
DN2222
Applied Numerical Methods
- part 2:
Numerical Linear Algebra

Lecture 2: Error Analysis &
Gaussian Elimination

2011-10-25

Norm

- A norm is a function mapping from R^n to R fulfilling the following three conditions:
 - $f(x) \geq 0$ and $f(x) = 0$ if and only if $x = 0$.
 - $f(\alpha x) = |\alpha|f(x)$ for all $\alpha \in R$ and all $x \in R^n$
 - $f(x + y) \leq f(x) + f(y)$ for all x and $y \in R^n$
 - A norm is often denoted by $\|\cdot\|$ (avoid $|\cdot|$!!!)
-

Famous Norms

- Euclidian norm, $\|x\|_2 = \sqrt{\sum_{i=1}^n x_i^2}$
 - Infimum norm, $\|x\|_\infty = \max_{i=1:n} |x_i|$
 - Maximum norm (or 1-norm), $\|x\|_1 = \sum_{i=1}^n |x_i|$
 - ℓ_p -norm, $\|x\|_p = (\sum_{i=1}^n x_i^p)^{(1/p)}$
-

Quiz

- If $\|x\|_2 < \|y\|_2$ what about the relation between $\|x\|_\infty$ and $\|y\|_\infty$?
-

Quiz' answer

- If $\|x\|_2 < \|y\|_2$ what about the relation between $\|x\|_\infty$ and $\|y\|_\infty$?
 - Nothing! See below:
 - Ex1: If $x = (1, 2)$ and $y = (3, 4)$ then $2 = \|x\|_\infty < \|y\|_\infty = 4$
 - Ex2: If $x = (10, 1)$ and $y = (8, 9)$ then $10 = \|x\|_\infty > \|y\|_\infty = 9$
-

Equivalent Norms

- Two norms $\|\cdot\|_\alpha$ and $\|\cdot\|_\beta$ in R^n are *equivalent* if there exists two constants $m > 0$ and $M > 0$ such that for all $x \in R^n$

$$m\|x\|_\alpha \leq \|x\|_\beta \leq M\|x\|_\alpha$$

- All vector norms in R^n are equivalent
-

Equivalent Norms (cont.)

The following relations are useful when converting error bounds in terms of one norm to error bounds in terms of another norm.

$$\|x\|_2 \leq \|x\|_1 \leq \sqrt{n}\|x\|_2$$

$$\|x\|_\infty \leq \|x\|_2 \leq \sqrt{n}\|x\|_\infty$$

$$\|x\|_\infty \leq \|x\|_1 \leq n\|x\|_\infty$$

(D p21: Lemma 1.5)

Inner product

Let B be a complex linear space. $\langle \cdot, \cdot \rangle: B \times B \rightarrow R$ is an inner product if all of the following apply:

- 1) $\langle x, y \rangle = \overline{\langle y, x \rangle}$
 - 2) $\langle x, y + z \rangle = \langle x, y \rangle + \langle x, z \rangle$
 - 3) $\langle \alpha x, y \rangle = \alpha \langle x, y \rangle$
 - 4) $\langle x, x \rangle \geq 0$ and $\langle x, x \rangle = 0$ iff $x = 0$
- x and y are orthogonal if $\langle x, y \rangle = 0$
 - $\sqrt{\langle x, x \rangle}$ is a norm.

Cauchy-Schwartz' inequality

- $|\langle x, y \rangle| \leq \sqrt{\langle x, x \rangle \langle y, y \rangle}$

Induced matrix norm

Let A be $m \times n$, $\|\cdot\|_{\hat{m}}$ be a norm on R^m and $\|\cdot\|_{\hat{n}}$ be a norm on R^n . Then

$$\|A\|_{\hat{m}\hat{n}} = \max_{x \neq 0} \frac{\|Ax\|_{\hat{m}}}{\|x\|_{\hat{n}}}$$

is called an operator norm or *induced norm* or subordinate norm.

- For operator norms we have $\|AB\| \leq \|A\| \cdot \|B\|$.

Special matrix norms

- $\|A\|_1 = \|A^T\|_\infty = \max_j \sum_i |a_{ij}|$ = maximum column sum.
- $\|A\|_2 = \sqrt{\lambda_{\max}(A^* A)}$
- $\|A\|_2 = \|A^T\|_2$
- $\|A\|_F = \sqrt{\sum_i \sum_j |a_{ij}|^2}$, the Frobenius norm.

Perturbation Theory

Suppose $Ax = b$ and $(A + \delta A)\hat{x} = b + \delta b$. Our goal is to bound the norm of $\delta x = \hat{x} - x$.

$$\begin{aligned} (A + \delta A)(x + \delta x) &= b + \delta b \\ Ax &= b \\ \longrightarrow \delta Ax + (A + \delta A)\delta x &= \delta b \end{aligned}$$

giving $\delta x = A^{-1}(\delta b - \delta A \hat{x})$ and

$$\|\delta x\| \leq \|A^{-1}\|(\|\delta b\| + \|\delta A\| \cdot \|\hat{x}\|)$$

We can also derive

$$\frac{\|\delta x\|}{\|\hat{x}\|} \leq \|A^{-1}\| \cdot \|A\| \cdot \left(\frac{\|\delta A\|}{\|A\|} + \frac{\|\delta b\|}{\|A\| \cdot \|\hat{x}\|} \right)$$

- The quantity $\kappa(A) = \|A^{-1}\| \cdot \|A\|$ is the *condition number*.

Use the residual

$$Ax = b$$

$$A\hat{x} = \hat{b}$$

$$A(x - \hat{x}) = b - \hat{b}$$

$$x - \hat{x} = A^{-1}(b - \hat{b})$$

$$x - \hat{x} = A^{-1}(b - A\hat{x})$$

$$x - \hat{x} = A^{-1}r$$

$$\|x - \hat{x}\| = \|A^{-1}\| \cdot \|r\|$$

LU-decomposition

- There exists a unique unit lower triangular matrix L and a non-singular upper triangular matrix U such that $A = LU$.
- **D: Thm 2.5** If A is non-singular, there exist permutations P_1 and P_2 , a unit lower matrix L , and a nonsingular upper triangular matrix U such that $P_1 A P_2 = LU$.
- one of the permutation matrices is necessary. $P_1 A$ reorders the rows of A , $A P_2$ reorders the columns of A ,

Permutation matrix

- A permutation matrix is the identity-matrix with permuted rows.
- PX is the same as X with its rows permuted.
- XP is the same as X with its columns permuted.
- $P^{-1} = P^T$
- $\det(P) = \pm 1$
- $P = \pm P_1 \cdot P_2$ is also a permutation matrix.

Floating Point Arithmetic

$$\text{fl}(a \circ b) = (a \circ b) \cdot (1 + \delta)$$

δ is bounded by ϵ , the machine epsilon or machine precision.

Example

- Calculate $z = a + b + c$
 - Step 1: $w = \text{fl}(a + b) = (a + b) \cdot (1 + \delta)$
 - Step 2: $z = \text{fl}(w + c) = (w + c) \cdot (1 + \delta)$
 $= ((a + b) \cdot (1 + \delta) + c) \cdot (1 + \delta)$
 $= (a + b + c) \cdot (1 + \delta) + (a + b) \cdot (1 + \delta)^2$
 - Note that the error does not depend equally on all a , b , and c !!!
-

Gaussian Elimination

on the blackboard...

Pivoting

on the blackboard...

Some review questions:

- **Q21.** Define the condition number of a matrix.
- **Q22.** Describe what happens with the solution x of a linear system $Ax = b$ when the right hand side b is perturbed into $b + \delta b$.
- **Q25.** What is meant with pivoting for stability?
- **Q28.** How many arithmetic operations are needed for computing the Gaussian elimination LU -factorization of an $n \times n$ -matrix A ?
- **Q29.** How many arithmetic operations are needed to solve a linear system by forward and backward substitution, once the triangular factors L and U are computed?
- **Q31.** How many arithmetic operations are needed to multiply a $m \times n$ matrix by a $n \times p$ matrix? Compare with the count for Gaussian elimination!