



ROYAL INSTITUTE
OF TECHNOLOGY

Strong Supervision from Weak Annotation: Interactive Training of Deformable Part Models

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Methods by level of supervision

- simple models, weak annotations
 - least effort, potentially fast learning, not best results
- complicated models, weak annotation
 - state-of-the-art performance (multiple instance learning, latent parts, latent structural SVM)
 - non-convex optimization
 - slow training
 - Hard to pinpoint error source (optimization error, inappropriate model or feature space, insufficient training data)

Methods by level of supervision

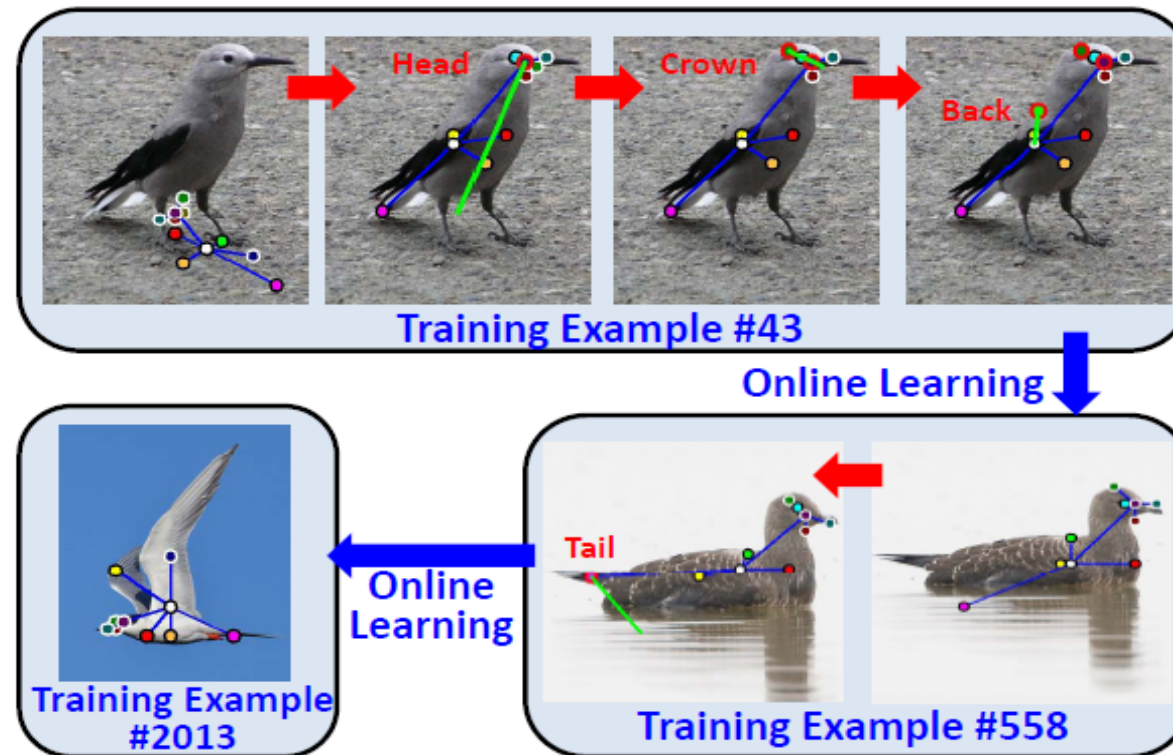
- Strong annotation
 - Very time consuming
 - Easy learning task (possible convex optimization)
 - Generalization guarantee
 - Sensitive to quality and style of annotation

Question: Is it possible to have strong supervision properties with weak annotation computational efficiency?

Yes! Interactive Labelling and Online Learning

- 1- Model part structures with structured models
- 2- Bring up a new image,
 - predict the part locations with current model
 - Correct the wrong locations
- 3-Update the learned model and go to 2

Interactive Labelling + Online Learning

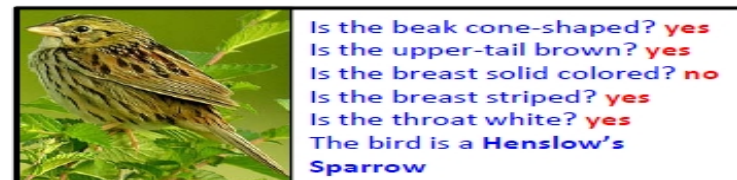
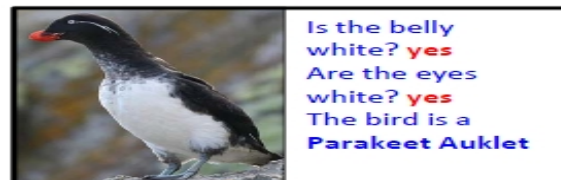
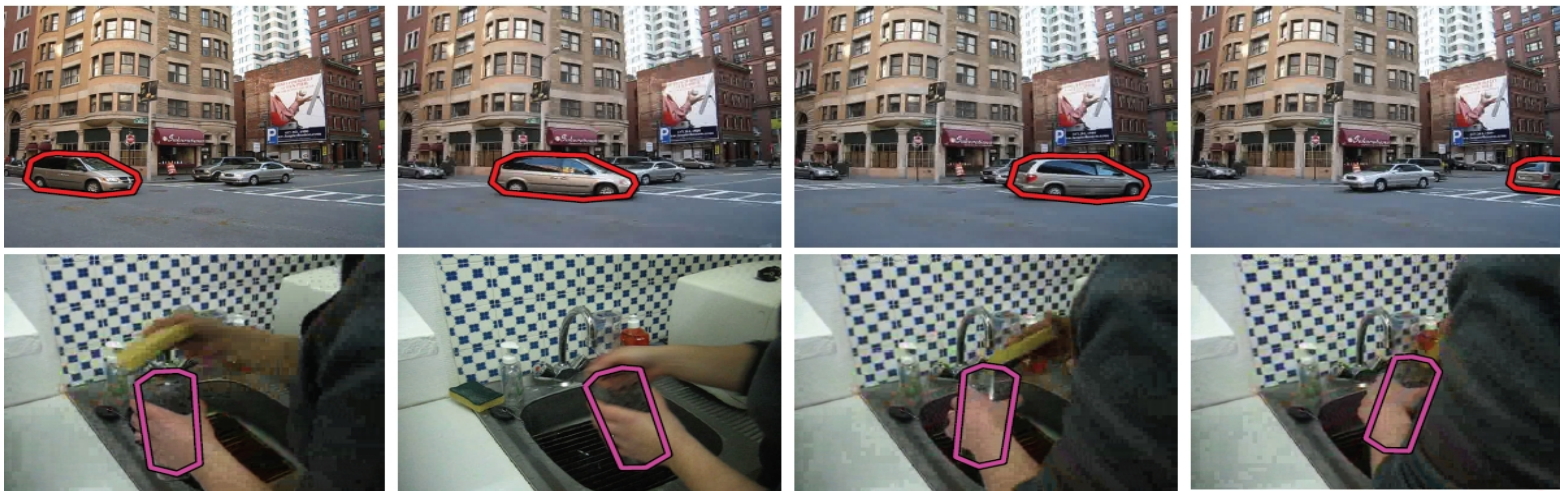
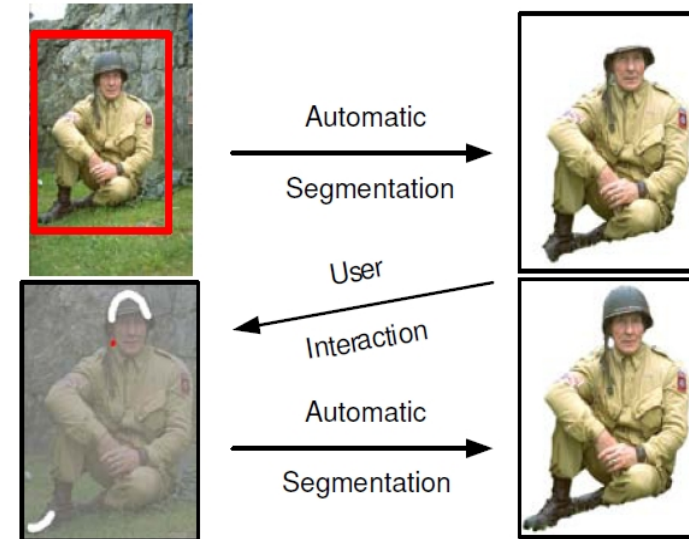


Interactive Labelling + Online Learning

- Interactive Labelling
 - Real time detection
 - Easy update
 - Tree-structured deformable parts model with dynamic programming is a good choice!
- Online Learning
 - Fast model updating
 - Convex optimization
 - Stochastic gradient descent

Related works

- Interactive labelling
 - Grab cut (Segmentation)
 - Label me video
 - Visipedia (attributes)



Related works

- Active learning
 - Intelligent computer decide which image to annotate
 - More savings than interactive labeling
 - In comparison to strong supervision
 - Higher computational complexity
 - Fewer theoretical quarantees



Most regions are understood, but this region is unclear.



This looks expensive to annotate, and it does not seem informative.

...

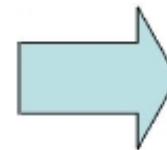


This looks expensive to annotate, but it seems very informative.



This looks easy to annotate, but its content is already understood.

...



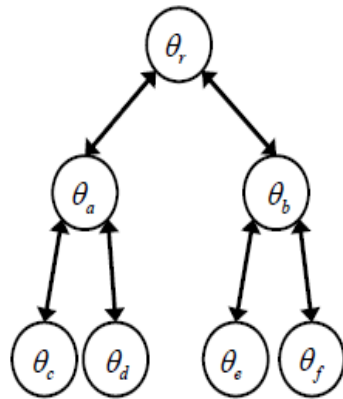
Label the object(s) in this region



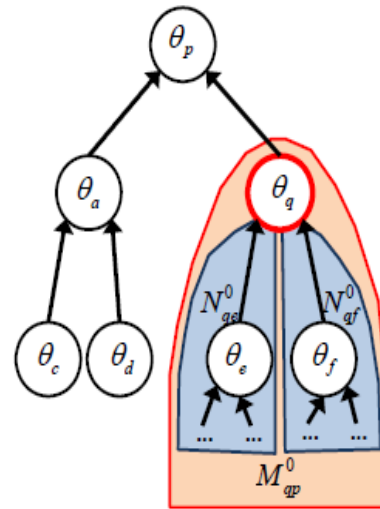
Completely segment and label this image.

Model and Interactive UI

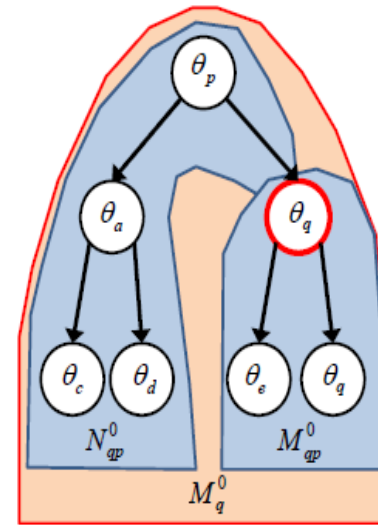
$$s(\Theta; x) = \sum_{p \in V} \psi_p(\theta_p; x) + \sum_{(p,q) \in E} \lambda_{pq}(\theta_p, \theta_q)$$



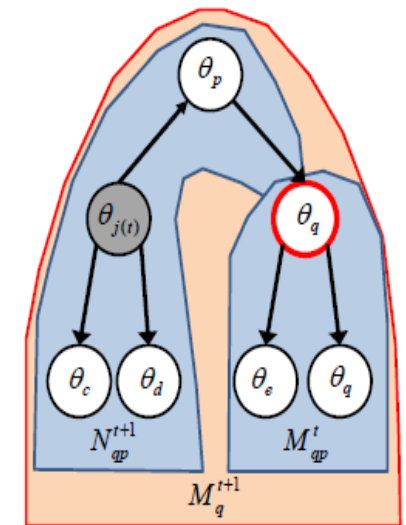
(a) Hierarchical Part Model



(b) Bottom-Up Preprocessing



(c) Top-Down Preprocessing



(d) Propagate User Response

Learning framework

- Strong Convex formulation

$$F_n(\mathbf{w}) = \frac{\lambda}{2} \|\mathbf{w}\|^2 + \frac{1}{n} \sum_{i=1}^n \ell_i(\mathbf{w}) \quad (16)$$

$$\ell_i(\mathbf{w}) = \max_y (\mathbf{w} \cdot \Phi(x_i, y) - \mathbf{w} \cdot \Phi(x_i, y_i) + \Delta(y_i, y))$$

- Gradient computable
- by one inference

$$\bar{y}_i = \max_y (\mathbf{w} \cdot \Phi(x_i, y) + \Delta(y_i, y))$$

$$\nabla \ell_i = \Phi(x_i, \bar{y}_i) - \Phi(x_i, y_i)$$

- Stochastic gradient descent
- Process an image at each step
 - Pegasus!

Theoretical properties

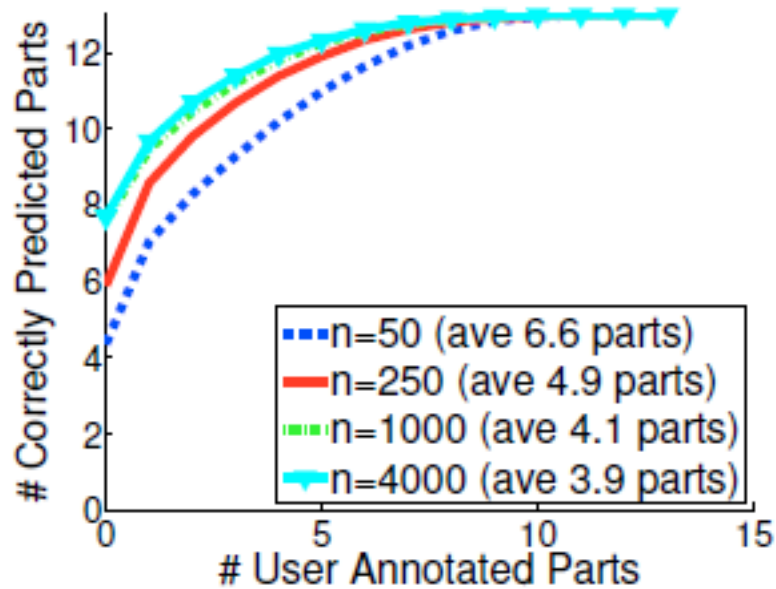
- Pegasos
 - Faster convergence rate than linear SVM
 - Performance guarantee with the number of iterations
 - Training time does not increase with increasing number of images (for a specific performance)
 - Slower steps than linear svm
 - Inference at each step
- Interactive labelling
 - Loss function is defined as the number of misplaced part
 - Number of annotation is bounded!

Some results...

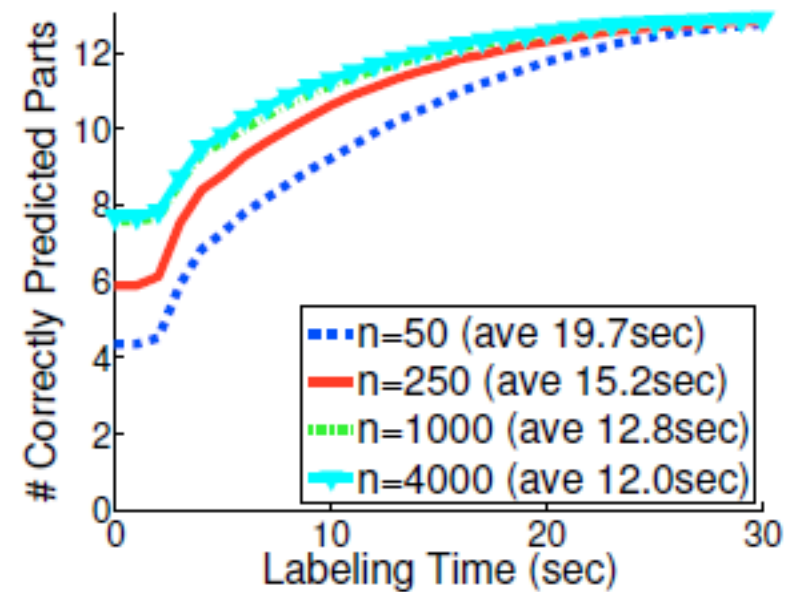


Tables

- 50 images:
 - 6.6 / 13 correction.
 - 19.7 seconds
- 4000 images:
 - 3.9 / 13 correction
 - 12 seconds



(a) Part Prediction By # Corrections



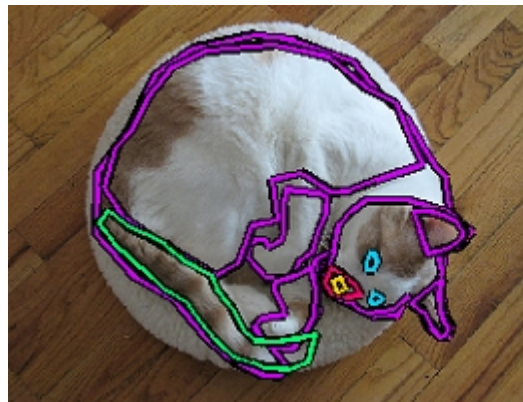
(b) Part Prediction By Time

Conclusion

- Framework for large scale annotation
- Simultaneous learning of structured models
- Nice theoretical properties, seen in practice

Cross-category Object Recognition (CORE)

- University of Illinois at Urbana-Champaign
- more detailed models and for exploring cross-category generalization in object recognition



Taxonomy:
Animal
Four legged
Mammal
Cat

Function:
Can Bite
Can Jump
Can Run
Carnivore

Pose:
Front Visible
Right Visible
Lying

CORE – Data overview

- Images from ImageNet, thus coming with object hierarchy
- Binary attributes
 - Pose
 - Surrounding context
 - Viewpoint
 - Etc.




Property	Value	Unsure
Objects Top	<input type="radio"/> Not Visible <input type="radio"/> Visible	<input type="checkbox"/>
Objects Bottom	<input type="radio"/> Not Visible <input type="radio"/> Visible	<input type="checkbox"/>
Objects Front	<input type="radio"/> Not Visible <input type="radio"/> Visible	<input type="checkbox"/>
Objects Back	<input type="radio"/> Not Visible <input type="radio"/> Visible	<input type="checkbox"/>
Objects Left Side	<input type="radio"/> Not Visible <input type="radio"/> Visible	<input type="checkbox"/>
Objects Right Side	<input type="radio"/> Not Visible <input type="radio"/> Visible	<input type="checkbox"/>
Context	<input type="radio"/> On Land <input type="radio"/> Flying	<input type="checkbox"/>
Another object in this image	<input type="checkbox"/> Visible	<input type="checkbox"/>
Visibility	<input type="radio"/> Fully Visible <input type="radio"/> Partially Visible	<input type="checkbox"/>
Unusual	<input type="radio"/> Typical Example <input type="radio"/> Something Unusual <input type="radio"/> Too Small	<input type="checkbox"/>

Submit Annotation

(a) Binary Attributes

CORE – data overview

- Polygon labels
 - Objects
 - Pre-defined parts of a category

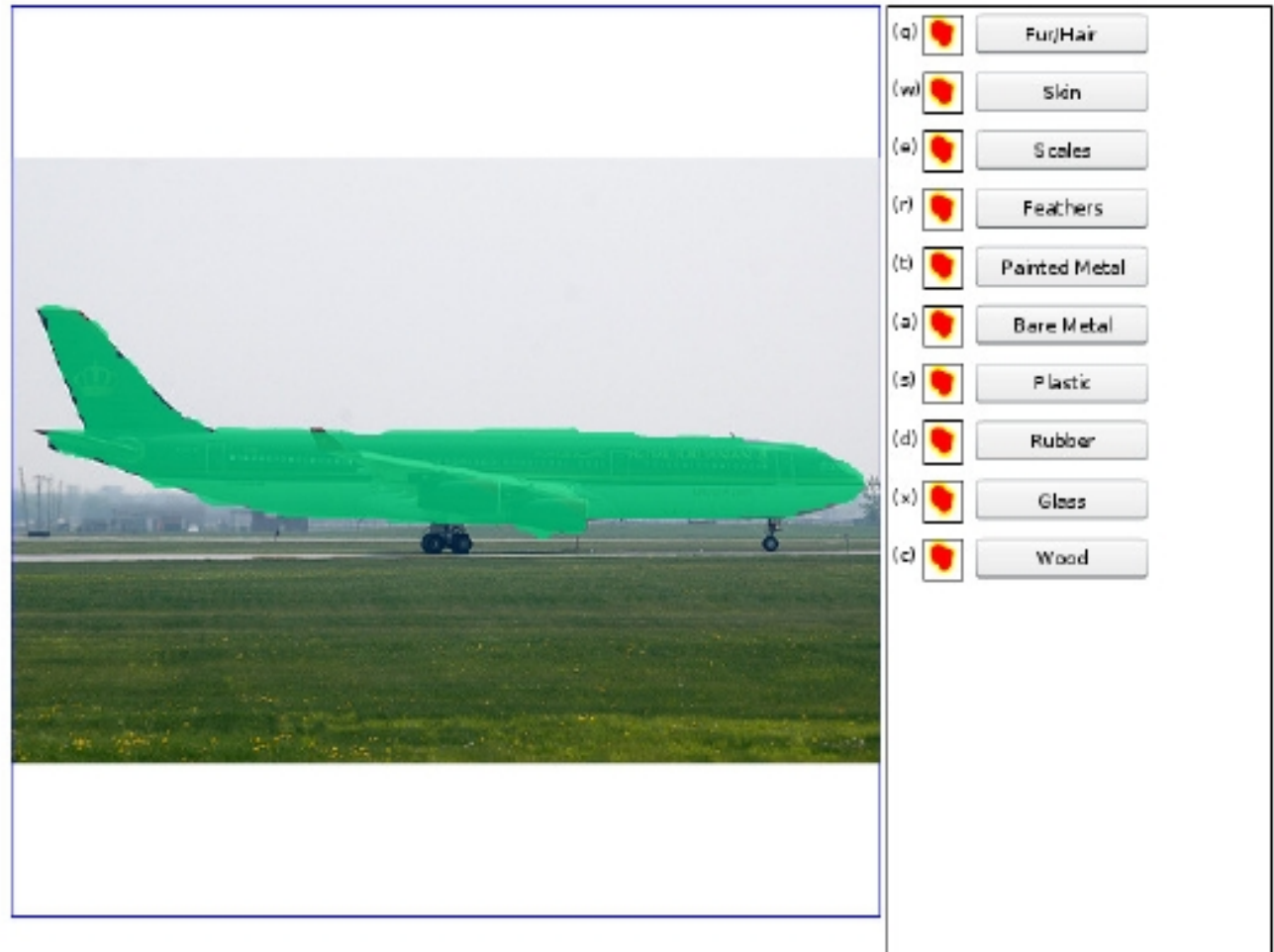


The screenshot displays a street scene with a person riding a motorbike. Two white labels with the word "wheel" are placed on the front and rear wheels of the motorbike. To the right of the image is a control panel with four buttons, each featuring a polygon icon and a label: (q) wheel, (w) handlebar, (e) fender, and (r) container. Below the image is a "Submit results" button.

(b) Polygons

CORE – data overview

- Segmentation mask
- Materials



Quality Measures

- Way of collecting images
- Which attributes
 - Easily annotatable
 - Unsure button
- Quality assurance methods...