

SYMBOLIC EXECUTION

The verification method that VERIFAST uses is called symbolic execution and is conceptually related to verification condition generation, but accomplishes the task by a different means.

ASSERT AND ASSUME

First, we extend our programming language with three new statements:

assert (ϕ) - aborts if ϕ evaluates to false

assume (ϕ) - halts if ϕ evaluates to false (ignore such paths)

havoc (V) - assign arbitrary values to all variables $v \in V$

Then: $F_{\text{par}}(\phi) \vdash C(\psi)$ if and only if the program
 $\text{assume}(\phi); C; \text{assert}(\psi)$ does not abort

SYMBOLIC EXECUTION

- we execute programs starting from a symbolic state, with symbolic constants as initial values (we use X, Y, ...)
- we consider all (feasible) paths from entry to exit point
- as we go along paths, we:
 - update symbolic state after assignment and havoc statements
 - update path condition when branching on Boolean guards and assumes:
 - substitute current symbolic values for the variables in the guard and add resulting formula to current path condition (check feasibility)
 - generate and prove proof obligations at assert statements; abort execution if false. Proof obligation is:
 - $\vdash \text{current_path_cond} \rightarrow \text{assert_cond}[\text{symb_vals}/\text{vars}]$

We illustrate the technique on Abs:

$$(x = x_0) \text{ if } (x > 0) \{ y = x; \} \text{ else } \{ y = -x; \} \quad (y = |x_0|)$$

First, we transform the Hoare triple to a program. We introduce labels at control points to help following the paths:

```

L1: assume (x=x0);
L2: if (x>0) {
L3:   y=x;
      } else {
L4:   y=-x;
      }
L5: assert (y=|x0|);
L6: return

```

We have two paths to consider: The first one is:

LABEL	SYMB. STATE	PATH COND.	PROOF OBLIG.
L ₁	x ↦ X, y ↦ Y	true	
L ₂	x ↦ X, y ↦ Y	X = x ₀	
L ₃	x ↦ X, y ↦ Y	X = x ₀ ∧ X > 0	
L ₅	x ↦ X, y ↦ X	X = x ₀ ∧ X > 0	$\vdash X = x_0 \wedge X > 0 \rightarrow X = x_0 $
L ₆	x ↦ X, y ↦ X	X = x ₀ ∧ X > 0	

Compare the resulting proof obligation with the one from our proof in Hoare logic: $\vdash x = x_0 \wedge x > 0 \rightarrow x = |x_0|$

The second path L₁L₂L₄L₅L₆ is handled similarly: Exercise

Loops while $B\{C\}$ annotated with (candidate) invariants η are translated/re-written to the command sequence:

```

assert( $\eta$ );
havoc( $\text{Var}_c$ );
assume( $\eta$ );
if  $B\{$ 
    C;
    assert( $\eta$ );
    assume(false);
} else{
    skip;
}

```

where Var_c denotes all variables that are assigned to in the loop body C. Symbolic execution of $\text{havoc}(\text{Var}_c)$ assigns new/fresh symbolic constants to the variables in Var_c . Then, the path condition can be simplified. The $\text{assume}(\text{false})$ statement above has the effect that the current path is not explored any further.

EXERCISE: Verify Copy; annotated with a loop invariant:

$$(x = x_0 \wedge x \geq 0) \quad y = 0; \quad (x + y = x_0) \text{ while } (x \neq 0) \quad \{y = y + 1; x = x - 1\} \quad (y = x_0)$$

VERIFast halts at points where

- current path condition is false : go to next path
- proof obligation is false : report an error

The presented method is equivalent to that of VCG, due to a fundamental equivalence for the assignment statement:

assertion $\Psi[E/x]$ holds in a state if and only if Ψ holds in the state resulting from s after executing the assignment $x = E$