

# FEM12 - lecture 4

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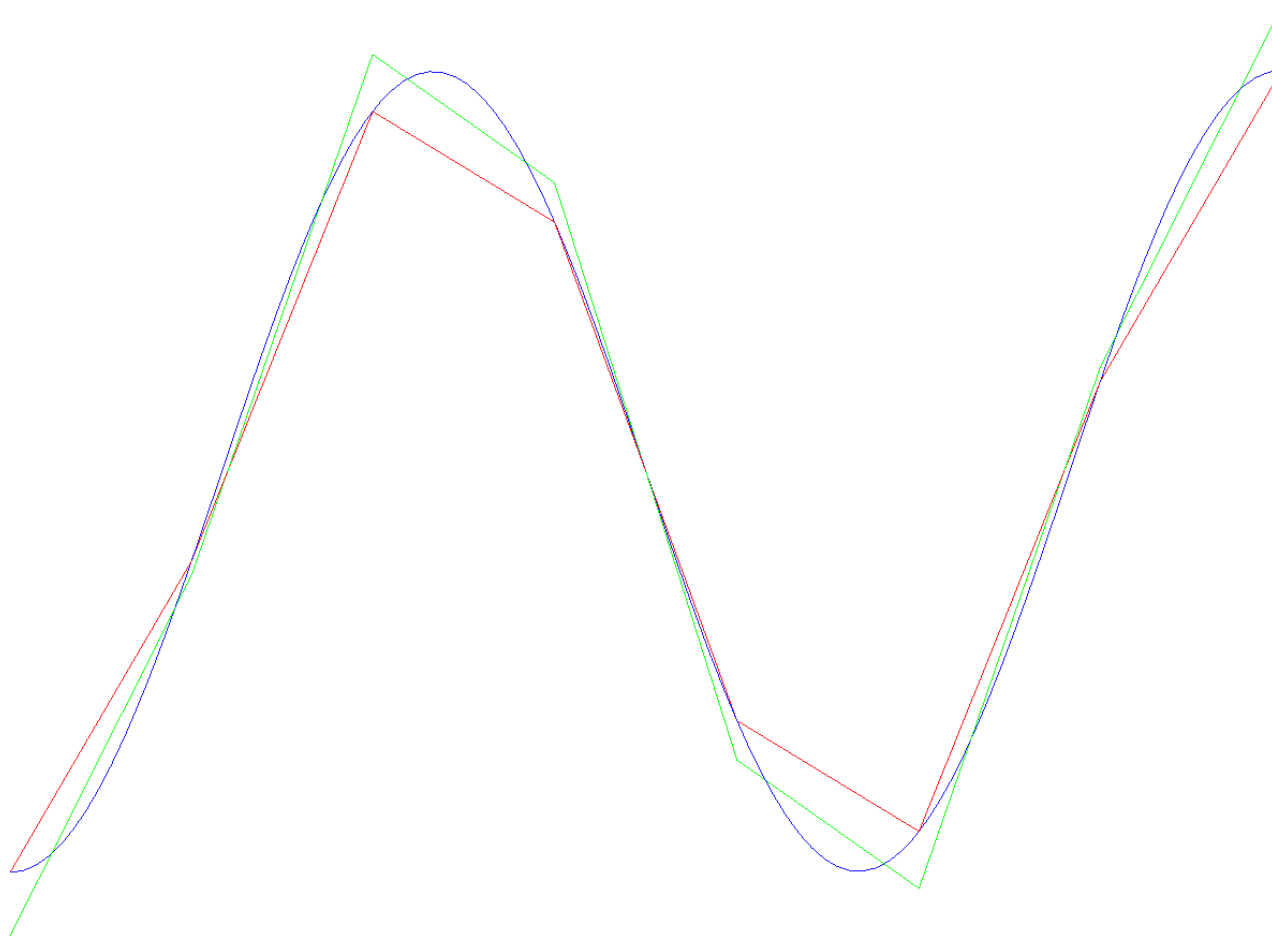
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# Outline

- Repetition: L2-projection
- Error estimation: a priori, a posteriori
- Poisson in 2D, integration by parts, BCs

# L2-projection



# Error estimation

Equation:  $R(u) = 0$ .

Compute solution  $U$ , exact solution  $u$ .

Error:  $e = u - U$

$u$  is unknown, what can we say about the computational error  $e$ ?

In science/engineering we want to guarantee our solution is acceptable, give a tolerance on error:

$$\|e\| < TOL$$

We also want to compute  $U$  with as little computational power as possible.

We will see how a posteriori error estimates/bounds can make this possible.

# Error estimation

Examples for specific equations:

A priori example (order of convergence):

$$\|e\|_E \leq C \|hu''\|$$

A posteriori example (actual computable bound on error):

$$\|e\|_E \leq C \|hR(U)\|$$

# Error estimation: example

We want to build a cooking pan. Assume the temperature of a hot stove is 400C.

Model the cooking pan with heat eq. (Poisson) and compute an approximate solution. The temperature at the handle of the cooking pan in our computation is 70C (not dangerous). Assume second degree burns start at 80C.

What is the error of the solution?

If the error is 10%, then at most the temperature can be 77C.

If the error is 50%, then at most the temperature can be 105C.

We would like to guarantee that the computational error is

smaller than 10%!:

$$\frac{\|e\|}{\|U\|} < 0.1 \quad (\|e\| < TOL)$$

# Function space

Remember: A vector space can be constructed with set of polynomials on domain  $(a, b)$  as basis vectors, where function addition and scalar multiplication satisfy the requirements for a vector space.

We can also define an inner product space with the  $L_2$  inner product defined as:

$$(f, g)_{L_2} = \int_{\Omega} f(x)g(x)dx$$

# Lagrange (nodal) Basis

We will use the Lagrange basis:  $\{\lambda_i\}_{i=0}^q$  associated to the distinct points  $\xi_0 < \xi_1 < \dots < \xi_q$  in  $(a, b)$ , determined by the requirement that  $\lambda_i(\xi_j) = 1$  if  $i = j$  and 0 otherwise.

$$\lambda_i(x) = \prod_{j \neq i} \frac{x - \xi_j}{\xi_i - \xi_j}$$

$$\lambda_0(x) = (x - \xi_1)(\xi_0 - \xi_1)$$

$$\lambda_1(x) = (x - \xi_0)/(\xi_1 - \xi_0)$$



# Polynomial interpolation

We assume that  $f$  is continuous on  $[a, b]$  and choose distinct interpolation nodes  $a \leq \xi_0 < \xi_1 < \dots < \xi_q \leq b$  and define a piecewise polynomial interpolant  $\pi_q f \in \mathcal{V}_h$ , that interpolates  $f(x)$  at the nodes  $\{\xi_i\}$  by requiring that  $\pi_q f$  take the same values as  $f$  at the nodes, i.e.  $\pi_q f(\xi_i) = f(\xi_i)$  for  $i = 0, \dots, q$ . Using the Lagrange basis corresponding to the  $\xi_i$ , we can express  $\pi_q f$  using “Lagrange’s formula”:

$$\pi_q f(x) = f(\xi_0)\lambda_0(x) + f(\xi_1)\lambda_1(x) + \dots + f(\xi_q)\lambda_q(x) \quad \text{for } a \leq x \leq b$$

# Interpolation error

Mean value theorem/Taylor:

$$f(x) = f(\xi_0) + f'(\eta)(x - \xi_0) = \pi_0 f(x) + f'(\eta)(x - \xi_0)$$

for some  $\eta$  between  $\xi_0$  and  $x$ , so that

$$|f(x) - \pi_0 f(x)| \leq |x - \xi_0| \max_{[a,b]} |f'| \quad \text{for all } a \leq x \leq b$$

Or:

$$\|f - \pi_0 f\|_{L_2(a,b)} \leq C_i(b - a) \|f'\|_{L_2(a,b)}$$

# $L_2$ projection

We seek a polynomial approximate solution  $U \in V_h$  to the equation:

$$R(u) = u - f = 0, \quad x \in (a, b)$$

where  $f$  in general is not piecewise polynomial, i.e.  $f \notin V_h$ . This means  $R(U)$  can in general not be zero. The best we can hope for is that  $R(U)$  is orthogonal to  $V_h$  which means solving the equation:

$$(R(U), v)_{L_2} = (U - f, v)_{L_2} = 0, \quad x \in \Omega, \quad \forall v \in P^q(a, b)$$

# Error estimate

The orthogonality condition means the computed  $L_2$  projection  $U$  is the best possible approximation of  $f$  in  $V_h$  in the  $L_2$  norm:

$$\begin{aligned}\|f - U\|^2 &= (f - U, f - U) = \\ &= (f - U, f - v) + (f - U, v - U) = \\ &= [v - U \in V_h] = (f - U, f - v) \leq \|f - U\| \|f - v\| \\ &\Rightarrow \\ \|f - U\| &\leq \|f - v\|, \quad \forall v \in V_h\end{aligned}$$

# Error estimate

Since  $\pi f \in V_h$ , we can choose  $v = \pi f$  which gives:

$$\|f - v\|_{L_2(a,b)} = \|f - \pi f\|_{L_2(a,b)} \leq C_i(b - a)\|f'\|_{L_2(a,b)}$$

i.e. we can use an interpolation error estimate since it bounds the projection error.

# Energy norm

For a linear PDE we observe:

$$a(u, v) - L(v) = 0$$

$$a(U, v) - L(v) = 0 \Rightarrow$$

$$a(u - U, v) = 0, \quad \forall v \in V_h$$

We can define the “energy” inner product/norm:

$$(f, g)_E = a(f, g) \Rightarrow \|f\|_E = \sqrt{a(f, f)}$$

For the equation:

$$R(u) = u'' - f = 0, \quad x \in (0, 1) \Rightarrow$$

$$(f, g)_E = \int_0^1 f' g' dx \Rightarrow \|f\|_E = \sqrt{\int_0^1 (f')^2 dx}$$

# A priori estimation

(Recall estimate for L2 projection)

$$\|e\|_E^2 = (e, e)_E = (u - U, u - U)_E = \dots$$

# A priori estimation

(Recall estimate for L2 projection)

$$\begin{aligned}\|e\|_E^2 &= (e, e)_E = (u - U, u - U)_E = \\ &= (u - U, u - U)_E + (u - U, v - v)_E = \\ &= (u - U, u - v)_E + (u - U, v - U)_E = \\ &= (u - U, u - v)_E \leq \|e\|_E \|u - v\|_E \Rightarrow \\ \|e\|_E &\leq \|u - v\|_E, \quad \forall v \in V_h\end{aligned}$$

This proves that there is no better approximation than  $U$  in  $V_h$  in the energy norm.



# A priori estimation

Continuing, remembering that interpolant  $\pi u \in V_h$  and using interpolation estimate  $\|u - \pi u\|_E \leq Ch\|u'\|_E$ :

$$\|e\|_E \leq \|u - v\|_E, \quad \forall v \in V_h \Rightarrow$$

$$\|e\|_E \leq \|u - \pi u\|_E \leq Ch\|u'\|_E$$

Which means that the energy norm (in this case derivative) of the error converges to zero with first order rate.

# A posteriori estimation

Want to extract  $R(U)$  from expression with  $e$ .

Observe that  $Ae = -R(U)$ .

Galerkin orthogonality:  $\int_0^1 U'v' - fvd x = 0, \quad \forall v \in V_h$

Note that  $\pi e \in V_h$

$$\begin{aligned}\|e\|_E^2 &= \int_0^1 e'e' dx = \int_0^1 (U'e' - fe) dx = \\ &\int_0^1 (U'e' - fe - (U'\pi e' - f\pi e)) dx =\end{aligned}$$

# A posteriori estimation

Continuing, using integration by parts on each cell/interval  $K_i = [a_i, b_i]$ ,  $0 < a_i < b_i < 1$  and that the interpolation error is zero in the nodes:  $(e - \pi e)(x_j) = 0$ .

$$\sum_{i=1}^M \int_{a_i}^{b_i} U'(e - \pi e)' dx - \int_0^1 f(e - \pi e) dx =$$
$$\sum_{i=1}^M \int_{a_i}^{b_i} (-U''(e - \pi e) - f(e - \pi e)) dx + [U'(e - \pi e)]_{a_i}^{b_i} =$$

Clean up, defining discontinuous  $\hat{R}(U) = -U'' - f$

$$\|e\|_E^2 = \int_0^1 \hat{R}(U)(e - \pi e) dx$$

# A posteriori estimation

Continuing using Cauchy-Schwartz and interpolation estimate

$$\|e - \pi e\| \leq Ch\|e'\| = Ch\|e\|_E$$

$$\|e\|_E^2 = \int_0^1 \hat{R}(U)(e - \pi e) dx \leq \|\hat{R}(U)\| \|e - \pi e\| \leq \|\hat{R}(U)\| Ch\|e\|_E$$

Which gives the final estimate/bound:

$$\|e\|_E \leq C\|h\hat{R}(U)\|$$

Note that the right hand side is computable given a solution  $U$ .

# Integration by parts in 2D

$$\int_{\Omega} D_{x_i} v w dx = \int_{\Gamma} v w n_i ds - \int_{\Omega} v D_{x_i} w dx, \quad i = 1, 2, \dots, d$$

$$\int_a^b D_x v w dx = [v w]_a^b - \int_a^b v D_x w dx \quad (1)$$

$$\int_{\Omega} D_{x_i} v D_{x_i} w dx = \int_{\Gamma} v D_{x_i} w n_i ds - \int_{\Omega} v D_{x_i} D_{x_i} w dx \quad (2)$$

$$\int_{\Omega} \nabla v \cdot \nabla w dx = \int_{\Gamma} v (\nabla w \cdot n) ds - \int_{\Omega} v \Delta w dx \quad (3)$$

# Poisson in 2D

$$-\Delta u - f = 0, \quad x \in \Omega \quad \Rightarrow$$

$$(-\Delta u - f, v) = 0, \quad x \in \Omega, \quad \forall v \in V \quad \Rightarrow$$

$$-(\nabla u, \nabla v) + \int_{\Gamma} v(\nabla u \cdot n) ds - (f, v) = 0, \quad x \in \Omega, \quad \forall v \in V$$

$$u = 0, \quad x \in \Gamma$$