

# Course: DD2427 - Exercise Set 5

In this set of exercises you will examine classifiers based on the nearest neighbour rule.

## Exercise 1: Nearest neighbour decision boundary

Assume that you have one feature vector  $\mathbf{x}_1 = (x_1, y_1)$  from class  $\omega_1$  and another feature vector  $\mathbf{x}_2 = (x_2, y_2)$  from class  $\omega_2$ . These two  $2d$  points can be used to define a very simple 1NN (nearest neighbour) classifier to distinguish between the classes  $\omega_1$  and  $\omega_2$ . Show that the decision boundary induced by this classifier is a straight line.

(**HINT:** When will a query point  $\mathbf{x} = (x, y)$  be classified as class  $\omega_1$ ? And similarly when will it be classified as class  $\omega_2$ ? And finally, when is the query point not clearly belonging to either class. This latter situation occurs at the decision boundary.)

## Exercise 2: Nearest neighbour example

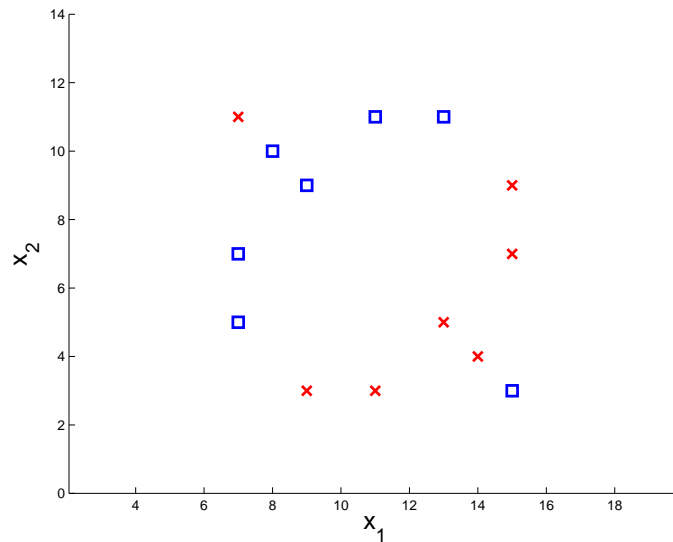


Figure 1: The training data for simple 1-NN classifier.

Next consider we have two attributes  $x_1, x_2 \in \mathbb{R}$  and a class label  $y \in \{0, 1\}$  and a training set that looks like:

Class 1 points:

$$\{(7, 11), (15, 9), (15, 7), (13, 5), (14, 4), (9, 3), (11, 3)\}$$

Class 2 points:

$$\{(11, 11), (13, 11), (8, 10), (9, 9), (7, 7), (7, 5), (15, 3)\}$$

Graphically, these points appear as in figure 1. **Draw the decision boundaries for 1-nearest neighbour classification on this data.** Assume the classifier uses a Euclidean distance metric and outputs either 1 or 2.

The boundary does not need to be exact - a print out of figure 1 with boundaries drawn approximately is sufficient. Make sure to label the regions with the classification label that would be given.

### Exercise 3: Nearest neighbour example II

One of the problems with  $k$ -nearest neighbor classification is selecting a value for  $k$ . Say you are given the data set shown in figure 2 as training data from which a  $k$ NN classifier is constructed. Assume the classifier uses a Euclidean distance metric and outputs either 1 or 2.

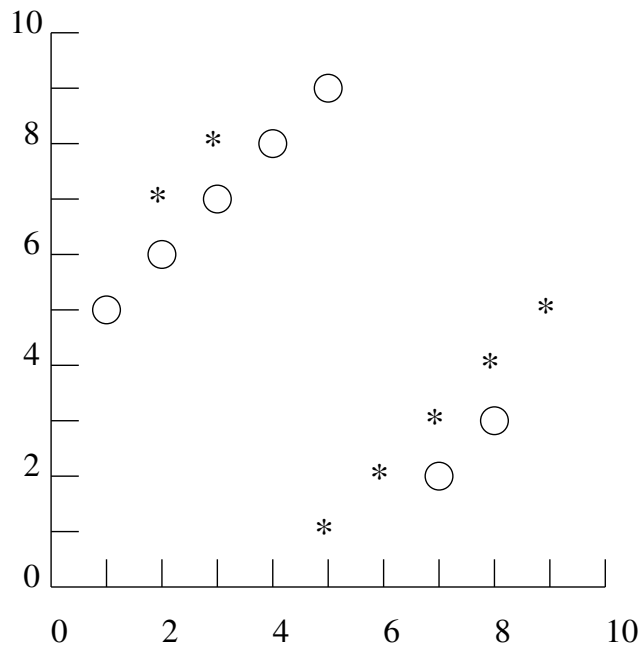


Figure 2: Training data for a  $k$ NN classifier.

**Questions** Why might using too large a value of  $k$  be bad for this data set? Why might using too small a value be bad for this data set?

**For the lecture:** 13th April

*Bring the following:*

- *Written solutions to Exercises 1 to 3.*

**Exercise 4:** *Error bound for 1-nearest neighbour classifier (optional)*

A classic paper of Cover and Hart [1] from 1967 shows that, as the amount of training data approaches infinity, the error rate of 1-nearest neighbour classifier is at most twice the Bayes-optimal error rate. In this exercise you will go through the proof for the case of binary classification with real-valued inputs.

Let  $\{\mathbf{x}_1, \mathbf{x}_2, \dots, \mathbf{x}_n\}$  be the training examples where each  $\mathbf{x}_i \in \mathbb{R}$  and  $\{\theta_1, \theta_2, \dots, \theta_n\}$  be their corresponding class labels, where each  $\theta_i \in \{\omega_1, \omega_2\}$ . Let  $p(\mathbf{x} | \omega_i)$  be the true class conditional probability distribution for points in class  $\omega_i$  and  $P(\omega_i)$  is the prior probability distribution for each class.

**Error of the Bayes' classifier**

From Lecture 3 we know that the classifier which minimizes the probability of error is defined and referred to as the Bayes' classifier:

$$\omega_m = \arg \max_i P(\omega_i | \mathbf{x}) = \arg \max_i p(\mathbf{x} | \omega_i) P(\omega_i)$$

Denote by  $P_B(\text{error})$  the error associated with the Bayes' classifier. It can be computed as follows via  $P_B(\text{error} | \mathbf{x})$ :

$$P_B(\text{error} | \mathbf{x}) = 1 - P_B(\text{correct} | \mathbf{x}) = 1 - P(\omega_m | \mathbf{x})$$

The error of the Bayes classifier, the best one can do, is then:

$$P_B(\text{error}) = \int_{\mathbf{x}} P_B(\text{error} | \mathbf{x}) p(\mathbf{x}) d\mathbf{x} = \int_{\mathbf{x}} (1 - P(\omega_m | \mathbf{x})) p(\mathbf{x}) d\mathbf{x}$$

**Error of the 1-NN classifier**

Now let's investigate the 1-NN (nearest neighbour) classifier and its probability of error. Suppose that the true class of an unseen point  $\mathbf{x}$  is  $\theta$  and that  $\mathbf{x}' \in \{\mathbf{x}_1, \mathbf{x}_2, \dots, \mathbf{x}_n\}$  is  $\mathbf{x}$ 's nearest neighbour from the training data.

For the nearest neighbour classifier the probability of error given  $\mathbf{x}$  and its nearest neighbour  $\mathbf{x}'$  is:

$$\begin{aligned}
P_N(\text{error} | \mathbf{x}, \mathbf{x}') &= 1 - P_N(\text{correct} | \mathbf{x}, \mathbf{x}') \\
&= 1 - \sum_{i=1}^2 P(\theta = \omega_i, \theta' = \omega_i | \mathbf{x}, \mathbf{x}') \\
&= 1 - \sum_{i=1}^2 P(\theta = \omega_i | \mathbf{x}, \mathbf{x}') P(\theta' = \omega_i | \mathbf{x}, \mathbf{x}'), \mathbf{x} \text{ and } \mathbf{x}' \text{ drawn independently} \\
&= 1 - \sum_{i=1}^2 P(\theta = \omega_i | \mathbf{x}) P(\theta' = \omega_i | \mathbf{x}')
\end{aligned}$$

The probability of error for the nearest neighbour classifier given  $\mathbf{x}$  is:

$$P_N(\text{error} | \mathbf{x}) = \int_{\mathbf{x}'} P_N(\text{error} | \mathbf{x}, \mathbf{x}') p(\mathbf{x}' | \mathbf{x}) d\mathbf{x}'$$

### Error of the 1-NN classifier as training data tends towards $\infty$

As the number of training examples tends towards infinity that is  $n \rightarrow \infty$  then  $\mathbf{x}' \rightarrow \mathbf{x}$  and  $p(\mathbf{x}' | \mathbf{x}) \rightarrow \delta(\mathbf{x}' - \mathbf{x})$ . Thus as  $n \rightarrow \infty$

$$P_N(\text{error} | \mathbf{x}, \mathbf{x}') = 1 - \sum_{i=1}^2 P(\omega_i | \mathbf{x}) P(\omega_i | \mathbf{x}') \longrightarrow 1 - \sum_{i=1}^2 P(\omega_i | \mathbf{x})^2$$

and

$$P_N(\text{error} | \mathbf{x}) = \int_{\mathbf{x}'} P_N(\text{error} | \mathbf{x}, \mathbf{x}') p(\mathbf{x}' | \mathbf{x}) d\mathbf{x}' \longrightarrow 1 - \sum_{i=1}^2 P(\omega_i | \mathbf{x})^2 \quad (1)$$

Let  $\omega_m$  be the prediction of the class of  $\mathbf{x}$  by the Bayes classifier. Then let  $\omega_l$  be the other class and thus

$$P(\omega_l | \mathbf{x}) = 1 - P(\omega_m | \mathbf{x}) = P_B(\text{error} | \mathbf{x})$$

Therefore

$$P(\omega_m | \mathbf{x}) = 1 - P_B(\text{error} | \mathbf{x}) \quad (2)$$

**Use equations (1) and (2) to express  $P_N(\text{error} | \mathbf{x})$  in terms of  $P_B(\text{error} | \mathbf{x})$ . Then express  $P_N(\text{error})$  in terms of  $P_B(\text{error})$  and deduce that  $P_N(\text{error}) \leq 2 P_B(\text{error})$  for the case of infinite training data.**

## References

- [1] T Cover and P. Hart. Nearest neighbor pattern classification. *IEEE Transactions on Information Theory*, pages 21–27, January 1967.