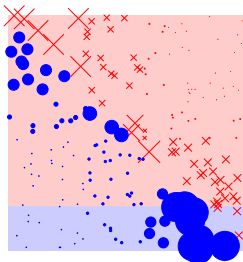
$$w_i^{(6)}\text{'s}$$



Current strong classifier

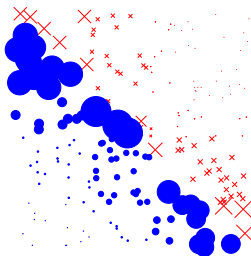
$$G(\mathbf{x})$$

Round 6



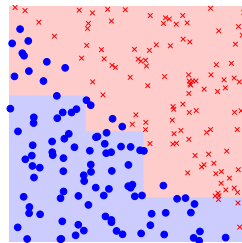
Chosen weak classifier

$$\epsilon_6 = 0.2262, \alpha_6 = 1.2298$$



Re-weight training points

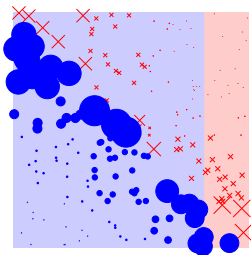
$$w_i^{(7)}\text{'s}$$



Current strong classifier

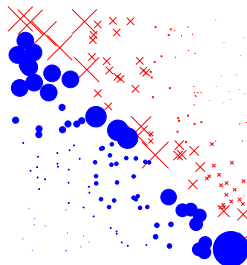
$$G(\mathbf{x})$$

Round 7



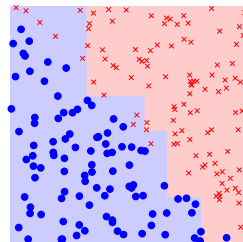
Chosen weak classifier

$$\epsilon_7 = 0.2680, \alpha_7 = 1.0049$$



Re-weight training points

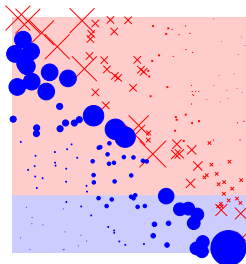
$$w_i^{(8)} \mathbf{s}$$



Current strong classifier

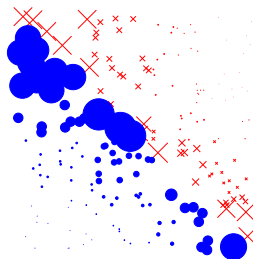
$$G(\mathbf{x})$$

Round 8



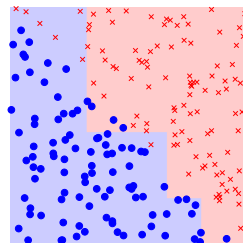
Chosen weak classifier

$$\epsilon_8 = 0.3282, \alpha_8 = 0.7165$$



Re-weight training points

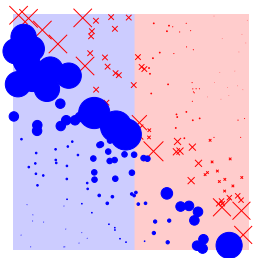
$$w_i^{(9)} \mathbf{x}$$



Current strong classifier

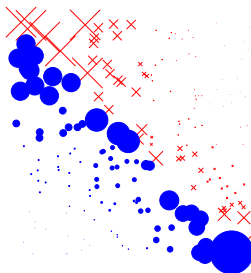
$$G(\mathbf{x})$$

Round 9



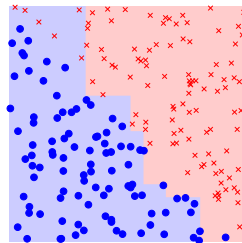
Chosen weak classifier

$$\epsilon_9 = 0.3048, \alpha_9 = 0.8246$$



Re-weight training points

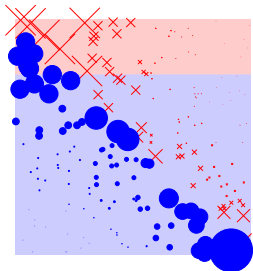
$$w_i^{(10)}, s$$



Current strong classifier

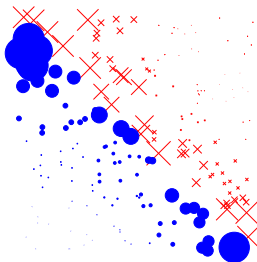
$$G(\mathbf{x})$$

Round 10



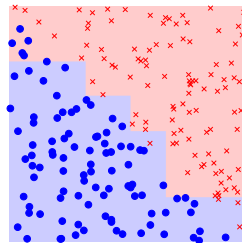
Chosen weak classifier

$$\epsilon_{10} = 0.2943, \alpha_{10} = 0.8744$$



Re-weight training points

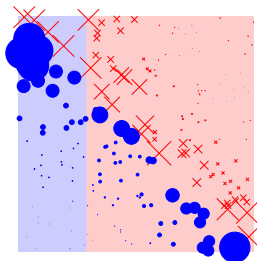
$$w_i^{(11)}, s$$



Current strong classifier

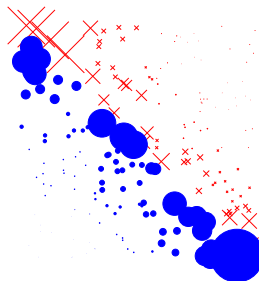
$$G(\mathbf{x})$$

Round 11



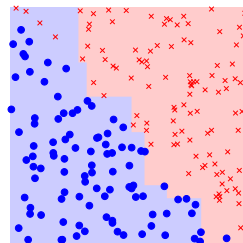
Chosen weak classifier

$$\epsilon_{11} = 0.2876, \alpha_{11} = 0.9071$$



Re-weight training points

$$w_i^{(12)}, \mathbf{s}$$

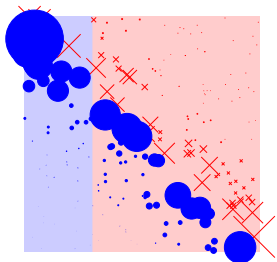


Current strong classifier

$$G(\mathbf{x})$$

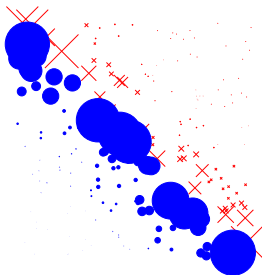
.....

Round 21



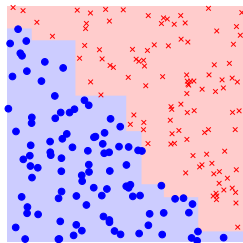
Chosen weak classifier

$$\epsilon_{21} = 0.3491, \alpha_{21} = 0.6232$$



Re-weight training points

$$w_i^{(22)}, \mathbf{s}$$



Current strong classifier

$$G(\mathbf{x})$$

AdaBoost can dramatically increase the performance of very weak classifier.

- Show AdaBoost fits an additive model in a base learner, optimizing a novel exponential loss function
- Show the population minimizer of the exponential loss function is the log-odds of the class probabilities
- Present loss functions that are more robust than squared error or exponential loss
- Argue decision trees are an ideal base learner for data mining applications of boosting.
- Develop class of gradient boosted models (GBMs), for boosting trees with any loss function.
- Emphasize the importance of “*slow learning*”.

Boosting Fits an Additive Model

- Boosting fits an additive expansion in a set of elementary *basis functions*.

$$G(x) = \operatorname{sgn} \left(\sum_{m=1}^M \alpha_m G_m(x) \right)$$

- The basis functions are the weak classifiers $G_m(x) \in \{-1, 1\}$.
- More generally, basis function expansions take the form

$$f(x) = \sum_{m=1}^M \beta_m b(x; \gamma_m)$$

where β_m 's are the expansion coefficients and $b(x; \gamma) \in \mathbb{R}$ are simple functions of the input x parameterized by γ .

- **Single-hidden-layer neural networks** where

$$b(x; \gamma) = \frac{1}{1 + \exp(-\gamma_0 - \gamma_1^t x)}$$

- **Multivariate adaptive regression splines (MARS)**

Use truncated-power spline basis functions where γ parameterizes the variables and values for the knots.

- **Trees**

γ parameterizes the split variables and split points at the internal nodes, and the predictions at the terminal nodes.

- Typically fit model by minimizing a loss function averaged over the training data:

$$\min_{\beta_1, \gamma_1, \dots, \beta_M, \gamma_M} \sum_{i=1}^n L \left(y_i, \sum_{m=1}^M \beta_m b(x_i; \gamma_m) \right)$$

- For many loss functions $L(x, f(x))$ and/or basis functions $b(x; \gamma)$ this is too hard....

Forward Stagewise Additive Modeling

Approximate the global solution to fitting additive model

- More simply can greedily add one basis function at a time in the following fashion.
- Set $f_0(x) = 0$
- for $m = 1, \dots, M$
 - ★ Compute

$$(\hat{\beta}_m, \hat{\gamma}_m) = \arg \min_{\beta_m, \gamma_m} \sum_{i=1}^n L \left(y_i, \sum_{m=1}^M f_{m-1}(x_i) + \beta_m b(x_i; \gamma_m) \right)$$

- ★ Set

$$f_m(x) = f_{m-1}(x) + \hat{\beta}_m b(x; \hat{\gamma}_m)$$

- ★ **Note:** Previously added terms are not modified.

Exponential Loss and AdaBoost

Interpretation of the Adaboost algorithm

- **Interpretation of AdaBoost.M1**

AdaBoost.M1 \equiv **forward stagewise additive modelling**
with an **exponential loss function**.

- Definition of exponential loss

$$L(y, f(x)) = \exp\{-y f(x)\}$$

- Will now go through the derivation of this result....

Interpretation of the Adaboost algorithm

- **Interpretation of AdaBoost.M1**

AdaBoost.M1 \equiv **forward stagewise additive modelling**
with an **exponential loss function**.

- Definition of exponential loss

$$L(y, f(x)) = \exp\{-y f(x)\}$$

- Will now go through the derivation of this result....

Specifics of forward stagewise additive modelling (fsam)

- At each iteration of **forward stagewise additive modelling** must solve this optimization problem

$$\begin{aligned}(\beta_m, G_m) &= \arg \min_{\beta, G} \sum_{i=1}^n L(y_i, f_{m-1}(x_i) + \beta G(x_i)) \\ &= \arg \min_{\beta, G} \sum_{i=1}^n \exp\{-y_i (f_{m-1}(x_i) + \beta G(x_i))\}\end{aligned}$$

where we assume an exponential loss and $G(x) \in \{-1, 1\}$.

- Can re-write

$$\begin{aligned}\sum_{i=1}^n \exp\{-y_i (f_{m-1}(x_i) + \beta G(x_i))\} &= \sum_{i=1}^n \exp\{-y_i f_{m-1}(x_i)\} \exp\{-y_i \beta G(x_i)\} \\ &= \sum_{i=1}^n w_i^{(m)} \exp\{-y_i \beta G(x_i)\}\end{aligned}$$

Optimization of the fsam cost function

- The optimization problem becomes

$$\min_{\beta, G} \sum_{i=1}^n w_i^{(m)} \exp\{-y_i \beta G(x_i)\} = \min_{\beta} \left(\min_G \sum_{i=1}^n w_i^{(m)} \exp\{-y_i \beta G(x_i)\} \right)$$

- Note

$$y_i G(x_i) = \begin{cases} 1 & \text{if } y_i = G(x_i) \\ -1 & \text{if } y_i \neq G(x_i) \end{cases}$$

and this implies $\exp\{-y_i \beta G(x_i)\}$ is equal to

$$e^{\beta} \text{Ind}(y_i \neq G(x_i)) + e^{-\beta} (1 - \text{Ind}(y_i \neq G(x_i)))$$

- The above implies $\sum_{i=1}^n w_i^{(m)} \exp\{-y_i \beta G(x_i)\}$ can be written as:

$$(e^{\beta} - e^{-\beta}) \sum_{i=1}^n w_i^{(m)} \text{Ind}(y_i \neq G(x_i)) + e^{-\beta} \sum_{i=1}^n w_i^{(m)}$$

Optimization of the fsam cost function: G_m ?

- The optimization problem becomes

$$\begin{aligned} & \arg \min_G \sum_{i=1}^n w_i^{(m)} \exp\{-y_i \beta G(x_i)\} \\ &= \arg \min_G \left((e^\beta - e^{-\beta}) \sum_{i=1}^n w_i^{(m)} \text{Ind}(y_i \neq G(x_i)) + e^{-\beta} \sum_{i=1}^n w_i^{(m)} \right) \\ &= \arg \min_G \left(\sum_{i=1}^n w_i^{(m)} \text{Ind}(y_i \neq G(x_i)) \right) \end{aligned}$$

- Therefore

$$G_m = \arg \min_G \left(\sum_{i=1}^n w_i^{(m)} \text{Ind}(y_i \neq G(x_i)) \right)$$

G_m minimizes the **weighted error** in the AdaBoost algorithm. (if the $w_i^{(m)}$'s have the same definition....)

Optimization of the fsam cost function: G_m ?

- The optimization problem becomes

$$\begin{aligned} & \arg \min_G \sum_{i=1}^n w_i^{(m)} \exp\{-y_i \beta G(x_i)\} \\ &= \arg \min_G \left((e^\beta - e^{-\beta}) \sum_{i=1}^n w_i^{(m)} \text{Ind}(y_i \neq G(x_i)) + e^{-\beta} \sum_{i=1}^n w_i^{(m)} \right) \\ &= \arg \min_G \left(\sum_{i=1}^n w_i^{(m)} \text{Ind}(y_i \neq G(x_i)) \right) \end{aligned}$$

- Therefore

$$G_m = \arg \min_G \left(\sum_{i=1}^n w_i^{(m)} \text{Ind}(y_i \neq G(x_i)) \right)$$

G_m minimizes the **weighted error** in the AdaBoost algorithm. (if the $w_i^{(m)}$'s have the same definition....)

Optimization of the fsam cost function: β_m ?

- Plugging G_m into the original optimization problem

$$\min_{\beta} \left(\min_G \sum_{i=1}^n w_i^{(m)} \exp\{-y_i \beta G(x_i)\} \right)$$

and using the previous result, it becomes

$$\arg \min_{\beta} \left((e^{\beta} - e^{-\beta}) \sum_{i=1}^n w_i^{(m)} \text{Ind}(y_i \neq G_m(x_i)) + e^{-\beta} \sum_{i=1}^n w_i^{(m)} \right)$$

- This quantity is minimized when

$$\beta_m = \frac{1}{2} \log \frac{1 - \text{err}_m}{\text{err}_m}$$

where

$$\text{err}_m = \frac{\sum_{i=1}^n w_i^{(m)} \text{Ind}(y_i \neq G_m(x_i))}{\sum_{i=1}^n w_i^{(m)}}$$

- Expression for β_m same (upto a multiplicative constant) as for α_m in AdaBoost.M1 (if the $w_i^{(m)}$'s have same definition....)

Optimization of the fsam cost function: β_m ?

- Plugging G_m into the original optimization problem

$$\min_{\beta} \left(\min_G \sum_{i=1}^n w_i^{(m)} \exp\{-y_i \beta G(x_i)\} \right)$$

and using the previous result, it becomes

$$\arg \min_{\beta} \left((e^{\beta} - e^{-\beta}) \sum_{i=1}^n w_i^{(m)} \text{Ind}(y_i \neq G_m(x_i)) + e^{-\beta} \sum_{i=1}^n w_i^{(m)} \right)$$

- This quantity is minimized when

$$\beta_m = \frac{1}{2} \log \frac{1 - \text{err}_m}{\text{err}_m}$$

where

$$\text{err}_m = \frac{\sum_{i=1}^n w_i^{(m)} \text{Ind}(y_i \neq G_m(x_i))}{\sum_{i=1}^n w_i^{(m)}}$$

- **Expression for β_m same (upto a multiplicative constant) as for α_m in AdaBoost.M1** (if the $w_i^{(m)}$'s have same definition....)

Optimization of the fsam cost function: $w_i^{(m)}$?

Update of the weights: Expression for $w_i^{(m+1)}$

- Need the following result

$$\begin{aligned} -y_i G_m(x_i) &= -\text{Ind}(y_i = G(x_i)) + \text{Ind}(y_i \neq G(x_i)) \\ &= -(1 - \text{Ind}(y_i \neq G(x_i))) + \text{Ind}(y_i \neq G(x_i)) \\ &= -1 + 2 \text{Ind}(y_i \neq G(x_i)) \end{aligned}$$

- The updated weights can then be written as

$$\begin{aligned} w_i^{(m+1)} &= e^{-y_i f_m(x_i)} = e^{-y_i (f_{m-1}(x) + \beta_m G_m(x))} \\ &= w_i^{(m)} e^{-y_i \beta_m G_m(x)} \\ &= w_i^{(m)} e^{2\beta_m \text{Ind}(y_i \neq G_m(x))} e^{-\beta_m} \end{aligned}$$

- As factor $e^{-\beta_m}$ is the same for all weights it has no effect.
- Expression for weight update for each example is the same as for AdaBoost.M1 as $\alpha_m = 2\beta_m$.

Optimization of the fsam cost function: $w_i^{(m)}$?

Update of the weights: Expression for $w_i^{(m+1)}$

- Need the following result

$$\begin{aligned}-y_i G_m(x_i) &= -\text{Ind}(y_i = G(x_i)) + \text{Ind}(y_i \neq G(x_i)) \\ &= -(1 - \text{Ind}(y_i \neq G(x_i))) + \text{Ind}(y_i \neq G(x_i)) \\ &= -1 + 2 \text{Ind}(y_i \neq G(x_i))\end{aligned}$$

- The updated weights can then be written as

$$\begin{aligned}w_i^{(m+1)} &= e^{-y_i f_m(x_i)} = e^{-y_i (f_{m-1}(x) + \beta_m G_m(x))} \\ &= w_i^{(m)} e^{-y_i \beta_m G_m(x)} \\ &= w_i^{(m)} e^{2\beta_m \text{Ind}(y_i \neq G_m(x))} e^{-\beta_m}\end{aligned}$$

- As factor $e^{-\beta_m}$ is the same for all weights it has no effect.
- **Expression for weight update for each example is the same as for AdaBoost.M1 as $\alpha_m = 2\beta_m$.**

Adaboost minimizes the exponential loss

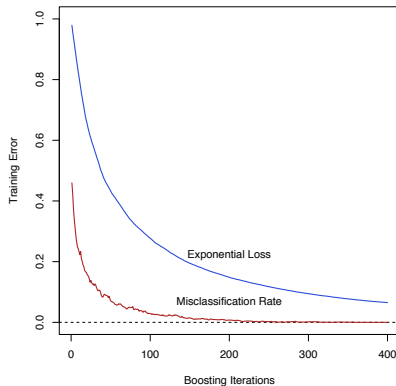
- Hence can view **AdaBoost.M1** as a method that approximates minimizing

$$\arg \min_{\beta_1, G_1, \dots, \beta_M, G_M} \sum_{i=1}^n \exp \left(-y_i \sum_{m=1}^M \beta_m G_m(x_i) \right)$$

via a **forward-stagewise additive modeling approach**.

Adaboost minimizes the exponential loss

For a simulated problem the training-set mis-classification error and average exponential loss:



While the mis-classification error decreases to zero ≈ 250 iterations, the exponential loss keeps decreasing.

Loss Functions and Robustness

- **Exponential Loss**

$$L(y, f(x)) = \exp\{-y f(x)\}$$

- **Binomial deviance loss**

$$L(y, f(x)) = -\log(1 + \exp\{-2y f(x)\})$$

where

$$p(x) = P(Y = 1 \mid x) = \frac{1}{1 + \exp\{-2f(x)\}}$$

- **Misclassification loss**

$$L(y, f(x)) = \text{Ind}(y f(x) < 0)$$

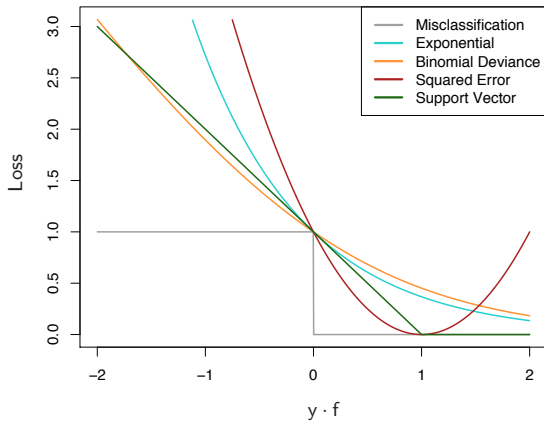
- These loss functions are functions of the “margin”: $y f(x)$
- Classification rule

$$G(x) = \text{sign}\{f(x)\}$$

\implies training examples with

- **positive margin** $y_i f(x_i) > 0$ are **correctly classified** and
 - **negative margin** $y_i f(x_i) < 0$ are **misclassified**
- Decision boundary defined by $f(x) = 0$
 - Classification algorithms attempt to produce positive margins for each training data point.
 - Loss criterion for classification should penalize negative margins more heavily than positive margins.

Loss functions for classification



Loss functions for classification

- *Exponential* and *deviance* loss continuous approx. to *mis-classification* loss.
- They increasingly penalize negative margin values more heavily than they reward positive ones.
- Binomial deviance penalty increases linearly with negative margin.
- Exponential loss penalty increases exponentially with negative margin.
- \implies in training the exponential criterion concentrates more of its efforts on large negative margin examples than the binomial criterion.
- Thus binomial criterion is far more robust than the exponential criterion in noisy settings - mislabels, overlapping classes.

- **Squared error loss**

$$L(y, f(x)) = (y - f(x))^2$$

Population optimum for this loss function: $f(x) = E[Y \mid x]$

- **Absolute loss**

$$L(y, f(x)) = |y - f(x)|$$

Population optimum for this loss function: $f(x) = \text{median}(Y \mid x)$

- On finite samples **squared error loss** puts far more emphasis on observations with large $|y_i - f(x_i)|$ than **absolute loss**.
- Thus **squared error loss** is less robust and performance degrades for long-tailed error distributions and mis-labellings.

- **Squared error loss**

$$L(y, f(x)) = (y - f(x))^2$$

Population optimum for this loss function: $f(x) = E[Y \mid x]$

- **Absolute loss**

$$L(y, f(x)) = |y - f(x)|$$

Population optimum for this loss function: $f(x) = \text{median}(Y \mid x)$

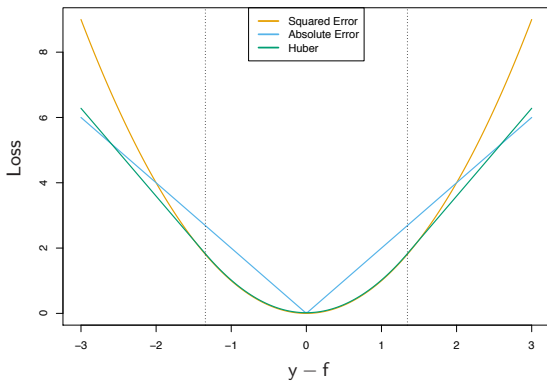
- On finite samples **squared error loss** puts far more emphasis on observations with large $|y_i - f(x_i)|$ than **absolute loss**.
- Thus **squared error loss** is less robust and performance degrades for long-tailed error distributions and mis-labellings.

- **Huber loss**

$$L(y, f(x)) = \begin{cases} (y - f(x))^2 & \text{for } |y - f(x)| \leq \delta \\ 2\delta|y - f(x)| - \delta^2 & \text{otherwise} \end{cases}$$

- strong resistance to gross outliers while
 - being nearly as efficient as least squares for Gaussian errors
- Combines the good properties of squared-error loss near zero and absolute error loss when $|y - f|$ is large.

Robust loss functions for regression



- When robustness is an issue
 - **squared-error loss** for regression and
 - **exponential loss** for classificationare **not** the best criterion to be optimizing.
- But, both these loss functions lead to elegant modular boosting algorithms in the context of *forward stagewise additive modelling*.
- For classification: perform a weighted fit of the base learner to the outputs y_i with weights $w_i = \exp\{-y_i f(x_i)\}$
- More robust criteria in their place do not give rise to such simple feasible boosting algorithms
- Later derive simple boosting algorithms based on any differentiable loss criterion.

- When robustness is an issue
 - **squared-error loss** for regression and
 - **exponential loss** for classificationare **not** the best criterion to be optimizing.
- But, both these loss functions lead to elegant modular boosting algorithms in the context of *forward stagewise additive modelling*.
- For classification: perform a weighted fit of the base learner to the outputs y_i with weights $w_i = \exp\{-y_i f(x_i)\}$
- More robust criteria in their place do not give rise to such simple feasible boosting algorithms
- Later derive simple boosting algorithms based on any differentiable loss criterion.

“Off-the-Shelf” Procedures for Data Mining

TABLE 10.1. *Some characteristics of different learning methods. Key: ▲= good, ◆=fair, and ▼=poor.*

Characteristic	Neural Nets	SVM	Trees	MARS	k-NN, Kernels
Natural handling of data of “mixed” type	▼	▼	▲	▲	▼
Handling of missing values	▼	▼	▲	▲	▲
Robustness to outliers in input space	▼	▼	▲	▼	▲
Insensitive to monotone transformations of inputs	▼	▼	▲	▼	▼
Computational scalability (large N)	▼	▼	▲	▲	▼
Ability to deal with irrelevant inputs	▼	▼	▲	▲	▼
Ability to extract linear combinations of features	▲	▲	▼	▼	◆
Interpretability	▼	▼	◆	▲	▼
Predictive power	▲	▲	▼	◆	▲

- Trees are great except....
 - they are inaccurate at making predictions.
- Boosting decision trees improve their accuracy but at the cost of
 - speed
 - interpretability and
 - for AdaBoost, robustness against overlapping class distributions and especially mislabeling of the training data.
- A gradient boosted model (GBM) is a generalization of tree boosting that attempts to mitigate these problems.
- It aims to produce an accurate and effective off-the-shelf procedure for data mining.

Boosting Trees

- Tree partitions the input space into $\mathcal{R}_j, j = 1, \dots, J$.
- Terminal/leaf nodes of tree represent the regions \mathcal{R}_j
- Constant γ_j assigned to each leaf.
- The predictive rule is

$$x \in \mathcal{R}_j \implies f(x) = \gamma_j$$

- A tree with parameters $\Theta = \{\mathcal{R}_j, \gamma_j\}_{j=1}^J$ is expressed as

$$T(x; \Theta) = \sum_{j=1}^J \gamma_j \text{Ind}(x \in \mathcal{R}_j)$$

(J is usually treated as a meta-parameter)

- Ideally parameters found by minimizing the empirical risk

$$\hat{\Theta} = \arg \min_{\Theta} \sum_{j=1}^J \sum_{x_i \in \mathcal{R}_j} L(y_i, \gamma_j)$$

- Very hard optimization problem, instead settle for approximate suboptimal solutions
- **Typical approach:** Divide optimization into two parts
 - **Find γ_j given \mathcal{R}_j**
Typically trivial - $\hat{\gamma}_j$ the mean of the training y 's falling in \mathcal{R}_j .
 - **Find \mathcal{R}_j**
Difficult part! Approximate solutions found. One strategy is to use a greedy, top-down recursive partitioning algorithm.

- A boosted tree is a sum of regression/classification trees

$$f_M(x) = \sum_{m=1}^M T(x; \Theta_m)$$

learned in a forward stagewise manner.

- At each step solve

$$\hat{\Theta}_m = \arg \min_{\Theta_m} \sum_{i=1}^N L(y_i, f_{m-1}(x_i) + T(x_i; \Theta_m))$$

for the parameters $\Theta_m = \{\mathcal{R}_{jm}, \gamma_{jm}\}_{j=1}^{J_m}$ of the next tree.

- How do we solve this optimization problem?

- **Find γ_{jm} given \mathcal{R}_{jm} - easy**

$$\hat{\gamma}_{jm} = \arg \min_{\gamma_{jm}} \sum_{x_i \in \mathcal{R}_{jm}} L(y_i, f_{m-1}(x_i) + \gamma_{jm})$$

- **Find \mathcal{R}_{jm} 's - not so easy....**

A few exceptions

- **Squared-error loss**

At each stage fit a regression tree to residuals $y_i - f_{m-1}(x_i)$

- **Two-class classification and exponential loss**

Gives rise to an AdaBoost method for boosting classification trees...

Adaboost for boosting classification trees

- If the trees are restricted to type where

$$\beta_m T(x_i; \Theta_m) \quad \text{and each} \quad \gamma_{jm} \in \{-1, 1\}$$

- The solution to

$$\hat{\Theta}_m = \arg \min_{\Theta_m} \sum_{i=1}^N L(y_i, f_{m-1}(x_i) + T(x_i; \Theta_m))$$

is the tree that minimizes the

$$\sum_{i=1}^N w_i^{(m)} \text{Ind}(y_i \neq T(x_i; \Theta_m))$$

with weights

$$w_i^{(m)} = \exp\{-y_i f_{m-1}(x_i)\}$$

- Straightforward to implement a greedy recursive-partitioning algorithm with this loss as a splitting criterion.

Adaboost for boosting classification trees

- If there is no restriction on the type of tree then the solution to

$$\hat{\Theta}_m = \arg \min_{\Theta_m} \sum_{i=1}^N L(y_i, f_{m-1}(x_i) + T(x_i; \Theta_m))$$

is the tree that minimizes the

$$\sum_{i=1}^N w_i^{(m)} \exp\{-y_i T(x_i; \Theta_m)\}$$

with weights

$$w_i^{(m)} = \exp\{-y_i f_{m-1}(x_i)\}$$

Numerical Optimization via Gradient Boosting

- If the loss, $L(\cdot, \cdot)$, is differentiable, can

$$\hat{\Theta}_m = \arg \min_{\Theta_m} \sum_{i=1}^N L(y_i, f_{m-1}(x_i) + T(x_i; \Theta_m))$$

be approximately solved with numerical optimization.

- Consider this...
- The loss associated with using any $f(x)$ to predict y is

$$L(f) = \sum_{i=1}^N L(y_i, f(x_i))$$

- Goal: Find f which minimizes $L(f)$.
- Re-interpret this optimization problem as find

$$\hat{\mathbf{f}} = \arg \min_{\mathbf{f}} L(\mathbf{f})$$

where $\mathbf{f} = \{f(x_1), \dots, f(x_N)\}$.

- If the loss, $L(\cdot, \cdot)$, is differentiable, can

$$\hat{\Theta}_m = \arg \min_{\Theta_m} \sum_{i=1}^N L(y_i, f_{m-1}(x_i) + T(x_i; \Theta_m))$$

be approximately solved with numerical optimization.

- Consider this...
- The loss associated with using any $f(x)$ to predict y is

$$L(f) = \sum_{i=1}^N L(y_i, f(x_i))$$

- Goal: Find f which minimizes $L(f)$.
- Re-interpret this optimization problem as find

$$\hat{\mathbf{f}} = \arg \min_{\mathbf{f}} L(\mathbf{f})$$

where $\mathbf{f} = \{f(x_1), \dots, f(x_N)\}$.

- Numerical optimization approximates

$$\hat{\mathbf{f}} = \arg \min_{\mathbf{f}} L(\mathbf{f})$$

as a sum of vectors

$$\mathbf{f}_M = \sum_{m=0}^M \mathbf{h}_m, \quad \mathbf{h}_m \in \mathbb{R}^N$$

where $\mathbf{f}_0 = \mathbf{h}_0$ is an initial guess and each \mathbf{f}_m is estimated from \mathbf{f}_{m-1} .

- Steepest descent chooses

$$\mathbf{h}_m = -\rho_m \mathbf{g}_m$$

where

- ρ_m is a scalar and
 - $\mathbf{g}_m \in \mathbb{R}^N$ is the gradient of $L(\mathbf{f})$ evaluated at $\mathbf{f} = \mathbf{f}_{m-1}$.
- Components of \mathbf{g}_m are

$$g_{im} = \left. \frac{\partial L(y_i, f(x_i))}{\partial f(x_i)} \right|_{f(x_i)=f_{i,m-1}}$$

- Step length is the solution to

$$\rho_m = \arg \min_{\rho} L(\mathbf{f}_{m-1} - \rho \mathbf{g}_m)$$

- Solution is updated: $\mathbf{f}_m = \mathbf{f}_{m-1} - \rho_m \mathbf{g}_m$

Forward stagewise Tree Boosting & Gradient Boosting

- Forward stagewise boosting is also a very greedy strategy:

$$\hat{\Theta}_m = \arg \min_{\Theta_m} \sum_{i=1}^N L(y_i, f_{m-1}(x_i) + T(x_i; \Theta_m))$$

- Tree predictions $T(x_i; \Theta_m)$ are analogous to the negative gradients $-g_{1m}, \dots, -g_{Nm}$.
- But $\mathbf{t}_m = \{T(x_1; \Theta_m), \dots, T(x_N; \Theta_m)\}$ are constrained to be predictions of a J_m -terminal node decision tree
- Whereas $-\mathbf{g}_m$ is the unconstrained maximal descent direction.
- Also analogous

$$\rho_m = \arg \min_{\rho} L(\mathbf{f}_{m-1} - \rho \mathbf{g}_m) \quad \text{to} \quad \hat{\gamma}_{jm} = \arg \min_{\gamma_{jm}} \sum_{x_i \in \mathcal{R}_{jm}} L(y_i, f_{m-1}(x_i) + \gamma_{jm})$$

but perform a *line search* for each terminal node.

Forward stagewise Tree Boosting & Gradient Boosting

- Forward stagewise boosting is also a very greedy strategy:

$$\hat{\Theta}_m = \arg \min_{\Theta_m} \sum_{i=1}^N L(y_i, f_{m-1}(x_i) + T(x_i; \Theta_m))$$

- Tree predictions $T(x_i; \Theta_m)$ are analogous to the negative gradients $-g_{1m}, \dots, -g_{Nm}$.
- But $\mathbf{t}_m = \{T(x_1; \Theta_m), \dots, T(x_N; \Theta_m)\}$ are constrained to be predictions of a J_m -terminal node decision tree
- Whereas $-\mathbf{g}_m$ is the unconstrained maximal descent direction.
- Also analogous

$$\rho_m = \arg \min_{\rho} L(\mathbf{f}_{m-1} - \rho \mathbf{g}_m) \quad \text{to} \quad \hat{\gamma}_{jm} = \arg \min_{\gamma_{jm}} \sum_{x_i \in \mathcal{R}_{jm}} L(y_i, f_{m-1}(x_i) + \gamma_{jm})$$

but perform a *line search* for each terminal node.

Forward stagewise Tree Boosting & Gradient Boosting

- If only goal is minimizing

$$\hat{\mathbf{f}} = \arg \min_{\mathbf{f}} L(\mathbf{f})$$

then perform steepest descent.

- However, the ultimate goal is to generalize $f_M(x)$ to new unseen data.
- A possible solution is as follows....

- Fit a tree $T(x; \Theta_m)$ at m th iteration whose predictions \mathbf{t}_m are as close as possible to the negative gradient

$$\tilde{\Theta}_m = \arg \min_{\Theta} \sum_{i=1}^N (-g_{im} - T(x_i; \Theta))^2$$

- From the solution regions $\tilde{\mathcal{R}}_{jm}$ set

$$\hat{\gamma}_{jm} = \arg \min_{\gamma_{jm}} \sum_{x_i \in \tilde{\mathcal{R}}_{jm}} L(y_i, f_{m-1}(x_i) + \gamma_{jm})$$

- The regions $\tilde{\mathcal{R}}_{jm}$ will not be identical to the regions \mathcal{R}_{jm} that solve the original problem, but they are similar enough.

Gradients for common loss functions

Setting	Loss function	$-\partial L(y_i, f(x_i))/\partial f(x_i)$
Regression	$\frac{1}{2}(y_i - f(x_i))^2$	$y_i - f(x_i)$
Regression	$ y_i - f(x_i) $	$\text{sign}\{y_i - f(x_i)\}$
Regression	Huber	$\begin{cases} y_i - f(x_i) & \text{if } y_i - f(x_i) \leq \delta_m \\ \delta_m \text{sign}\{y_i - f(x_i)\} & \text{if } y_i - f(x_i) > \delta_m \end{cases}$
Classification	Deviance	$k\text{th component: } \text{Ind}(y_i = G_k) - p_k(x_i)$

where the K -class deviance loss function is

$$L(y, p(x)) = - \sum_{k=1}^K \text{Ind}(y = G_k) \log p_k(x) = - \sum_{k=1}^K \text{Ind}(y = G_k) + \log \left(\sum_{l=1}^K \exp\{f_l(x)\} \right)$$

$$\text{if } p_k(x) = \exp\{f_k(x)\} / \sum_{l=1}^K \exp\{f_l(x)\}$$

Algorithm 10.3 *Gradient Tree Boosting Algorithm.*

1. Initialize $f_0(x) = \arg \min_{\gamma} \sum_{i=1}^N L(y_i, \gamma)$.

2. For $m = 1$ to M :

(a) For $i = 1, 2, \dots, N$ compute

$$r_{im} = - \left[\frac{\partial L(y_i, f(x_i))}{\partial f(x_i)} \right]_{f=f_{m-1}}.$$

(b) Fit a regression tree to the targets r_{im} giving terminal regions R_{jm} , $j = 1, 2, \dots, J_m$.

(c) For $j = 1, 2, \dots, J_m$ compute

$$\gamma_{jm} = \arg \min_{\gamma} \sum_{x_i \in R_{jm}} L(y_i, f_{m-1}(x_i) + \gamma).$$

(d) Update $f_m(x) = f_{m-1}(x) + \sum_{j=1}^{J_m} \gamma_{jm} I(x \in R_{jm})$.

3. Output $\hat{f}(x) = f_M(x)$.

Right-Sized Trees for Boosting

- Learning a large pruned tree at each round performs poorly.
- Better if
 - Restrict all trees to be same size $J_m = J \forall m$
 - Perform cross-validation to choose an optimal J
- Interaction level of tree-based approximations is limited by J :
 - if $J = 2$ then $f_M(x)$ can only be of the form

$$\sum_k \eta_k(X_k)$$

- if $J = 3$ then $f_M(x)$ can be of the form

$$\sum_k \eta_k(X_k) + \sum_{jk} \eta_{jk}(X_j, X_k)$$

- if $J = 4$ then $f_M(x)$ can be of the form

$$\sum_k \eta_k(X_k) + \sum_{jk} \eta_{jk}(X_j, X_k) + \sum_{jkl} \eta_{jkl}(X_j, X_k, X_l)$$

- etc...

- Learning a large pruned tree at each round performs poorly.
- Better if
 - Restrict all trees to be same size $J_m = J \forall m$
 - Perform cross-validation to choose an optimal J
- Interaction level of tree-based approximations is limited by J :
 - if $J = 2$ then $f_M(x)$ can only be of the form
$$\sum_k \eta_k(X_k)$$
 - if $J = 3$ then $f_M(x)$ can be of the form
$$\sum_k \eta_k(X_k) + \sum_{jk} \eta_{jk}(X_j, X_k)$$
 - if $J = 4$ then $f_M(x)$ can be of the form
$$\sum_k \eta_k(X_k) + \sum_{jk} \eta_{jk}(X_j, X_k) + \sum_{jkl} \eta_{jkl}(X_j, X_k, X_l)$$
 - etc...

- Learning a large pruned tree at each round performs poorly.
- Better if
 - Restrict all trees to be same size $J_m = J \forall m$
 - Perform cross-validation to choose an optimal J
- Interaction level of tree-based approximations is limited by J :
 - if $J = 2$ then $f_M(x)$ can only be of the form

$$\sum_k \eta_k(X_k)$$

- if $J = 3$ then $f_M(x)$ can be of the form

$$\sum_k \eta_k(X_k) + \sum_{jk} \eta_{jk}(X_j, X_k)$$

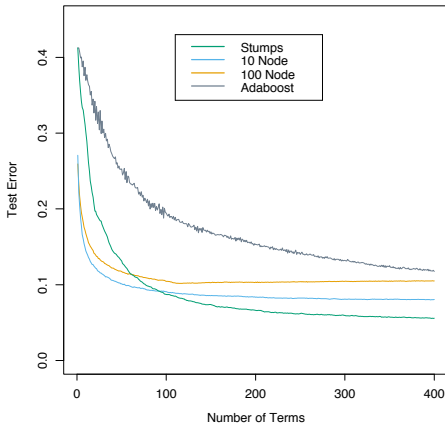
- if $J = 4$ then $f_M(x)$ can be of the form

$$\sum_k \eta_k(X_k) + \sum_{jk} \eta_{jk}(X_j, X_k) + \sum_{jkl} \eta_{jkl}(X_j, X_k, X_l)$$

- etc...

- For many practical problems low-order interactions dominate.
- Therefore models that produce strong higher-order interaction effects suffer in accuracy.
- Authors claim that $4 \leq J \leq 8$ works well in the context of boosting.

Boosting with different sized trees



$$Y = \begin{cases} 1 & \text{if } \sum_{j=1}^{10} X_j^2 > \chi_{10}^2(.5) \\ -1 & \text{otherwise} \end{cases}$$

where X_1, \dots, X_{10} are standard indpt Gaussian and $\chi_{10}^2(.5) = 9.34$.

Regularization

Options for regularization

- Control number of boosting rounds

- Too large $M \implies$ danger of over-fitting

\therefore There is a M^* that minimizes future risk

- Shrinkage

- Scale the contribution of each tree by factor $0 < \nu < 1$

$$f_m(x) = f_{m-1}(x) + \nu \cdot \sum_{j=1}^J \gamma_{jm} \text{Ind}(x \in \mathcal{R}_{jm})$$

- Smaller $\nu \implies$ larger M to obtain low training error
- Empirical finding: small $\nu < .1$ and sufficiently large $M \implies$ better result than no shrinkage. Especially for regression problems

Options for regularization

- Control number of boosting rounds

- Too large $M \implies$ danger of over-fitting
 \therefore There is a M^* that minimizes future risk

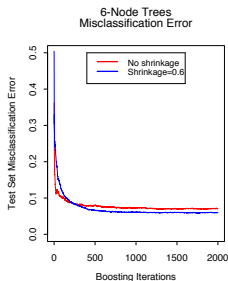
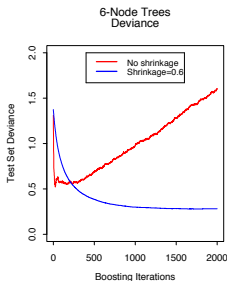
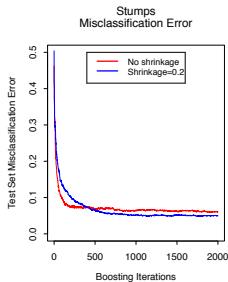
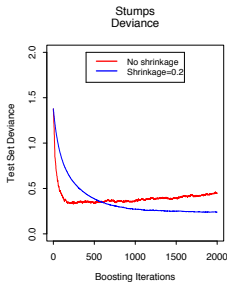
- Shrinkage

- Scale the contribution of each tree by factor $0 < \nu < 1$

$$f_m(x) = f_{m-1}(x) + \nu \cdot \sum_{j=1}^J \gamma_{jm} \text{Ind}(x \in \mathcal{R}_{jm})$$

- Smaller $\nu \implies$ larger M to obtain low training error
- Empirical finding: small $\nu < .1$ and sufficiently large $M \implies$ better result than no shrinkage. Especially for regression problems

Shrinkage example



$$Y = \begin{cases} 1 & \text{if } \sum_{j=1}^{10} X_j^2 > \chi_{10}^2(.5) \\ -1 & \text{otherwise} \end{cases}$$

where X_1, \dots, X_{10} are
standard indpt Gaussian and
 $\chi_{10}^2(.5) = 9.34$.

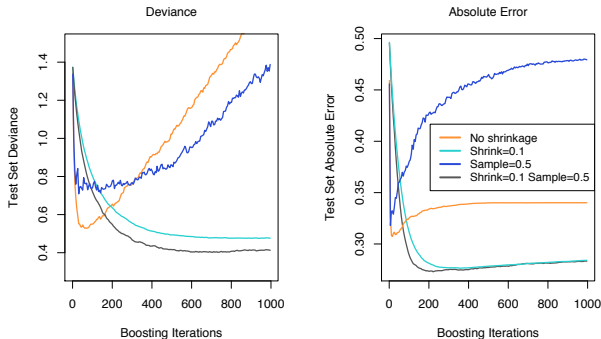
Deviance: $-2 \log \hat{p}_G(X)$

Options for regularization

- Subsampling
 - Stochastic gradient boosting - each iteration sample a fraction η of the training observations (without replacement).
 - A typical value is $\eta = .5$
 - Empirically subsampling without shrinkage works poorly
 - But subsampling with shrinkage works well
 - Now have 4 parameters to estimate J, M, ν , and η

Subsample example

4-Node Trees



$$Y = \begin{cases} 1 & \text{if } \sum_{j=1}^{10} X_j^2 > \chi_{10}^2(.5) \\ -1 & \text{otherwise} \end{cases}$$

where X_1, \dots, X_{10} are standard indpt Gaussian and $\chi_{10}^2(.5) = 9.34$.