

Hints and solutions to problems in course book: Computational Differential Equations

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If the problem has been solved at an excercise session this is indicated, see your notes from that session.

If nothing else is indicated the following conventions are used:

$$\|w\| \equiv \|w\|_{L_2(\Omega)}$$

Chapter 4

4.21: Move absolute values inside integral:

$$\begin{aligned} |(f, g)| &= \left| \int_a^b f(x) g(x) dx \right| \leq \int_a^b |f(x) g(x)| dx = \int_a^b |f(x)| |g(x)| dx \\ &\leq \int_a^b \max_{x \in (a,b)} |f(x)| |g(x)| dx = \max_{x \in [a,b]} |f(x)| \int_a^b |g(x)| dx = \|f\|_{L_\infty(a,b)} \|g\|_{L_1(a,b)} \end{aligned}$$

4.22: Prove conditions for a norm at p.63. First condition is given by continuity of the function: the only function f such that $\|f\|_{L_p(a,b)} = 0$ for $p = 1, 2, \infty$ is $f = 0$. We then prove the second and third conditions:

$$\begin{aligned} \|\alpha f\|_{L_1(a,b)} &= \int_a^b |\alpha f(x)| dx = \int_a^b |\alpha| |f(x)| dx = |\alpha| \int_a^b |f(x)| dx \\ \|\alpha f\|_{L_2(a,b)} &= \left(\int_a^b |\alpha f(x)|^2 dx \right)^{1/2} = \left(|\alpha|^2 \int_a^b |f(x)|^2 dx \right)^{1/2} = |\alpha| \left(\int_a^b |f(x)|^2 dx \right)^{1/2} \end{aligned}$$

$$\|\alpha f\|_{L_\infty(a,b)} = \max_{x \in (a,b)} |\alpha f(x)| = \max_{x \in (a,b)} |\alpha| |f(x)| = |\alpha| \max_{x \in (a,b)} |f(x)|$$

To prove the third condition, the triangle inequality, we prove some useful inequalities that are valid for general domains $\Omega \subset \mathbb{R}^d$:

Young's inequality:

$$ab \leq \frac{a^p}{p} + \frac{b^q}{q}, \quad a, b \geq 0, \quad p > 1, \quad \frac{1}{p} + \frac{1}{q} = 1$$

Proof: $\log(x)$ is concave: $\log(\lambda x_1 + (1-\lambda)x_2) \geq \lambda \log(x_1) + (1-\lambda) \log(x_2)$

$$\log(ab) = \frac{1}{p} \log a^p + \frac{1}{q} \log b^q \leq \log\left(\frac{a^p}{p} + \frac{b^q}{q}\right)$$

Hölder's inequality:

$$\|f g\|_{L_1(\Omega)} \leq \|f\|_{L_p(\Omega)} \|g\|_{L_q(\Omega)}, \quad \frac{1}{p} + \frac{1}{q} = 1$$

Proof: Using Young's inequality, with the notation: $\|f\|_p \equiv \|f g\|_{L_p(\Omega)}$

$$\begin{aligned} \frac{\|f g\|_1}{\|f\|_p \|g\|_q} &= \frac{1}{\|f\|_p \|g\|_q} \int_{\Omega} |f g| \, dx = \int_{\Omega} \frac{|f|}{\|f\|_p} \frac{|g|}{\|g\|_q} \, dx \\ &\leq \frac{1}{p} \int_{\Omega} \left(\frac{|f|}{\|f\|_p} \right)^p \, dx + \frac{1}{q} \int_{\Omega} \left(\frac{|g|}{\|g\|_q} \right)^q \, dx \\ &= \frac{1}{p} \frac{1}{\|f\|_p^p} \int_{\Omega} |f|^p \, dx + \frac{1}{q} \frac{1}{\|g\|_q^q} \int_{\Omega} |g|^q \, dx = \frac{1}{p} + \frac{1}{q} = 1 \end{aligned}$$

Cauchy-Schwarz inequality: Follows by Hölder's inequality ($p = 2$):

$$|(f, g)| = \left| \int_{\Omega} f g \, dx \right| \leq \int_{\Omega} |f g| \, dx = \|f g\|_1 \leq \|f\|_2 \|g\|_2$$

Minkowski's inequality:

$$\|f + g\|_p \leq \|f\|_p + \|g\|_p$$

Proof: With $q = p/p - 1$, so that $(p-1)q = p$:

$$|f+g|^p = |f+g| |f+g|^{p-1} \leq (|f| + |g|) |f+g|^{p-1} = |f| |f+g|^{p-1} + |g| |f+g|^{p-1}$$

$$\begin{aligned} \int_{\Omega} |f| |f+g|^{p-1} dx &\leq \left(\int_{\Omega} |f|^p dx \right)^{1/p} \left(\int_{\Omega} |f+g|^{(p-1)q} dx \right)^{1/q} \\ \int_{\Omega} |g| |f+g|^{p-1} dx &\leq \left(\int_{\Omega} |g|^p dx \right)^{1/p} \left(\int_{\Omega} |f+g|^{(p-1)q} dx \right)^{1/q} \\ \Rightarrow \left(\int_{\Omega} |f+g|^p dx \right)^{1/p} &= \left(\int_{\Omega} |f+g|^p dx \right)^{1-1/q} = \frac{\int_{\Omega} |f+g|^p dx}{\left(\int_{\Omega} |f+g|^p dx \right)^{1/q}} \leq \|f\|_p + \|g\|_p \end{aligned}$$

Minkowski's inequality gives the triangle inequality for the norms $\|\cdot\|_p$ with $p = 1, 2$, and for $\|\cdot\|_\infty$ we get the triangle inequality by the triangle inequality of the absolute value.

4.24:

$$\begin{aligned} \|\sin \pi x\|_{L_\infty(0,1)} &= \sin \frac{\pi}{2} = 1 \\ \|\sin \pi x\|_{L_1(0,1)} &= \int_0^1 |\sin \pi x| dx = \int_0^1 \sin \pi x dx = \left[\frac{-\cos \pi x}{\pi} \right] = \frac{2}{\pi} \\ \|\sin \pi x\|_{L_2(0,1)}^2 &= \dots = \frac{1}{2} - \frac{\sin 2}{4} \Rightarrow \|\sin \pi x\|_{L_2(0,1)} = \dots = \sqrt{\frac{1}{2} - \frac{\sin 2}{4}} \\ \|x^2\|_{L_\infty(0,1)} &= \dots = 1 \\ \|x^2\|_{L_1(0,1)} &= \int_0^1 |x^2| dx = \int_0^1 x^2 dx = \left[\frac{x^3}{3} \right]_0^1 = \frac{1}{3} \\ \|x^2\|_{L_2(0,1)} &= \left(\int_0^1 |x^2|^2 dx \right)^{1/2} = \dots = \frac{1}{\sqrt{5}} \\ \|e^x\|_{L_\infty(0,1)} &= e^1 = e \\ \|e^x\|_{L_1(0,1)} &= \int_0^1 |e^x| dx = \int_0^1 e^x dx = \dots = e - 1 \end{aligned}$$

$$\|e^x\|_{L_2(0,1)} = \left(\int_0^1 |e^x|^2 dx \right)^{1/2} = \dots = \frac{e^2 - 1}{2}$$

4.25: The function $f(x) = x^{-s}$ is in the space $L_p(0, 1)$ if $\|f\|_{L_p(\Omega)} < \infty$.

$$\int_\epsilon^1 x^{-s} dx = \left[\frac{x^{1-s}}{1-s} \right]_\epsilon^1 = \frac{1 - \epsilon^{1-s}}{1-s}$$

$\epsilon \rightarrow 0 \Rightarrow \frac{1 - \epsilon^{1-s}}{1-s} \rightarrow \infty$ if $s \geq 1$. That is, $f(x) = x^{-s} \in \|f\|_{L_1(0,1)}$ if $s < r = 1$. Similarly, $f(x) = x^{-s} \in \|f\|_{L_2(0,1)}$ if $s < r = 0.5$.

Chapter 5

5.8: Use Lagrange's formula (5.1):

$$\pi_3 f(x) = \sin(0)\lambda_0(x) + \sin(\pi/6)\lambda_1(x) + \sin(\pi/4)\lambda_2(x) + \sin(\pi/3)\lambda_3(x)$$

$$\begin{aligned} &= \frac{1}{2}\lambda_1(x) + \frac{1}{\sqrt{2}}\lambda_2(x) + \frac{\sqrt{3}}{2}\lambda_3(x) \\ &\lambda_1(x) \frac{(x-0)(x-\pi/4)(x-\pi/3)}{(\pi/6-0)(\pi/6-\pi/4)(\pi/6-\pi/3)} \\ &\lambda_2(x) \frac{(x-0)(x-\pi/6)(x-\pi/3)}{(\pi/4-0)(\pi/4-\pi/6)(\pi/4-\pi/3)} \\ &\lambda_3(x) \frac{(x-0)(x-\pi/6)(x-\pi/4)}{(\pi/3-0)(\pi/3-\pi/6)(\pi/3-\pi/4)} \end{aligned}$$

5.9: Excercise session 3. Use definition of λ_i at p.76:

$$\lambda_0 + \lambda_1 = \frac{x-b}{a-b} + \frac{x-a}{b-a} = \frac{a-b}{a-b} = 1$$

$$(\xi_0 - x)\lambda_0(x) + (\xi_1 - x)\lambda_1(x) = (\xi_0 - x) \frac{x - \xi_1}{\xi_0 - \xi_1} + (\xi_1 - x) \frac{x - \xi_0}{\xi_1 - \xi_0} = 0$$

Use (5.4),(5.5), and the above equalities, to prove the error representation formula.

5.13:

$$\lambda'_0 + \lambda'_1 = \frac{1}{a-b} + \frac{1}{b-a} = 0$$

$$(\xi_0 - x)\lambda'_0(x) + (\xi_1 - x)\lambda'_1(x) = \frac{x_0 - x}{\xi_0 - \xi_1} + \frac{\xi_1 - x}{\xi_1 - \xi_0} = 1$$

5.14: See lecture notes from Lecture 4.

5.17: Excercise session 3. Use the coordinate transformation $x = \xi b + (1 - \xi)a$, with $\xi \in (0, 1)$ and $x \in (a, b)$. This gives that $dx = (b - a)d\xi$, and $\frac{\partial f}{\partial \xi} = \frac{\partial f}{\partial x} \frac{\partial x}{\partial \xi} = (b - a)\frac{\partial f}{\partial x}$.

$$\begin{aligned}\|f\|_{L_p(0,1)} &= \left(\int_0^1 |f(\xi)|^p d\xi \right)^{1/p} = \left(\int_a^b |f(x)|^p (b - a) dx \right)^{1/p} = (b - a)^{1/p} \|f\|_{L_p(a,b)} \\ \|f''\|_{L_p(0,1)} &= \left(\int_0^1 |f''(\xi)|^p d\xi \right)^{1/p} = \left(\int_a^b |(b - a)^2 f''(x)|^p (b - a) dx \right)^{1/p} \\ &= (b - a)^{(2p+1)/p} \|f''\|_{L_p(a,b)}\end{aligned}$$

Thus,

$$\begin{aligned}\|f - \pi_i f\|_{L_p(0,1)} &\leq \|f''\|_{L_p(0,1)} \\ \Rightarrow (b - a)^{1/p} \|f - \pi_i f\|_{L_p(a,b)} &\leq (b - a)^{2+1/p} \|f''\|_{L_p(a,b)} \\ \Rightarrow \|f - \pi_i f\|_{L_p(a,b)} &\leq (b - a)^2 \|f''\|_{L_p(a,b)}\end{aligned}$$

5.23: For sub-interval $I_i = (x_{i-1}, x_i)$, choose for example the midpoint $\bar{x}_i = (x_{i-1} + x_i)/2$, and then use the second degree Lagrange polynomial defined on page p.76.

5.24:

$$\varphi_0(x) = \frac{x_1 - x}{x_1 - x_0}, \quad \varphi_{m+1}(x) = \frac{x - x_m}{x_{m+1} - x_m}$$

Chapter 6

6.2: Use (6.4). You do not have to solve the resulting systems of equations.

The case $q = 2$:

$$\begin{aligned} a_{11} &= \frac{1}{1+1} - \frac{1}{1+1+1} = \frac{1}{2} - \frac{1}{3} = \frac{1}{6} \\ a_{12} &= \frac{2}{2+1} - \frac{1}{2+1+1} = 1 - \frac{1}{4} = \frac{3}{4} \\ a_{21} &= \frac{1}{1+2} - \frac{1}{1+2+1} = \frac{1}{3} - \frac{1}{4} = \frac{1}{12} \\ a_{22} &= \frac{2}{2+2} - \frac{1}{2+2+1} = \frac{1}{2} - \frac{1}{5} = \frac{3}{10} \\ b_1 &= \frac{1}{1+1} = \frac{1}{2} \\ b_2 &= \frac{1}{2+1} = \frac{1}{3} \\ \begin{bmatrix} \frac{1}{6} & \frac{3}{4} \\ \frac{1}{12} & \frac{3}{10} \end{bmatrix} \begin{bmatrix} \xi_1 \\ \xi_2 \end{bmatrix} &= \begin{bmatrix} \frac{1}{2} \\ \frac{1}{3} \end{bmatrix} \end{aligned}$$

6.8:

$$a_{i-1,i} = \int_{x_{i-1}}^{x_i} \frac{-1}{h_i} \frac{1}{h_i} dx = \frac{-1}{h_i^2} \int_{x_{i-1}}^{x_i} dx = \frac{-1}{h_i}$$

6.9: $a_{ii} = 2/h$, $a_{i-1,i} = a_{i,i+1} = -1/h$, and all other entries zero.

6.10: Use the definition of the basis function $\varphi_i(x)$.

6.11: Use Problems 6.9 and 6.10.

6.12: All function in V_h can be written as a linear combination of the basisfunctions: $v \in V_h \Rightarrow v(x) = \sum_{i=1}^m \eta_i \varphi_i(x)$, $v'(x) = \sum_{i=1}^m \eta_i \varphi'_i(x)$

$$0 \geq (v'(x))^2 = \sum_{i=1}^m \eta_i \varphi'_i(x) \sum_{j=1}^m \eta_j \varphi'_j(x) = \sum_{i,j=1}^m \eta_i \eta_j \varphi'_i(x) \varphi'_j(x) = \sum_{i,j=1}^m \eta_i a_{ij} \eta_j = \eta^T A \eta$$

If not $\eta_i = 0$ for all $i = 1, 2, \dots, m$.

6.14: Excercise session 1. Use partial integration in equation (6.19).

Chapter 8

8.6 Similarly for a_{ii-1} and b_i .

$$\begin{aligned}
a_{ii} &= \int_0^1 a \varphi'_i \varphi'_i \, dx = \int_{x_{i-1}}^{x_i} (1+x) \frac{1}{h} \frac{1}{h} \, dx + \int_{x_i}^{x_{i+1}} (1+x) \frac{-1}{h} \frac{-1}{h} \, dx \\
&= \frac{1}{h^2} \left[x + \frac{x^2}{2} \right]_{x_{i-1}}^{x_i} + \frac{1}{h^2} \left[x + \frac{x^2}{2} \right]_{x_i}^{x_{i+1}} \\
&= \frac{1}{h^2} \left(h + h \frac{x_{i-1} + x_i}{2} \right) + \frac{1}{h^2} \left(h + h \frac{x_i + x_{i+1}}{2} \right) \\
&= \frac{1}{h} \left(2 + \frac{x_{i-1} + x_i}{2} + \frac{x_i + x_{i+1}}{2} \right) \\
a_{i-1i} &= \int_0^1 a \varphi'_{i-1} \varphi'_{i-1} \, dx = \int_{x_{i-1}}^{x_i} (1+x) \frac{1}{h} \frac{-1}{h} \, dx = \frac{-1}{h^2} \left[x + \frac{x^2}{2} \right]_{x_{i-1}}^{x_i} \\
&= \frac{-1}{h^2} \left(h + h \frac{x_{i-1} + x_i}{2} \right) = \frac{-1}{h} \left(1 + \frac{x_{i-1} + x_i}{2} \right)
\end{aligned}$$

8.7: Yes, the stiffness matrix is still symmetric, positive-definit and tridiagonal.

8.9:

$$\begin{aligned}
g'_z(x) &= \begin{cases} 1-z & 0 \leq x \leq z \\ -z & z \leq x \leq 1 \end{cases} \\
\int_0^1 g'_z(x) e'(x) \, dx &= \int_0^z (1-z) e'(x) \, dx + \int_z^1 (-z) e'(x) \, dx \\
&= (1-z) \int_0^z e'(x) \, dx - z \int_z^1 e'(x) \, dx \\
&= (1-z)(e(z) - e(0)) - z(e(1) - e(z)) = e(z)
\end{aligned}$$

$$e(z) = \int_0^1 g'_z(x) e'(x) \, dx = - \int_0^1 g_z(x) u''(x) \, dx + [g_z(x) u'(x)]_0^1$$

$$\begin{aligned}
&= - \int_0^1 g_z(x)(u''(x) - U''(x)) dx = \int_0^1 g_z(x)(f(x) + U''(x)) dx \\
&= \int_0^1 g_z(x)R(x) dx = 0 \text{ if } g_z \in V_h, \\
&\text{and } g_z \in V_h \text{ if and only if } z = x_j \text{ (with } x_j \text{ a node in the mesh of } V_h)
\end{aligned}$$

8.10:

$$\begin{aligned}
&- \int_0^1 g_z''(x)v(x) dx = \int_0^1 g_z'(x)v'(x) dx - [g_z'(x)v(x)]_0^1 \\
&= (1-z) \int_0^z v'(x) dx - z \int_z^1 v'(x) dx - (-zv(1) - (1-z)v(0)) \\
&= (1-z)(v(z)-z(0))-z(v(1)-v(z))+(zv(1)+(1-z)v(0)) = v(z) \Rightarrow -g_z''(x) = \delta_z(x)
\end{aligned}$$

8.11: Excercise session 3.

8.12: Excercise session 3. Partial integration of (8.13), then use the Robin condition (8.12).

8.13: At the left end-node $x_0 = 0$ there is a trial basis function but no test basis function. Integrating over the element $I_i = [x_0, x_1]$, we get the equation

$$\xi_0 - \xi_1 = 0$$

and for the rest of the unknowns ξ_i we get equations:

$$-\xi_{i-1} + 2\xi_i - \xi_{i+1}$$

With M interior nodes we get a $M + 1 \times M + 1$ system with $i = 0, 1, 2, \dots, M$.

8.16:

8.17: Excercise session 5.

$$\left| \int_0^1 av'w' dx \right| = \left| \int_0^1 (a^{1/2}v')(a^{1/2}w') dx \right| \leq \|v'\|_a \|w'\|_a$$

$$\left| \int_0^1 v'w' dx \right| = \left| \int_0^1 (a^{1/2}v')(a^{-1/2}w') dx \right| \leq \|v'\|_a \|w'\|_{-a}$$

8.18:

$v(x)$ for $x \in (0, 1)$ and with $v(0) = 0$:

$$\begin{aligned} v(y) &= \int_0^y v'(x) dx = \int_0^y a^{-1/2}(a^{1/2}v'(x)) dx \\ &\leq (\int_0^y a^{-1} dx)^{1/2} (\int_0^y a(v')^2(x) dx)^{1/2} \quad 0 < y < 1 \end{aligned}$$

$$\text{If } \int_0^1 a^{-1} dx < \infty \Rightarrow$$

$$|v(y)| \leq (\int_0^y a^{-1} dx)^{1/2} (\int_0^y a(v')^2(x) dx)^{1/2} \leq \|1\|_{a^{-1}} \|v\|_E \Rightarrow \|v\|_\infty \leq \|1\|_{a^{-1}} \|v\|_E$$

8.20:

$$\|hR(U)\|_{a^{-1}} = \|ha^{-1/2}(f + (aU')'\| = \|ha^{-1/2}(-(au')' + (aU')')\|$$

$$= \|ha^{-1/2}(-a'u' - au'' + a'U')\| = \|ha^{1/2}(\frac{a'}{a}(U' - u') + (-u'')\|$$

$$\leq C\|u' - U'\|_a + \|hu''\|_a \leq C\|u' - \pi_h u'\|_a + \|hu''\|_a \leq (CC_i + 1)\|hu''\|_a$$

8.21:

8.22:

The a priori error estimate is the same since the same Galerkin orthogonality holds for the weak formulation:

$$\int_0^1 au'v' \, dx = \int_0^1 fv \, dx + g_1 v(1)$$

For the a posteriori error estimate, note that

$$g_1(e(1) - \pi_h e(1)) = 0$$

8.23:

8.37:

8.40:

8.41:

Chapter 9

9.4: Excercise session 4.

9.5: Excercise session 4.

9.10: Excercise session 5.

Chapter 10

10.18: Excercise session 4.

10.21: Excercise session 4.

Chapter 13

13.30 Excercise session 1. Use (13.12) with $w = \frac{\partial w}{\partial x_i}$

Chapter 14

14.9 $(\phi_i, \phi_j) = \int_{\Omega} \phi_i(x) \phi_j(x) \, dx$; is zero for all i, j so that the support of ϕ_i and ϕ_j do not overlap.

Chapter 15

15.14: Excercise session 1.

15.16: Excercise session 1.

15.19: Excercise session 6.

15.20: Excercise session 6.

15.21: Excercise session 6.

15.44:

15.45: Excercise session 1.

15.48:

15.49: Excercise session 5.

Chapter 16

16.14 Excercise session 4.

Chapter 21

21.1 Excercise session 2. Bilinear and linear forms for equations (8.1), (8.2), and (15.18):

$$(8.1) : \quad a(u, v) = \int_0^1 u'v' + cuv \, dx \quad L(v) = \int_0^1 fv \, dx$$

$$(8.2) : \quad a(u, v) = \int_0^1 au'v' \, dx \quad L(v) = \int_0^1 fv \, dx$$

$$(15.18) : \quad a(u, v) = \int_{\Omega} \nabla u \cdot \nabla v \, dx \quad L(v) = \int_{\Omega} fv \, dx$$

21.2 For symmetric bilinear forms we define the energy norm as

$$\|w\|_a = a(w, w)^{1/2}$$

for which we have the Schwarz inequality:

$$|a(v, w)| \leq \|v\|_a \|w\|_a$$

Proof of equation (21.22):

$$\begin{aligned}\|u - U\|_a^2 &= a(u - U, u - U) = a(u - U, u - U) + a(u - U, U - v) \\ &= a(u - U, u - v) \leq \|u - U\|_a \|u - v\|_a\end{aligned}$$

Proof of analog of (21.5): bilinear form $a(\cdot, \cdot)$ is elliptic, and linear form $L(\cdot)$ is continuous, which gives:

$$\kappa_1 \|U\|_V \leq a(U, U) = L(U) \leq \kappa_3 \|U\|_V$$

21.8(a) Excercise session 2. Let $V = \{v \in H^1(0, 1) : v(0) = 0\}$,

$$\|w\|_V^2 = \|w\|_{H^1(0,1)}^2 = \int_0^1 |w'|^2 + w^2 dx = \|w'\|^2 + \|w\|^2$$

Multiply by $v \in V$, partial integration gives variational form:

$$\int_0^1 u'(x)v'(x) dx - [u'(x)v(x)]_0^1 + \alpha \int_0^1 u(x)v(x) dx = \int_0^1 f(x)v(x) dx$$

Boundary conditions gives:

$$\int_0^1 u'(x)v'(x) dx + \alpha \int_0^1 u(x)v(x) dx = \int_0^1 f(x)v(x) dx$$

Let $a(u, v) = \int_0^1 u'(x)v'(x) dx + \int_0^1 \alpha u(x)v(x) dx$ and $L(v) = \int_0^1 f(x)v(x) dx$.
For $\alpha = 1$ we have $\kappa_1 = 1$:

$$\|w\|_V^2 = \|w'\|^2 + \|w\|^2 = a(w, w)$$

For $\alpha = 0$ we have $\kappa_1 = \sqrt{3}$, using Poincare-Friedrichs inequality (21.17):

$$\|w\|_V^2 = \|w'\|^2 + \|w\|^2 \leq \|w'\|^2 + 2\|w'\|^2 = 3\|w'\|^2 = 3a(w, w)$$

That is, $a(\cdot, \cdot)$ is elliptic for $\alpha = 0, 1$. Continuity of $a(\cdot, \cdot)$ with $\kappa_2 = 1$ follows by Cauchy-Schwarz inequality, and since for $v_i, w_i > 0$:

$$v_1 w_1 + v_2 w_2 = (v_1, v_2) \cdot (w_1, w_2) \leq (v_1^2 + v_2^2)^{1/2} (w_1^2 + w_2^2)^{1/2}$$

For $\alpha = 1$:

$$\begin{aligned} a(v, w) &= \int_0^1 v'(x)w'(x) dx + \int_0^1 v(x)w(x) dx \leq \|v'\| \|w'\| + \|v\| \|w\| \\ &\leq (\|v'\|^2 + \|v\|^2)^{1/2}(\|w'\|^2 + \|w\|^2)^{1/2} = \|v\|_V \|w\|_V \end{aligned}$$

and for $\alpha = 0$:

$$\begin{aligned} a(v, w) &= \int_0^1 v'(x)w'(x) dx \leq \|v'\| \|w'\| \leq \|v'\| \|w'\| + \|v\| \|w\| \\ &\leq (\|v'\|^2 + \|v\|^2)^{1/2}(\|w'\|^2 + \|w\|^2)^{1/2} = \|v\|_V \|w\|_V \end{aligned}$$

Continuity of $L(\cdot)$ with $\kappa_2 = \|f\|$ follows by Cauchy-Schwarz inequality:

$$L(v) = \int_0^1 f(x)v(x) dx \leq \|f\| \|v\| \leq \|f\| \|v\|_V = \|f\| (\|v\|^2)^{1/2} \leq \|f\| \|v\|_V$$

21.8(b) Choose $V = \{v : \int_0^1 v'(x)^2 dx + v(0)^2 + v(1)^2 < \infty\}$

$$\|w\|_V^2 = \int_0^1 w'(x)^2 dx + w(0)^2 + w(1)^2$$

Multiply by $v \in V$, partial integration gives variational form:

$$\int_0^1 u'(x)v'(x) dx - [u'(x)v(x)]_0^1 = \int_0^1 f(x)v(x) dx$$

Boundary conditions gives:

$$\int_0^1 u'(x)v'(x) dx + u(0)v(0) + u(1)v(1) = \int_0^1 f(x)v(x) dx$$

Let

$$a(u, v) = \int_0^1 u'(x)v'(x) dx + u(0)v(0) + u(1)v(1)$$

and

$$L(v) = \int_0^1 f(x)v(x) dx$$

Ellipticity of $a(\cdot, \cdot)$ with $\kappa_1 = 1$ is given by

$$\|w\|_V^2 = \|w'\|^2 + w(0)^2 + w(1)^2 = a(w, w)$$

Continuity of $a(\cdot, \cdot)$ with $\kappa_2 = 1$ is given by

$$\begin{aligned} a(v, w) &= \int_0^1 v'(x)w'(x) dx + v(0)w(0) + v(1)w(1) \leq \|v'\| \|w'\| + v(0)w(0) + v(1)w(1) \\ &= (\|v'\|, v(0), v(1)) \cdot (\|w'\|, w(0), w(1)) \\ &\leq (\|v'\|^2 + v(0)^2 + v(1)^2)^{1/2} (\|w'\|^2 + w(0)^2 + w(1)^2)^{1/2} = \|v\|_V \|w\|_V \end{aligned}$$

Continuity of $L(\cdot)$ with $\kappa_3 = 1$:

$$L(v) = \int_0^1 f(x)v(x) dx \leq \|f\| \|v\| \leq \|f\| (\|v\|^2 + v(0)^2 + v(1)^2)^{1/2} = \|f\| \|v\|_V$$

21.9 Excercise session 5. Multiply by a test function v and use integration by parts:

$$\int_0^1 u''(x)v''(x) dx + [u'''(x)v(x)]_0^1 - [u''(x)v'(x)]_0^1 = \int_0^1 f(x)v(x) dx$$

$$(a) u(0) = u'(0) = u(1) = u'(1) = 0$$

$$V = \{v \in H^2(0, 1) : v(0) = v'(0) = v(1) = v'(1) = 0\}$$

$$H^2(0, 1) = \{v : \int_0^1 (v(x)')^2 dx + \int_0^1 (v(x))' dx + \int_0^1 (v(x))^2 dx < \infty\}$$

$$\|w\|_V^2 = \int_0^1 (w''(x))^2 + (w'(x))^2 + (w(x))^2 dx$$

$$a(u, v) = \int_0^1 u''(x)v''(x) dx, \quad L(v) = \int_0^1 f(x)v(x) dx$$

Ellipticity of $a(\cdot, \cdot)$ with $\kappa_1 = \sqrt{7}$ follows by Poincare's inequality (21.17) for v and v' :

$$\begin{aligned}
\|v\|_V^2 &= \int_0^1 (v''(x))^2 + (v'(x))^2 + (v(x))^2 \, dx \\
&\leq \int_0^1 (v''(x))^2 + 2(v''(x))^2 + 2(v'(x))^2 \, dx \\
&\leq \int_0^1 (v''(x))^2 + 2(v''(x))^2 + 4(v''(x))^2 \, dx = 7a(v, v)
\end{aligned}$$

Continuity of $a(\cdot, \cdot)$ with $\kappa_2 = 1$ follows by Cauchy-Schwarz inequality:

$$a(v, w) = \int_0^1 v''(x)w''(x) \, dx \leq \|v''\| \|w''\| \leq \|v\|_V \|w\|_V$$

Continuity of $L(\cdot)$ with $\kappa_3 = \|f\|$ follows by Cauchy-Schwarz inequality:

$$L(v) = \int_0^1 f(x)v(x) \, dx \leq \|f\| \|v\| \leq \|f\| \|v\|_V$$

$$(b) \quad u(0) = u''(0) = u'(1) = u'''(1) = 0$$

$$V = \{v \in H^2(0, 1) : v(0) = v''(0) = v'(1) = v'''(1) = 0\}$$

$$\begin{aligned}
\|w\|_V^2 &= \int_0^1 (w''(8x))^2 + (w'(x))^2 + (w(x))^2 \, dx \\
a(u, v) &= \int_0^1 u''(x)v''(x) \, dx, \quad L(v) = \int_0^1 f(x)v(x) \, dx
\end{aligned}$$

Ellipticity and continuity shown similar to (a).

$$(c) \quad u(0) = -u''(0) + u'(0) = 0, \quad u(1) = u''(1) + u'(1) = 0$$

$$V = \{v : \int_0^1 (v''(x))^2 \, dx + \int_0^1 (v(x))^2 \, dx + (v'(0))^2 + (v'(1))^2 < \infty, \quad v(0) = v(1) = 0\}$$

$$\begin{aligned}
\|w\|_V^2 &= \int_0^1 (w''(x))^2 + (w'(x))^2 + (w(x))^2 \, dx \\
a(u, v) &= \int_0^1 u''(x)v''(x) \, dx, \quad L(v) = \int_0^1 f(x)v(x) \, dx
\end{aligned}$$

Ellipticity and continuity follows by Cauchy-Schwarz inequality and the inequality $v_1w_1 + v_2w_2 + v_3w_3 \leq (v_1 + v_2 + v_3)(w_1 + w_2 + w_3)$ for $v_i, w_i > 0$.

21.11 $f \in H^{-1}(\Omega)$ means that $\|f\|_{H^{-1}(\Omega)} < \infty$, with

$$\|f\|_{H^{-1}(\Omega)} \equiv \sup_{v \in H_0^1(\Omega)} \frac{(f, v)}{\|v\|_V}$$

This gives that

$$\frac{(f, v)}{\|v\|_V} \leq \|f\|_{H^{-1}(\Omega)} \quad \Rightarrow \quad (f, v) \leq \|f\|_{H^{-1}(\Omega)} \|v\|_V$$

with $\|\cdot\|_V = \|\cdot\|_{H^1(\Omega)}$. Thus

$$L(v) = \int_{\Omega} fv \, dx + \int_{\Gamma} gv \, ds \leq \|f\|_{H^{-1}(\Omega)} \|v\|_V + \|g\|_{L_2(\Gamma)} \|v\|_{L_2(\Gamma)}$$

$$\leq \|f\|_{H^{-1}(\Omega)} \|v\|_V + \|g\|_{L_2(\Gamma)} C \|v\|_{H^1(\Omega)} \leq (\|f\|_{H^{-1}(\Omega)} + C \|g\|_{L_2(\Gamma)}) \|v\|_V$$

by the trace inequality (21.20):

$$\|v\|_{L_2(\Gamma)} \leq C \|v\|_{H^1(\Omega)}$$

21.12 Excercise session 2. Find $u \in V$ such that

$$\int_{\Omega} \nabla u \cdot \nabla v \, dx = \int_{\Omega} fv \, dx, \quad \forall v \in \hat{V}$$

with

$$V = \{v \in H^1(\Omega) : v = g \text{ on } \Gamma\}, \quad \hat{V} = H_0^1(\Omega)$$

21.13 Excercise session 2. Similar to 21.8, but use Green's formula instead of integration by parts. For the case of $\alpha = \sigma = 0$ we cannot use Poincare-Friedrich's inequality (21.18), we cannot say anything about $\|u\|_{L_2(\Gamma)}$ since we only have a Neumann boundary condition $\partial_n u = g$ on Γ . Thus the conditions for Lax-Milgram are not satisfied. It is easy to see that indeed we do not have a unique solution to this problem, since for any solution $u(x)$, the solution plus a constant $u(x) + C$ is also a solution.

21.14 We prove ellipticity of $a(\cdot, \cdot)$ using

$$\int_{\Omega} (\beta \cdot \nabla v \cdot v + \alpha v^2) \, dx \geq 0$$

and the Poincare-Friedrich inequality (21.18):

$$a(w, w) = \int_{\Omega} \epsilon \nabla w \cdot \nabla w + \beta \cdot \nabla w \cdot w + \alpha w \cdot w \, dx \geq \epsilon \int_{\Omega} \nabla w \cdot \nabla w \, dx$$

$$\|w\|_V^2 = \|w\|^2 + \|\nabla w\|^2 \leq (C + 1) \|\nabla w\|^2 \leq \frac{C + 1}{\epsilon} a(w, w)$$

This means that the constant $\kappa_1 = \frac{\epsilon}{C + 1}$ decreases as ϵ decreases.

21.17 Use Poincare-Friedrich inequality for each vector component, and use the norm

$$\|v\|_V = \int_{\Omega} \sum_{i=1}^3 |\nabla v_i| \, dx$$