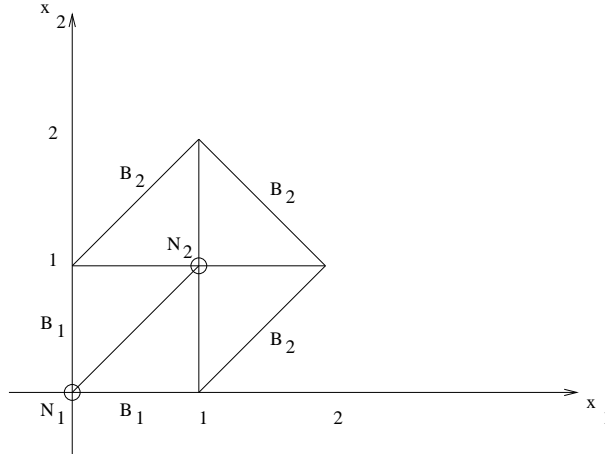


**TMA371/MAN660 Partial Differential Equations TM, IMP, E3, GU  
2003-04-22. Solutions**

1. Let  $\Omega$  be the triangulated domain below. Compute the cG(1) solution of  $-\Delta u = 0$  in  $\Omega$  with the Neumann data:  $\partial_n u = 3$  on  $B_1$  and Dirichlet condition:  $u = 0$  on  $B_2$ .



**Solution.**

Variational Formulation: Using Green's formula we have that

$$\begin{aligned}
 0 &= \int_{\Omega} -\Delta u v \, dx = \{\text{Green's}\} = \int_{\Omega} \nabla u \cdot \nabla v - \int_{\Gamma} (\partial_n u) v \\
 (1) \quad &= \{\Gamma := \partial\Omega := B_1 \cup B_2\} = \{v = 0 \text{ on } B_2, \text{ and } \partial_n u = 3 \text{ on } B_1\} \\
 &= \int_{\Omega} \nabla u \cdot \nabla v \, dx - \int_{B_1} 3v \, ds
 \end{aligned}$$

Thus we have the finite element formulation: Find piecewise linear function  $U \in V_h$  such that

$$(2) \quad \int_{\Omega} \nabla U \cdot \nabla v = \int_{B_1} 3v \, ds, \quad \forall v \in V_h.$$

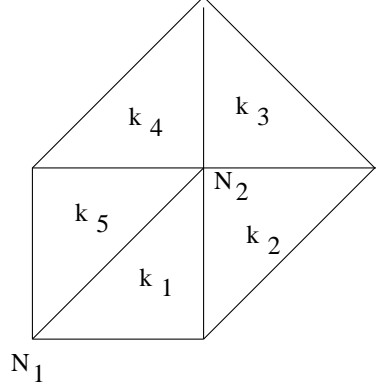
Let now

$$(3) \quad U(x) = U_1 \varphi_1(x) + U_2 \varphi_2(x),$$

where  $\varphi_i$  are the piecewise linears basis functions for the above discretization of  $\Omega$  with  $\varphi_i(N_j) = \delta_{ij}$ ,  $i, j = 1, 2$ . We insert (3) in (2) and let  $v = \varphi_i$ ,  $i = 1, 2$  to obtain a  $2 \times 2$  system viz,

$$(4) \quad \begin{cases} \int_{\Omega} \nabla \varphi_1 \cdot \nabla \varphi_1 \, dx U_1 + \int_{\Omega} \nabla \varphi_2 \cdot \nabla \varphi_1 \, dx U_2 = 3 \int_{B_1} \varphi_1 \, ds, \\ \int_{\Omega} \nabla \varphi_1 \cdot \nabla \varphi_2 \, dx U_1 + \int_{\Omega} \nabla \varphi_2 \cdot \nabla \varphi_2 \, dx U_2 = 3 \int_{B_1} \varphi_2 \, ds. \end{cases}$$

Note that using the orientation in the figure below we have



$$\begin{array}{l} \nabla\varphi_1|_{k_1} = (-1, 0) \quad \nabla\varphi_2|_{k_1} = (0, 1) \\ \nabla\varphi_1|_{k_2} = (0, 0) \quad \nabla\varphi_2|_{k_2} = (-1, 1) \\ \nabla\varphi_1|_{k_3} = (0, 0) \quad \nabla\varphi_2|_{k_3} = (-1, -1) \\ \nabla\varphi_1|_{k_4} = (0, 0) \quad \nabla\varphi_2|_{k_4} = (1, -1) \\ \nabla\varphi_1|_{k_5} = (0, -1) \quad \nabla\varphi_2|_{k_5} = (1, 0) \end{array}$$

Thus

$$\int_{\Omega} \nabla\varphi_1 \cdot \nabla\varphi_2 \, dx = \int_{\Omega} \nabla\varphi_2 \cdot \nabla\varphi_1 \, dx = 0,$$

and

$$\begin{aligned} \int_{\Omega} \nabla\varphi_1 \cdot \nabla\varphi_1 \, dx &= \sum_{i=1}^5 |k_i| \left( \nabla\varphi_1|_{k_i} \cdot \nabla\varphi_1|_{k_i} \right) \\ &= \frac{1}{2} \times (-1, 0) \cdot (-1, 0) + \frac{1}{2} \times (0, -1) \cdot (0, -1) = \frac{1}{2} + \frac{1}{2} = 1. \end{aligned}$$

Similarly

$$\begin{aligned} \int_{\Omega} \nabla\varphi_2 \cdot \nabla\varphi_2 \, dx &= \sum_{i=1}^5 |k_i| \left( \nabla\varphi_2|_{k_i} \cdot \nabla\varphi_2|_{k_i} \right) = \frac{1}{2} \times \left( (0, 1) \cdot (0, 1) \right. \\ &\quad \left. + (-1, 1) \cdot (-1, 1) + (-1, -1) \cdot (-1, -1) + (1, -1) \cdot (1, -1) + (1, 0) \cdot (1, 0) \right) \\ &= \frac{1}{2} \times (1 + 2 + 2 + 2 + 1) = 4. \end{aligned}$$

As for the right hand side we have

$$3 \int_{B_1} \varphi_1 = 3 \times \text{aread of the side along } B_1 = 3 \left( \frac{1}{2} + \frac{1}{2} \right) = 3,$$

while

$$3 \int_{B_1} \varphi_2 = 0.$$

Summing up we have a trivial situation as follows:

$$\begin{bmatrix} 1 & 0 \\ 0 & 4 \end{bmatrix} \begin{bmatrix} U_1 \\ U_2 \end{bmatrix} = \begin{bmatrix} 3 \\ 0 \end{bmatrix}$$

Thus  $U(x) = 3\varphi_1(x)$  and actually, with this configuration, we have a trivial one-dimensional problem.

Alternatively: We may include  $N_3 = (1, 0)$  and  $N_4 = (0, 1)$  as new nodes and extend the triangles with Neumann outer boundaries to include  $k_2$  and  $k_4$ . This would lead to a  $4 \times 4$  system which we are not considering here!

2. Consider the one-dimensional heat equation:

$$\begin{cases} \dot{u} - u'' = f, & 0 < x < 1, & t > 0, \\ u(x, 0) = u_0(x), & 0 < x < 1, & \\ u(0, t) = u_x(1, t) = 0, & & t > 0. \end{cases}$$

a) Using appropriate variational forms show the stability estimates:

$$\|u(\cdot, t)\| \leq \|u_0\| + \int_0^t \|f(\cdot, s)\| ds, \text{ and } \|u_x(\cdot, t)\|^2 \leq \|u_0'\|^2 + \int_0^t \|f(\cdot, s)\|^2 ds.$$

b. Give physical meaning to the equation when  $f=9-u$ .

**Solution:** a) Multiply the equation by  $u$  and integrate over  $(0, 1)$  to get

$$\int_0^1 \dot{u}u dx - \int_0^1 u''u dx = \int_0^1 fu dx.$$

Integrating by parts and using the boundary conditions we have

$$\begin{aligned} \frac{1}{2} \frac{d}{dt} \int_0^1 u^2 dx + \int_0^1 (u')^2 dx - u'(1, t)u(1, t) + u'(0, t)u(0, t) &= \frac{1}{2} \frac{d}{dt} \|u\|^2 + \|u'\|^2 \\ &= \|u\| \frac{d}{dt} \|u\| + \|u'\|^2 = \int_0^1 fu dx \leq \|f\| \|u\|. \end{aligned}$$

Consequently

$$\frac{d}{dt} \|u\| \leq \|f\|,$$

which integrating over time:

$$\int_0^t \|f\| ds \geq \|u(\cdot, t)\| - \|u_0\|,$$

gives the first estimate in a).

To derive the second estimate we multiply the equation by  $\dot{u}$  and integrate over  $(0, 1)$  to obtain:

$$\begin{aligned} \int_0^1 (\dot{u})^2 dx - \int_0^1 u''\dot{u} dx &= \|\dot{u}\|^2 + \int_0^1 u'\dot{u}' dx - u'(1, t)\dot{u}(1, t) + u'(0, t)\dot{u}(0, t) \\ &= \|\dot{u}\|^2 + \frac{d}{dt} \|u'\|^2 = \int_0^1 f\dot{u} dx \leq \|f\| \|\dot{u}\| \leq \frac{1}{2} (\|f\|^2 + \|\dot{u}\|^2). \end{aligned}$$

Thus

$$\frac{1}{2} \|\dot{u}\|^2 + \frac{1}{2} \frac{d}{dt} \|u'\|^2 \leq \frac{1}{2} \|f\|^2,$$

and hence

$$\frac{d}{dt} \|u'\|^2 \leq \|f\|^2,$$

which, as in the first estimate, integrating over time:  $\int_0^t ds$  gives the second estimate.

b) Heat conduction with

$$\begin{aligned} u(x, t) &= && \text{temperature at } x \text{ at time } t. \\ u(x, 0) &= u_0(x), && \text{the initial temperature at } t = 0. \\ u(0, t) &= 0, && \text{fixed temperature at } x = 0. \\ u'(1, t) &= 0, && \text{isolated at } x = 1, \text{ (no heat flux).} \\ f &= 9 - u, && \text{heat source, in this case a control system to force } u \rightarrow 9. \end{aligned}$$

3. Let  $a$  be a positive constant. Consider the boundary value problem (BVP)

$$-u''(x) + au(x) = f(x), \quad 0 < x < 1, \quad u(0) = u(1) = 0.$$

Formulate the corresponding variational formulation (VF), and the minimization problem (MP) and prove that  $(BVP) \iff (VF) \iff (MP)$ .

**Solution:** See lecture notes, Chapter 8.

4. Prove an a priori and an a posteriori error estimate (in the  $H^1$ -norm:  $\|u\|_{H^1}^2 = \|u'\|^2 + \|u\|^2$ ) for a finite element method for the problem

$$-u'' + 2xu' + 2u = f, \quad 0 < x < 1, \quad u(0) = u(1) = 0.$$

**Solution:** We multiply the differential equation by a test function  $v \in H_0^1(I)$ ,  $I = (0, 1)$  and integrate over  $I$ . Using partial integration and the boundary conditions we get the following *variational problem*: Find  $u \in H_0^1(I)$  such that

$$(5) \quad \int_I (u'v' + 2xu'v + 2uv) = \int_I fv, \quad \forall v \in H_0^1(I).$$

A *Finite Element Method* with  $cG(1)$  reads as follows: Find  $U \in V_h^0$  such that

$$(6) \quad \int_I (U'v' + 2xU'v + 2Uv) = \int_I fv, \quad \forall v \in V_h^0 \subset H_0^1(I),$$

where

$$V_h^0 = \{v : v \text{ is piecewise linear and continuous in a partition of } I, v(0) = v(1) = 0\}.$$

Now let  $e = u - U$ , then (1)-(2) gives that

$$(7) \quad \int_I (e'v' + 2xe'v + 2ev) = 0, \quad \forall v \in V_h^0.$$

*A posteriori error estimate:* We note that using  $e(0) = e(1) = 0$ , we get

$$(8) \quad \int_I 2xe'e = \int_I x \frac{d}{dx}(e^2) = (xe^2)|_0^1 - \int_I e^2 = - \int_I e^2,$$

so that

$$\begin{aligned}
\|e\|_{H^1}^2 &= \int_I (e' e' + ee) = \int_I (e' e' + 2xe' e + 2ee) \\
&= \int_I ((u - U)' e' + 2x(u - U)' e + 2(u - U)e) = \{v = e \text{ in(1)}\} \\
(9) \quad &= \int_I f e - \int_I (U' e' + 2xU' e + 2Ue) = \{v = \pi_h e \text{ in(2)}\} \\
&= \int_I f(e - \pi_h e) - \int_I (U'(e - \pi_h e)' + 2xU'(e - \pi_h e) + 2U(e - \pi_h e)) \\
&= \{P.I. \text{ on each subinterval}\} = \int_I \mathcal{R}(U)(e - \pi_h e),
\end{aligned}$$

where  $\mathcal{R}(U) := f + U'' - 2xU' - 2U = f - 2xU' - 2U$ , (for approximation with piecewise linears,  $U \equiv 0$ , on each subinterval). Thus (5) implies that

$$\begin{aligned}
\|e\|_{H^1}^2 &\leq \|h\mathcal{R}(U)\| \|h^{-1}(e - \pi_h e)\| \\
&\leq C_i \|h\mathcal{R}(U)\| \|e'\| \leq C_i \|h\mathcal{R}(U)\| \|e\|_{H^1},
\end{aligned}$$

where  $C_i$  is an interpolation constant, and hence we have with  $\|\cdot\| = \|\cdot\|_{L_2(I)}$  that

$$\|e\|_{H^1} \leq C_i \|h\mathcal{R}(U)\|.$$

*A priori error estimate:* We use (4) and write

$$\begin{aligned}
\|e\|_{H^1}^2 &= \int_I (e' e' + ee) = \int_I (e' e' + 2xe' e + 2ee) \\
&= \int_I (e'(u - U)' + 2xe'(u - U) + 2e(u - U)) = \{v = U - \pi_h u \text{ in(3)}\} \\
&= \int_I (e'(u - \pi_h u)' + 2xe'(u - \pi_h u) + 2e(u - \pi_h u)) \\
&\leq \|(u - \pi_h u)'\| \|e'\| + 2\|u - \pi_h u\| \|e'\| + 2\|u - \pi_h u\| \|e\| \\
&\leq \{ \|(u - \pi_h u)'\| + 4\|u - \pi_h u\| \} \|e\|_{H^1} \\
&\leq C_i \{ \|hu''\| + \|h^2 u''\| \} \|e\|_{H^1},
\end{aligned}$$

this gives that

$$\|e\|_{H^1} \leq C_i \{ \|hu''\| + \|h^2 u''\| \},$$

which is the a priori error estimate.

**5.** Consider the boundary value problem

$$-div(\varepsilon \nabla u + \beta u) = f, \text{ in } \Omega, \quad u = 0, \text{ on } \partial\Omega,$$

where  $\Omega$  is a bounded polygonal domain in  $\mathbb{R}^2$ ,  $\varepsilon > 0$  is a constant,  $\beta = (\beta_1(x), \beta_2(x))$ , and  $f = f(x)$ . Give the conditions (based on Lax-Milgrams theorem) for existence of a unique solution for this problem. Derive stability estimates for  $u$  in terms of  $\|f\|_{L_2(\Omega)}$ ,  $\varepsilon$  and  $diam(\Omega)$ .

**Solution:** Consider

$$(10) \quad -div(\varepsilon \nabla u + \beta u) = f, \text{ in } \Omega, \quad u = 0 \text{ on } \Gamma = \partial\Omega.$$

a) Multiply the equation (6) by  $v \in H_0^1(\Omega)$  and integrate over  $\Omega$  to obtain the Green's formula

$$-\int_{\Omega} \operatorname{div}(\varepsilon \nabla u + \beta u) v \, dx = \int_{\Omega} (\varepsilon \nabla u + \beta u) \cdot \nabla v \, dx = \int_{\Omega} f v \, dx.$$

Variational formulation for (6) is as follows: Find  $u \in H_0^1(\Omega)$  such that

$$(11) \quad a(u, v) = L(v), \quad \forall v \in H_0^1(\Omega),$$

where

$$a(u, v) = \int_{\Omega} (\varepsilon \nabla u + \beta u) \cdot \nabla v \, dx,$$

and

$$L(v) = \int_{\Omega} f v \, dx.$$

According to the Lax-Milgram's theorem, for a unique solution for (7) we need to verify that the following relations are valid:

i)

$$|a(v, w)| \leq \gamma \|u\|_{H^1(\Omega)} \|w\|_{H^1(\Omega)}, \quad \forall v, w \in H_0^1(\Omega),$$

ii)

$$a(v, v) \geq \alpha \|v\|_{H^1(\Omega)}^2, \quad \forall v \in H_0^1(\Omega),$$

iii)

$$|L(v)| \leq \Lambda \|v\|_{H^1(\Omega)}, \quad \forall v \in H_0^1(\Omega),$$

for some  $\gamma, \alpha, \Lambda > 0$ .

Now since

$$|L(v)| = \left| \int_{\Omega} f v \, dx \right| \leq \|f\|_{L_2(\Omega)} \|v\|_{L_2(\Omega)} \leq \|f\|_{L_2(\Omega)} \|v\|_{H^1(\Omega)},$$

thus iii) follows with  $\Lambda = \|f\|_{L_2(\Omega)}$ .

Further we have that

$$\begin{aligned} |a(v, w)| &\leq \int_{\Omega} |\varepsilon \nabla v + \beta v| |\nabla w| \, dx \leq \int_{\Omega} (\varepsilon |\nabla v| + |\beta| |v|) |\nabla w| \, dx \\ &\leq \left( \int_{\Omega} (\varepsilon |\nabla v| + |\beta| |v|)^2 \, dx \right)^{1/2} \left( \int_{\Omega} |\nabla w|^2 \, dx \right)^{1/2} \\ &\leq \sqrt{2} \max(\varepsilon, \|\beta\|_{\infty}) \left( \int_{\Omega} (|\nabla v|^2 + v^2) \, dx \right)^{1/2} \|w\|_{H^1(\Omega)} \\ &= \gamma \|v\|_{H^1(\Omega)} \|w\|_{H^1(\Omega)}, \end{aligned}$$

which, with  $\gamma = \sqrt{2} \max(\varepsilon, \|\beta\|_{\infty})$ , gives i).

Finally, if  $\operatorname{div} \beta \leq 0$ , then

$$\begin{aligned} a(v, v) &= \int_{\Omega} \left( \varepsilon |\nabla v|^2 + (\beta \cdot \nabla v) v \right) \, dx = \int_{\Omega} \left( \varepsilon |\nabla v|^2 + (\beta_1 \frac{\partial v}{\partial x_1} + \beta_2 \frac{\partial v}{\partial x_2}) v \right) \, dx \\ &= \int_{\Omega} \left( \varepsilon |\nabla v|^2 + \frac{1}{2} (\beta_1 \frac{\partial}{\partial x_1} (v)^2 + \beta_2 \frac{\partial}{\partial x_2} (v)^2) \right) \, dx = \text{Green's formula} \\ &= \int_{\Omega} \left( \varepsilon |\nabla v|^2 - \frac{1}{2} (\operatorname{div} \beta) v^2 \right) \, dx \geq \int_{\Omega} \varepsilon |\nabla v|^2 \, dx. \end{aligned}$$

Now by the Poincare's inequality

$$\int_{\Omega} |\nabla v|^2 \, dx \geq C \int_{\Omega} (|\nabla v|^2 + v^2) \, dx = C \|v\|_{H^1(\Omega)}^2,$$

for some constant  $C = C(\text{diam}(\Omega))$ , we have

$$a(v, v) \geq \alpha \|v\|_{H^1(\Omega)}^2, \quad \text{with } \alpha = C\varepsilon,$$

thus ii) is valid under the *condition that*  $\text{div}\beta \leq 0$ .

From ii), (7) (with  $v = u$ ) and iii) we get that

$$\alpha \|u\|_{H^1(\Omega)}^2 \leq a(u, u) = L(u) \leq \Lambda \|u\|_{H^1(\Omega)},$$

which gives the *stability estimate*

$$\|u\|_{H^1(\Omega)} \leq \frac{\Lambda}{\alpha},$$

with  $\Lambda = \|f\|_{L_2(\Omega)}$  and  $\alpha = C\varepsilon$  defined above.

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