Plan **Chapter 10: Linear And Nonlinear Conservation Laws** • A simple upstream discretization of the transport equation • Proof of convergence via Fourier transformations Michael Hanke Nonlinear conservation laws Mathematical Models, Analysis and Simulation, Part I Shock waves • Unique solvability: viscosity solutions Michael Hanke, NADA, November 6, 2008 Michael Hanke, NADA, November 6, 2008 1 The problem **Trigonometric Interpolation** • Consider the pure initial value problem • Let $\mathbf{f} = \{f_j | j \in \mathbb{Z}\}$ be an infinite sequence: $u_t = cu_x, \quad x \in \mathbb{R}, \quad u(x,0) = u^0(x)$ $\tilde{f}(x) := \sum_{i=-\infty}^{+\infty} \operatorname{sinc} \frac{\pi}{h} (x - x_j) f_j, \quad x \in \mathbb{R}.$ with c > 0. The discretization is Because of $\frac{u_j^{n+1}-u_j^n}{\Delta t}=c\frac{u_{j+1}^n-u_j^n}{\Delta x}.$ $\operatorname{sinc} \frac{\pi}{h} (x - x_j) = \frac{\sin \frac{\pi}{h} (x_k - x_j)}{\frac{\pi}{h} (x_k - x_j)} = \begin{cases} 0, & k \neq j \\ 1, & k = j \end{cases}$ • Convergence: it holds **Q:** How to compare the discrete solution u_i^n and the $\tilde{f}(x_j) = f_j$ continuous solution $u(x,t_n)$? A: Use interpolation by trigonometric polynomials! \tilde{f} is a trigonometric interpolant of **f**.

Semi-Discrete Fourier Transform

Proof of Theorem

• The semi-discrete Fourier transform is given by

$$\hat{f}(k) = h \sum_{j=-\infty}^{+\infty} f_j e^{-ikx_j}, k \in \mathbb{R}.$$

Notes:

- \hat{f} is defined on all of \mathbb{R} .
- Compared to the DFT, a different scaling is used.
- \hat{f} is $2\pi/h$ -periodic,

$$\hat{f}(k) = \hat{f}(k + 2\pi/h).$$

• The band-limited Fourier transform:

$$\check{f}(k) = \begin{cases} \hat{f}(k), & |k| < \pi/h, \\ 0, & \text{otherwise.} \end{cases}$$

Theorem.

$$\hat{\tilde{f}}(k) \equiv \check{f}(k)$$

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Proof: Cont

$$\begin{split} \hat{f}(k) &= \int_{-\infty}^{+\infty} \left(\sum_{j=-\infty}^{+\infty} \frac{\sin \frac{\pi}{h} (x-x_j)}{\frac{\pi}{h} (x-x_j)} f_j \right) e^{-ikx} dx \\ &= \sum_{j=-\infty}^{+\infty} f_j \int_{-\infty}^{+\infty} \frac{\sin \frac{\pi}{h} (x-x_j)}{\frac{\pi}{h} (x-x_j)} e^{-ikx} dx \\ \stackrel{y=x-x_j}{=} \sum_{j=-\infty}^{+\infty} f_j e^{-ikx_j} \int_{-\infty}^{+\infty} \frac{\sin \frac{\pi}{h} y}{\frac{\pi}{h} y} e^{-iky} dy \\ &= \sum_{j=-\infty}^{+\infty} f_j e^{-ikx_j} h\chi_{\pi/h}(k) \\ &= \begin{cases} h \sum_{j=-\infty}^{+\infty} f_j e^{-ikx_j}, & |k| < \pi/h \\ 0, & \text{otherwise} \\ &= \check{f}(k) \end{cases}$$

• Define, for a > 0,

 $\chi_a(x) = egin{cases} 1, & |x| < a, \ 0, & ext{otherwise}. \end{cases}$

• Fourier transform (Strang, p 310):

$$\widehat{\chi}_a(k) = 2a \frac{\sin ak}{ak}.$$

• Using the inversion theorem, one gets

$$\left(\frac{\sin bx}{bx}\right)^{\widehat{}} = \frac{\pi}{b}\chi_b(x)$$

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Convergence

$$\|u(\cdot,t_n)-\tilde{u}(\cdot,t_n)\| \xrightarrow{h,\Delta t\to 0} 0??$$

Continuous Fourier transform of $u_t = cu_x$, $u(\cdot, 0) = u^0$ yields

$$\frac{d\hat{u}}{dt} = ick\hat{u}, \quad \hat{u}(\cdot, 0) = \hat{u^0}.$$

Hence,

 $\hat{u}(k,t+\Delta t) = e^{ick\Delta t}\hat{u}(k,t).$

Finally,

$$\begin{split} \hat{u}(\cdot,t) &= H(\Delta t)^n \hat{u}(\cdot,0) = H(k,\Delta t)^n \hat{u^0} \\ \\ H(k,\Delta t) &= e^{ick\Delta t}. \end{split}$$

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Convergence: Cont

Convergence: Cont

Discrete Write the discretization like

$$u_{j}^{n+1} = u_{j}^{n} + r(u_{j+1}^{n} - u_{j}^{n}), \quad r = \frac{c\Delta t}{\Delta x}.$$

Semi-discrete Fourier transform

$$\hat{u}^{n+1} = \hat{u}^n + r(e^{ikh}\hat{u}^n - \hat{u}^n).$$

Finally,

$$\begin{aligned} \hat{u}^n &= G^n \hat{u}^0 \\ \check{u}^n &= G^n \check{u}^0, |kh| < \pi \\ G &= 1 + r(e^{-ikh} - 1). \end{aligned}$$

The initial value can be chosen in different ways. We use the most obvious

$$u_j^0 = u^0(x_j).$$

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The Second Term

• Assume stability:

$$|G| < 1 \Leftrightarrow 0 < c\Delta t < h$$

• Split the factors:

$$H^n - G^n = (H - G) \sum_{j=0}^{n-1} H^{n-j-1} G^j.$$

• Because of stability, it holds

$$\left|\sum_{j=0}^{n-1} H^{n-j-1} G^{j}\right| \le \sum_{j=0}^{n-1} 1 \cdot |G^{j}| < n = \frac{t_{n}}{\Delta t}$$

Remember Plancherel's and Parseval's identities:

$$\|\hat{u}\|^2 = 2\pi \|u\|^2$$
, $2\pi \|\widetilde{u^0}\|^2 = \|\breve{u^0}\|^2$.

We obtain

$$\begin{split} \|u(\cdot,t_n) - \tilde{u}(\cdot,t_n)\| &= \frac{1}{\sqrt{2\pi}} \|\hat{u}(\cdot,t_n) - \check{u}^n\| \\ &= \frac{1}{\sqrt{2\pi}} \|H^n \widehat{u^0} - G^n \check{u}^0\| \\ &= \frac{1}{\sqrt{2\pi}} \|H^n \widehat{u^0} - H^n \check{u}^0 + H^n \check{u}^0 - G^n \check{u}^0\| \\ &\leq \frac{1}{\sqrt{2\pi}} (\|H^n (\widehat{u^0} - \check{u}^0)\| + \|(H^n - G^n) \check{u}^0\|) \end{split}$$

- The first term contains the propagation of the initial error (in frequency space). In the present case, |H| = 1.
- The first term becomes small if the approximation of the initial values is consistent:

$$\|\widetilde{u^0} - \breve{u^0}\| \to 0 \text{ for all } u^0 \in L^2(\mathbb{R}).$$

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The Second Term: Cont

• Fix the wave number k now. Then

$$\begin{aligned} H - G &= e^{ick\Delta t} - (1 + r(e^{ikh} - 1)) \\ &= 1 + ick\Delta t + O((\Delta t)^2) - (1 + \frac{c\Delta t}{h}(1 + ikh + O(h^2) - 1)) \\ &= 1 + ick\Delta t + O((\Delta t)^2) - (1 + ick\Delta t + O((\Delta t)^2)) \\ &= O((\Delta t)^2)) \end{aligned}$$

This is a consequence of first order consistency: $|H-G| = O((\Delta t)^{p+1})$

• Putting everything together,

 $|H^n-G^n|=t_n\cdot O(\Delta t).$

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Conclusions

• We have just seen:

 $consistency + stability \Rightarrow convergence.$

• Previous chapter:

no stability \Rightarrow no convergence.

• This is obvious:

 $convergence \Rightarrow consistency.$

Conclusion:

 $consistency + stability \Leftrightarrow convergence$

This is one instance of the Lax Equivalence Theorem.

Nonlinear Conservation Laws: An Example

Read: Strang, Ch 6.6

Problem: Determine the flow of cars on a narrow street.

- Density ρ of cars: number of cars per unit length.
- Velocity of cars v depends on density: $v = v(\rho)$.

$$\rho \text{ small} \Rightarrow v \text{ large}$$

$$\rho \text{ large} \Rightarrow v \text{ low}$$

Normalization:

- Largest possible velocity: v = 1.
- Road full means $\nu = 0$. Let this be at $\rho = 1$.
- Simple velocity model: $\nu(\rho)=1-\rho.$
- Conservation: Flux is $\Phi = \nu \rho = (1 \rho)\rho$,

$$\rho_t + \operatorname{div}((1-\rho)\rho) = 0.$$

- Initial data: $\rho(x,0) = \rho^0(x)$.
- Solution by characteristics:

$$\frac{dx}{dt} = 1 - 2\rho, \quad \frac{d\rho(x(t), t)}{dt} = 0$$

- ρ is constant along each characteristic.

Since *dx/dt* is constant, the characteristics are *straight* lines.

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Example: Smooth Solutions

Assume initial data:

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• Characteristics:





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Example: Cont

• The following possibilities arise:



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Example: Shocks

Shocks: Cont



Compute the shock location s(t): Integrate the equation on $[s - \varepsilon, s + \varepsilon]$:

$$\int_{s(t)-\varepsilon}^{s(t)+\varepsilon} \frac{\partial \rho}{\partial t} dx + \Phi(\rho(s(t)+\varepsilon)) - \Phi(\rho(s(t)-\varepsilon)) = 0$$

It holds

$$\frac{d}{dt}\int_{s(t)-\varepsilon}^{s(t)+\varepsilon}\partial\rho dx = \int_{s(t)-\varepsilon}^{s(t)+\varepsilon}\frac{\partial\rho}{\partial t}dx + \rho(s(t)+\varepsilon)\frac{ds}{dt} - \rho(s(t)-\varepsilon)\frac{ds}{dt}$$

Taking the limit $\epsilon \to 0,$ this leads to

$$0 = \lim_{\varepsilon \to 0} \int_{s(t)-\varepsilon}^{s(t)+\varepsilon} \frac{\partial \rho}{\partial t} dx + \rho(s(t)+) \frac{ds}{dt} - \rho(s(t)-) \frac{ds}{dt}$$

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Rankine-Hugoniot Jump Condition

Result:

$$\frac{ds}{dt} = \frac{\Phi(\rho^+) - \Phi(\rho^-)}{\rho^+ - \rho^-}$$

This is the famous Rankine-Hugoniot jump condition.



Entropy Solutions, Rarefaction Waves

Consider initial data



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Entropy Solutions, Rarefaction Waves: Cont

Entropy Solutions, Rarefaction Waves: Cont

There are (at least) two solutions which satisfy the Rankine-Hugoniot condition:

- $\rho(x,t) = \rho^0(x)$ for all t > 0.
- Rarefaction wave

$$\rho(x,t) = \begin{cases} 1, & x \le -t \\ 0, & x \ge t \\ \frac{1}{2}(1-\frac{x}{t}), & -t < x < t \end{cases}$$

Which one is the "correct" one?



In order to select one solution, we must use physical considerations.

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Entropy Solutions, Rarefaction Waves: Cont

Numerical approximations: How to choose ϵ ?

- 1. $\epsilon = O(h)$ gives nice, non-wiggly solutions, but only first-order accurate.
- 2. Choose $\varepsilon = \varepsilon(\rho_x)$, where

$$\varepsilon \sim \begin{cases} h, & \text{if } \rho_x \text{ is large} \\ 0, & \text{if } \rho_x \text{ is small} \end{cases}$$

This is called switched artificial diffusion.

- ON: near shocks,
- OFF: where the solution is smooth.

Idea: Modify the equation by adding small artificial diffusion:

$$v = 1 - \rho - \epsilon \rho_x / \rho, 0 < \epsilon \ll 1$$

(Say, drivers look ahead.)

Modified equation:

 $\rho_t + (\rho(1-\rho)_x = \varepsilon \rho_{xx}$

- Entropy solution: The limiting function $\rho = \lim_{\epsilon \to 0} \rho_{\epsilon}$
- All solutions are smooth. However, gradients may become large.
- The added diffusion is also necessary for numerical schemes.

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