

Cost-optimal and Net-benefit Planning - A Parameterised Complexity View

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Introduction

- The usage of *zero-cost* or *rational-cost* actions **does** change the parameterised complexity of planning
- Analysis of a large number of subclasses, using both PUBS restrictions and restricting the number of preconditions and effects

Problem Definition

INSTANCE: $\mathbb{P} = \langle V, A, I, G, c, U \rangle$

- $\langle V, A, I, G \rangle \in C \subseteq \text{SAS}^+$
 V, A, I and G are the set of variables, the set of actions, initial state and goal state, respectively.
- $c : A \rightarrow \mathbb{D}$ (numeric) is a cost function
- $U : \text{vars}(G) \rightarrow \mathbb{D}$ is a utility function

PARAMETER: A non-negative integer k .

QUESTIONS:

COST-OPTIMAL PLANNING ($\text{COP}(C, \mathbb{D})$):

Does \mathbb{P} have a plan ω of cost $c(\omega) \leq k$?

NET-BENEFIT PLANNING ($\text{NBP}(C, \mathbb{D})$): Is

there a state $s \in S(V)$ and a plan ω from I to s such that $U(s) - c(\omega) \geq k$?

RESTRICTIONS ON C :

- P (post-unique)**: No two actions change the same variable to the same value.
- U (unary)**: Each action has only one effect.
- B (binary)**: Each variable takes only two values.
- S (single-valued)**: When two actions have v as their precondition but not as effect, then they require the same value from v .

Parameterised Complexity Theory

Standard Complexity measures complexity as a function of the input size (n).

Tractable: solvable in time $O(n^c)$ for some constant c .

Parameterised Complexity measures complexity as a function of both input size (n) and a parameter (k) which is independent of n .

Fixed-parameter tractable: solvable in time $O(f(k) \cdot n^c)$.

Parameterised Complexity Classes:

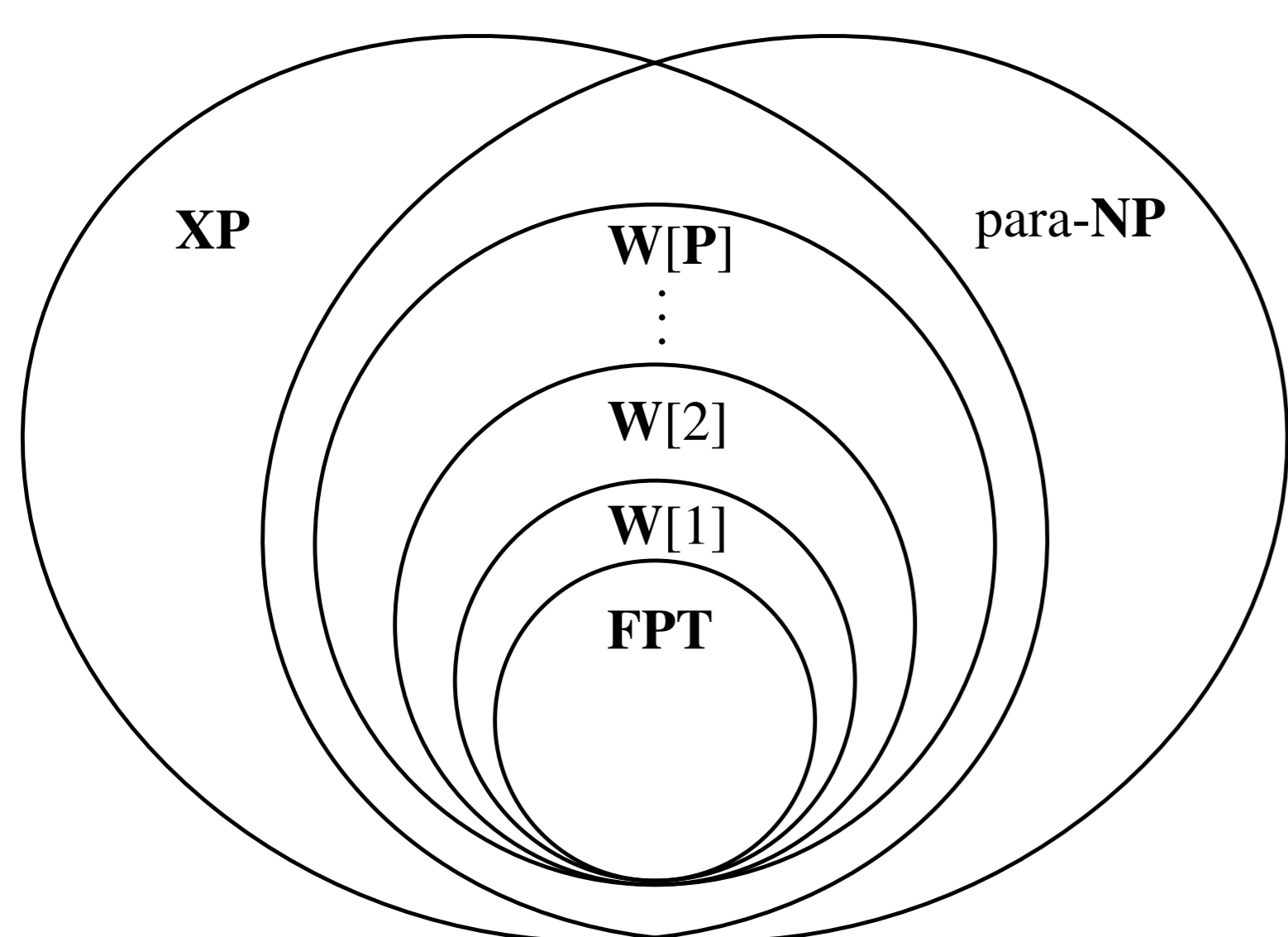
FPT: Fixed-parameter tractable problems

W[i]: Defined by WEIGHTED SATISFIABILITY PROBLEM (weight $\leq k$, literal alterations $\leq i$)

W[P]: Same as W[i] but with with unbounded alternations.

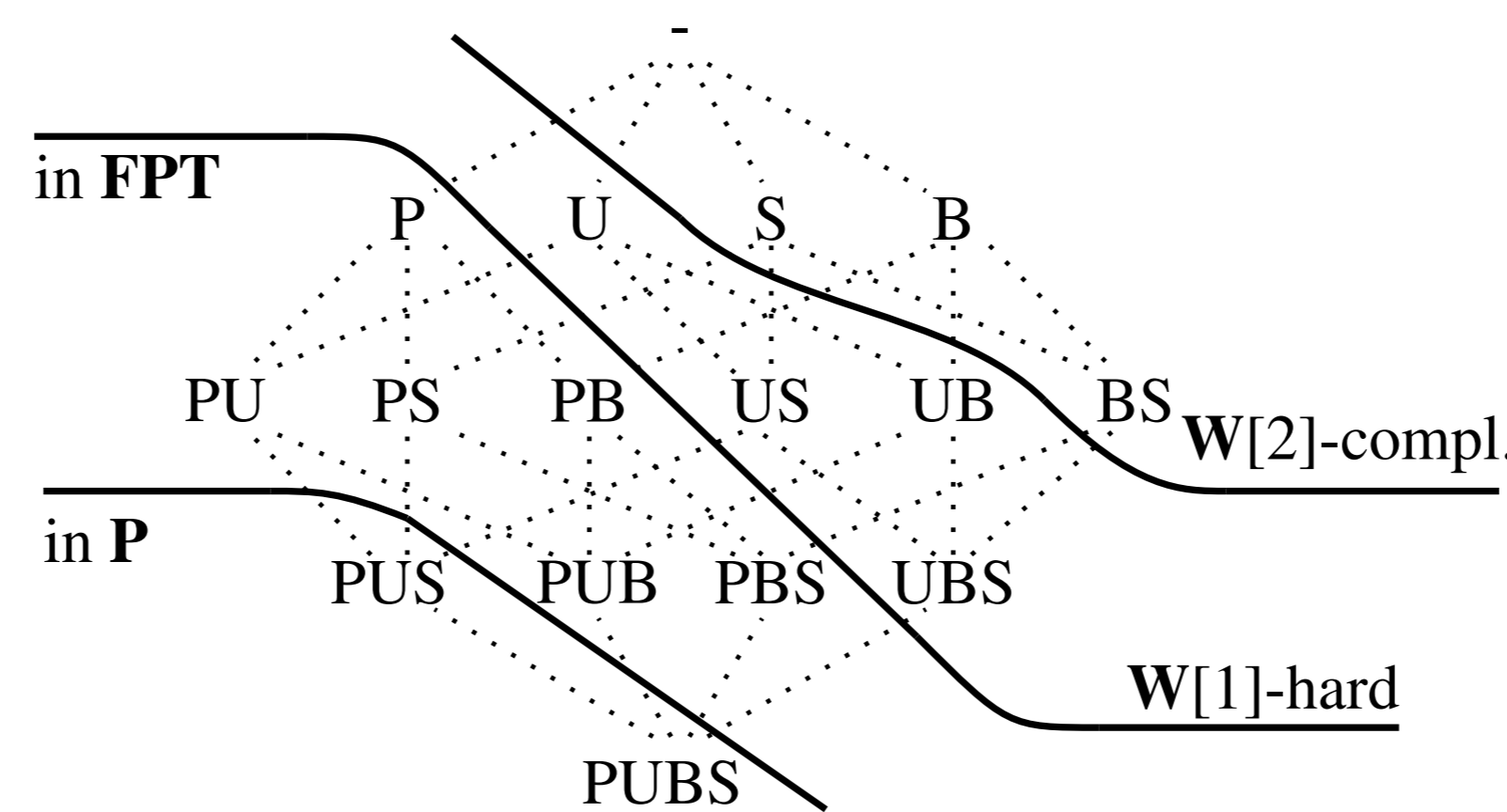
para-NP: Problems solvable in non-deterministic time $f(k) \cdot n^c$.

XP: Problems solvable in time $n^{f(k)}$.

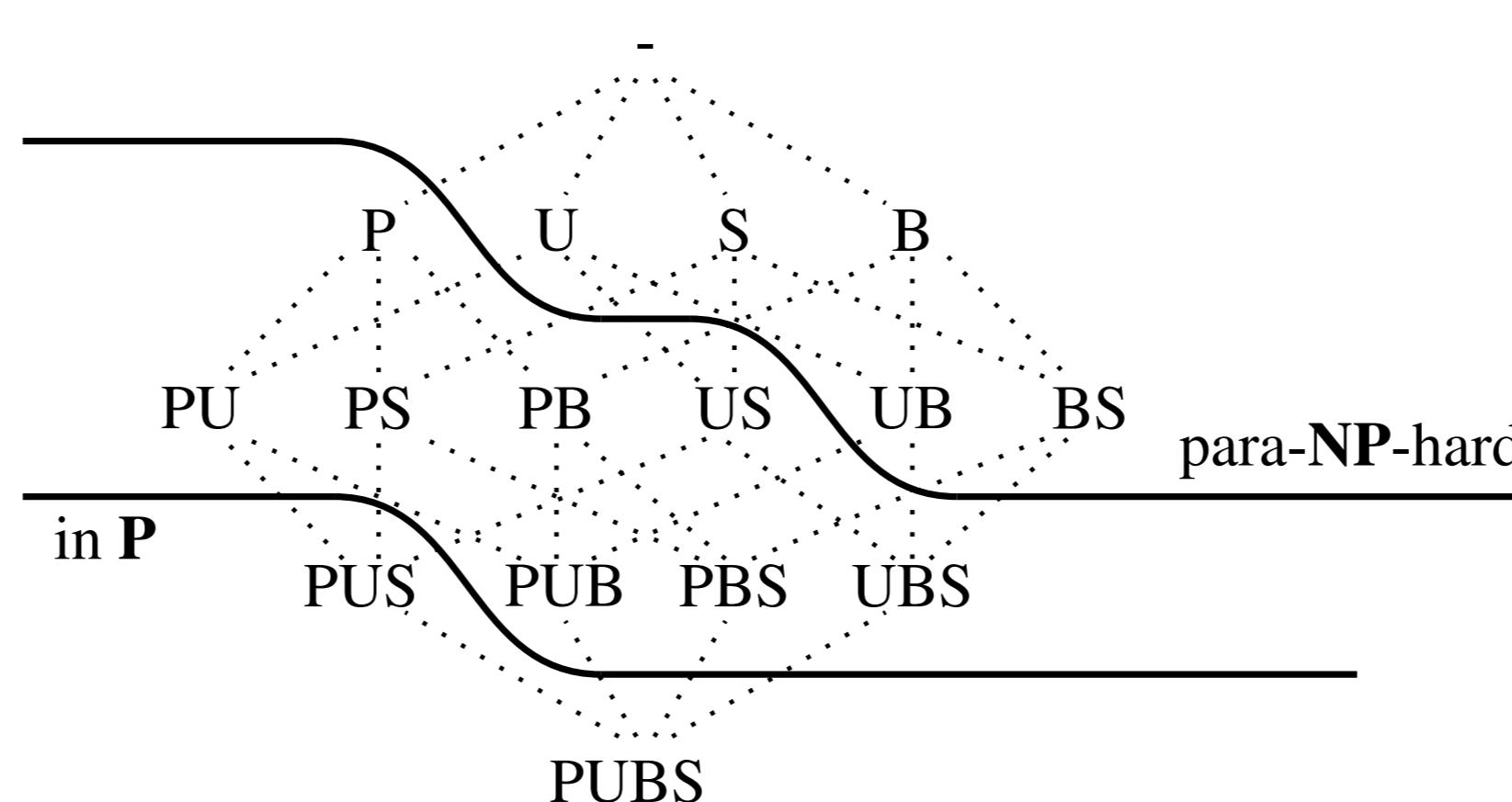


Results - PUBS Restrictions

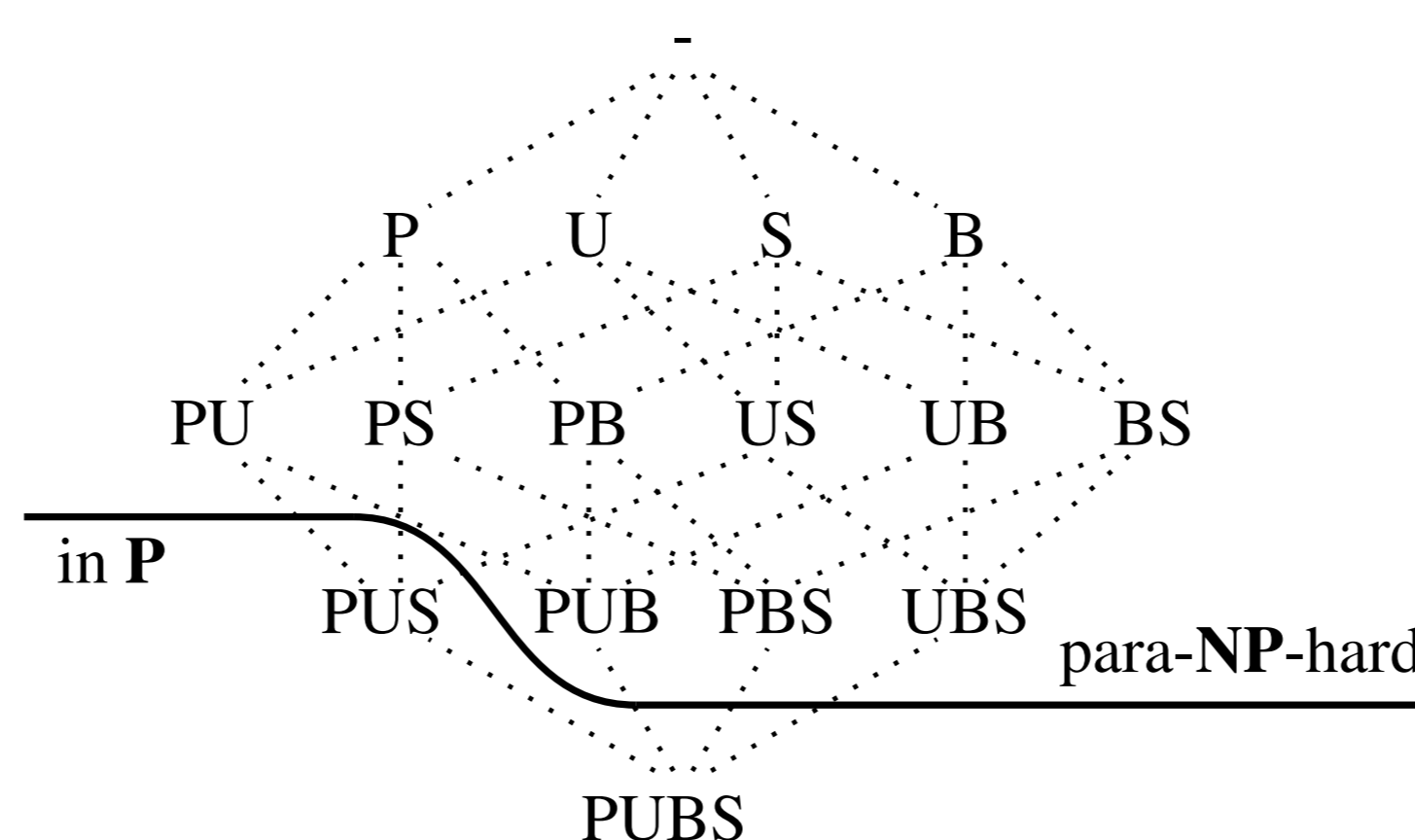
Positive Integers: $\text{COP}(C, \mathbb{Z}_+)$



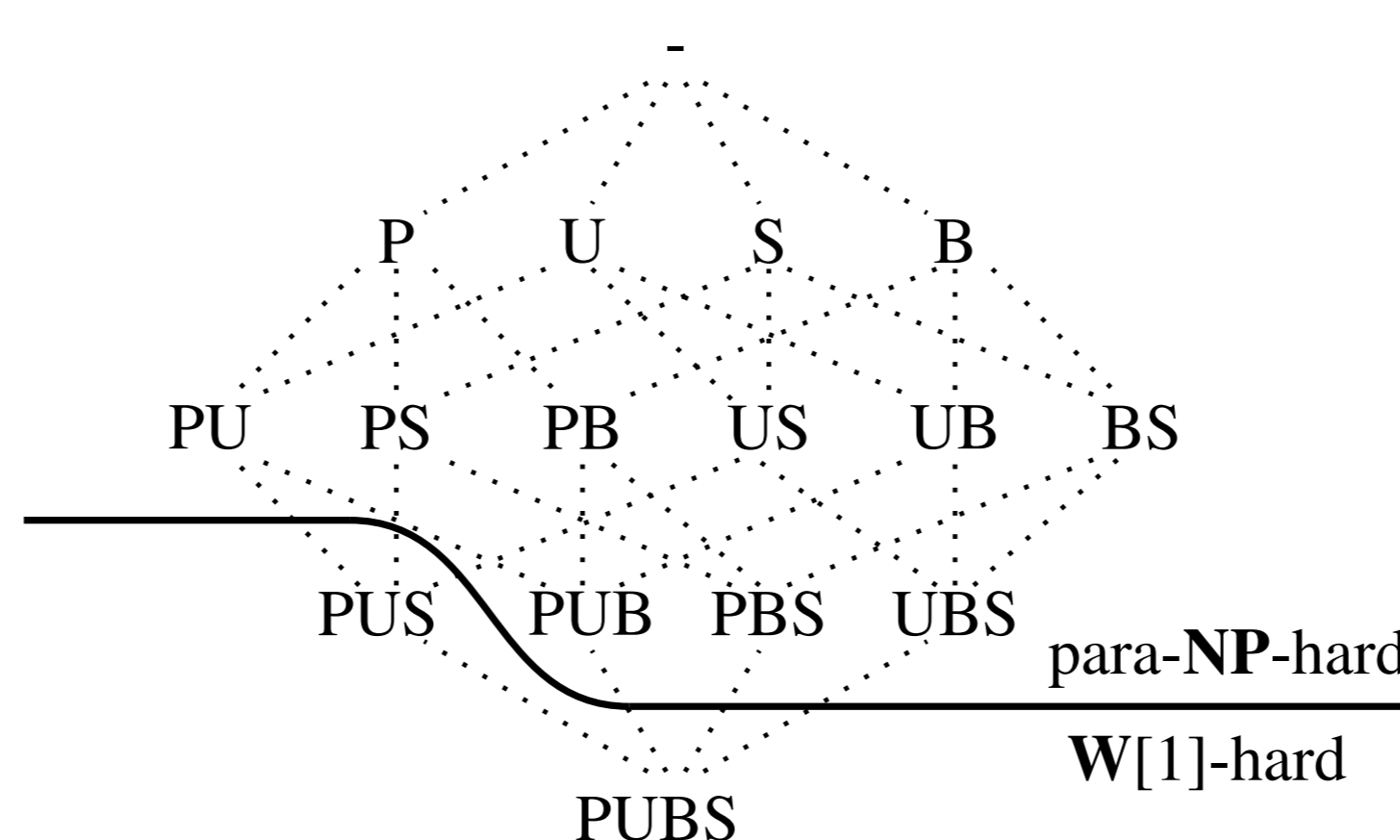
Non-negative Integers: $\text{COP}(C, \mathbb{Z}_0)$



Positive Rationals: $\text{COP}(C, \mathbb{Q}_+)$



$\text{NBP}(C, \mathbb{Z}_+), \text{NBP}(C, \mathbb{Z}_0), \text{NBP}(C, \mathbb{Q}_+)$



Results - Pre/Eff Restrictions

In this section, results based on restricting the number of preconditions and effects are brought.

$\text{COP}(C, \mathbb{Z}_+)$

		eff		
		1	≥ 3	*
pre	0	P	W[1]-hard	W[2]-hard
	≥ 1	W[1]-hard	W[1]-hard	W[2]-hard
	*	W[1]-hard	W[1]-hard	W[2]-hard

$\text{COP}(C, \mathbb{Z}_0)$

		eff		
		1	≥ 3	*
pre	0	P	W[1]-hard	W[2]-hard
	≥ 1	para-NP-hard	para-NP-hard	para-NP-hard
	*	para-NP-hard	para-NP-hard	para-NP-hard

$\text{COP}(C, \mathbb{Q}_+)$

		eff		
		1	≥ 2	*
pre	0	P	para-NP-hard	para-NP-hard
	≥ 1	para-NP-hard	para-NP-hard	para-NP-hard
	*	para-NP-hard	para-NP-hard	para-NP-hard

$\text{NBP}(C, \mathbb{Z}_+), \text{NBP}(C, \mathbb{Z}_0), \text{NBP}(C, \mathbb{Q}_+)$

		eff		
		1	≥ 2	*
pre	0	P	?	?
	≥ 2	para-NP-hard	para-NP-hard	para-NP-hard
	*	para-NP-hard	para-NP-hard	para-NP-hard

?: Open cases

Observation

Instead of ordinary polynomial-time reductions, an *fpt reduction* is used in parameterised complexity. An *fpt reduction* from a parameterised language $L \subseteq \Sigma^* \times \mathbb{Z}_0$ to another parameterised language $L' \subseteq \Pi^* \times \mathbb{Z}_0$ is a mapping $R : \Sigma^* \times \mathbb{Z}_0 \rightarrow \Pi^* \times \mathbb{Z}_0$ such that:

- (1) $\langle \mathbb{I}, k \rangle \in L \Leftrightarrow \langle \mathbb{I}', k' \rangle = R(\mathbb{I}, k) \in L'$
- (2) There is a computable function f and a constant c such that R can be computed in time $f(k) \cdot |\mathbb{I}|^c$
- (3) There is a computable function g such that $k' \leq g(k)$

A $\text{COP}(\text{SAS}^+, \mathbb{Q}_+)$ instance can be polynomially reduced to a $\text{COP}(\text{SAS}^+, \mathbb{Z}_+)$ instance by multiplying all costs and the parameter with a suitable value α . This is, however, **not an fpt reduction** since α will typically not depend on the parameter (only), which contradicts condition (3) for fpt reductions. Hence, the membership results for $\text{COP}(C, \mathbb{Z}_+)$ do not transfer to $\text{COP}(C, \mathbb{Q}_+)$.

References

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