

# Fast Neighbor Joining

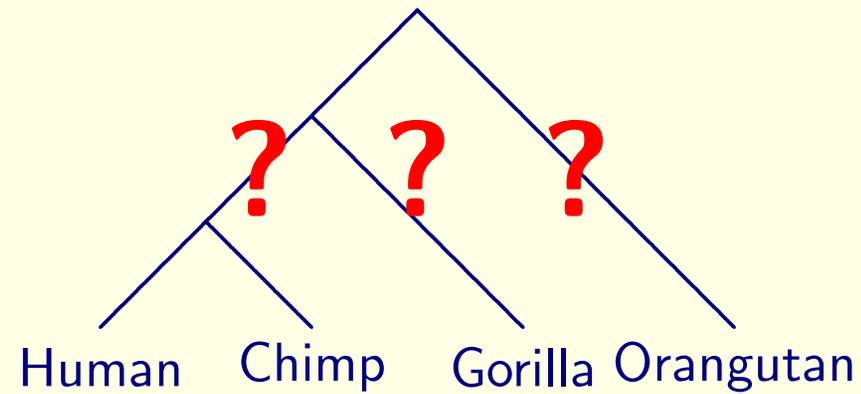
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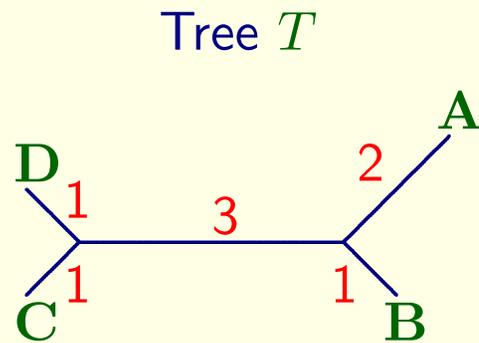
Sweden

# Evolutionary History



- Distance methods
- Parsimony methods
- ML methods

# Tree Reconstruction Problem



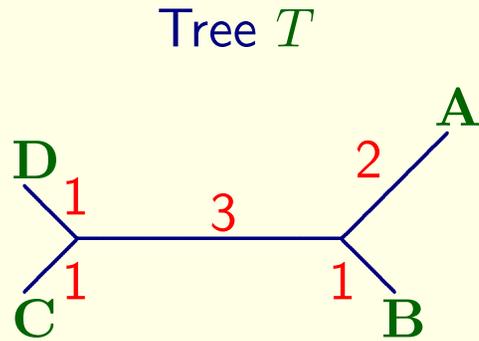
Additive Metric

$$D_T(x, y) = \sum_{e \in \text{path}(x, y)} l(e)$$

$D_T =$

	A	B	C	D
A	0	3	6	6
B		0	5	5
C			0	2
D				0

# Tree Reconstruction Problem



Additive Metric

$$D_T(x, y) = \sum_{e \in \text{path}(x, y)} l(e)$$

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	A	B	C	D
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C			0	2
D				0

**Input** A non-additive metric  $D$ .

**Output** Tree  $S$ , without edge lengths, that is **closest** to  $D$ ,

$$\min_{D_S} |D_S - D|_{\infty}.$$

$$D =$$

	A	B	C	D
A	0	3	5	6
B		0	4	5
C			0	1
D				0

# The Mighty Error Correcting Code

1. G\*d is sending us the message  $T$ .

2. He has written down  $D_T$ .

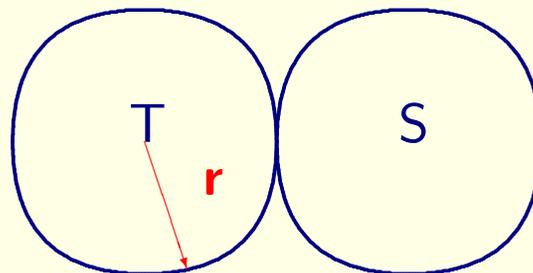
3.  $D_T$  changes at most  $r$ .

$$D_T \rightsquigarrow D \implies |D_T - D|_\infty < r$$

4. Find the closest tree  $S$ .

$$D_S = \operatorname{argmin}_{D_S} |D_S - D|_\infty$$

**How big can  $r$  be such that  $T = S$  ?**



## Optimal Reconstruction Radius [Atteson]

$\mu(T)$  = shortest edge length in  $T$ .

1. If  $r \leq \frac{\mu(T)}{2}$  then  $S = T$  ( $D$  is nearly additive).
2. If  $r > \frac{\mu(T)}{2}$  then it can be that  $S \neq T$ .

No algorithm can have reconstruction radius  $> \frac{\mu(T)}{2}$ .

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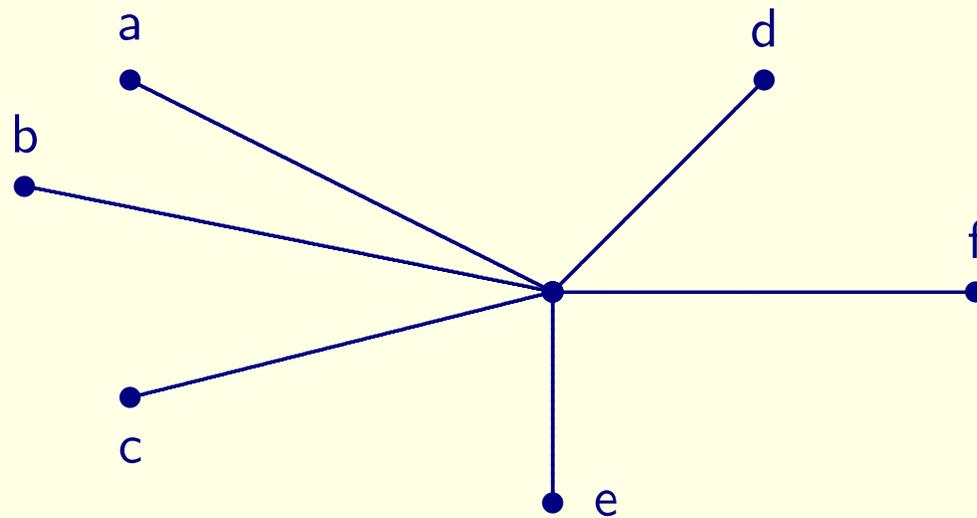
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	Time	Radius	Our contribution
<b>NJ</b>	$O(n^3)$	$\frac{\mu(T)}{2}$	simplify the proof
<b>FNJ</b>	$O(n^2)$	$\frac{\mu(T)}{2}$	new fast algorithm

# Iterative Clustering

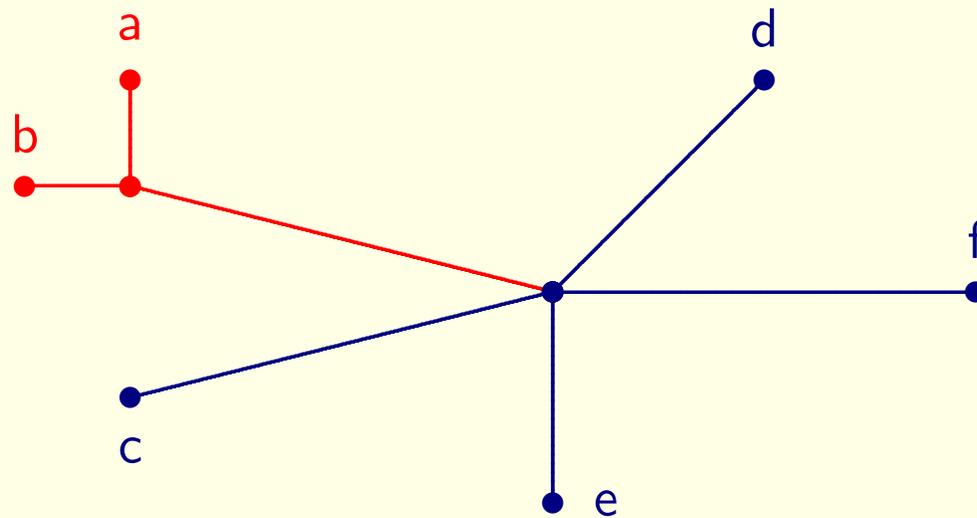
Unresolved



**n = 6**

# Iterative Clustering

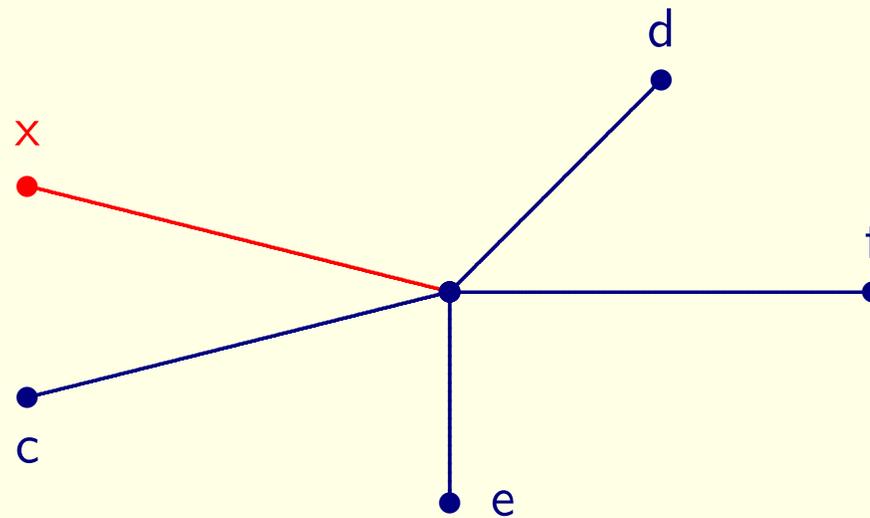
Cluster - find two siblings



$$n = 6$$

# Iterative Clustering

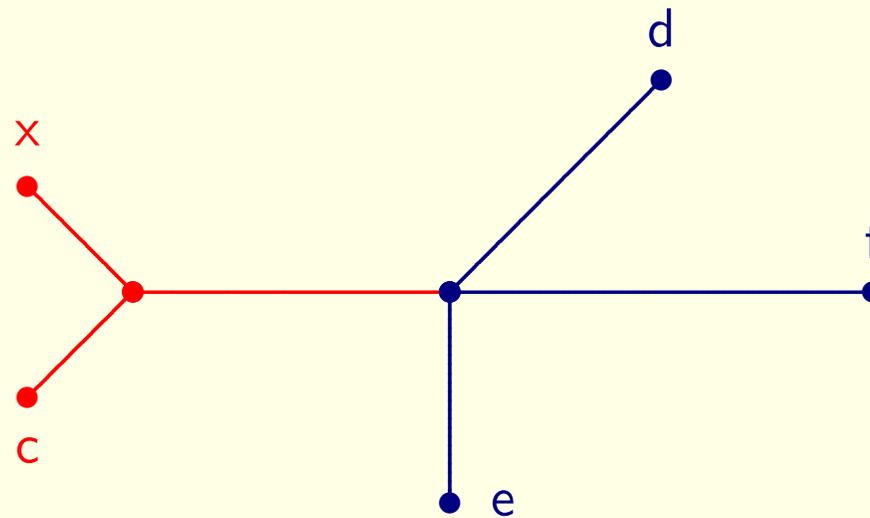
Reduce - replace by parent



$$n = 5$$

# Iterative Clustering

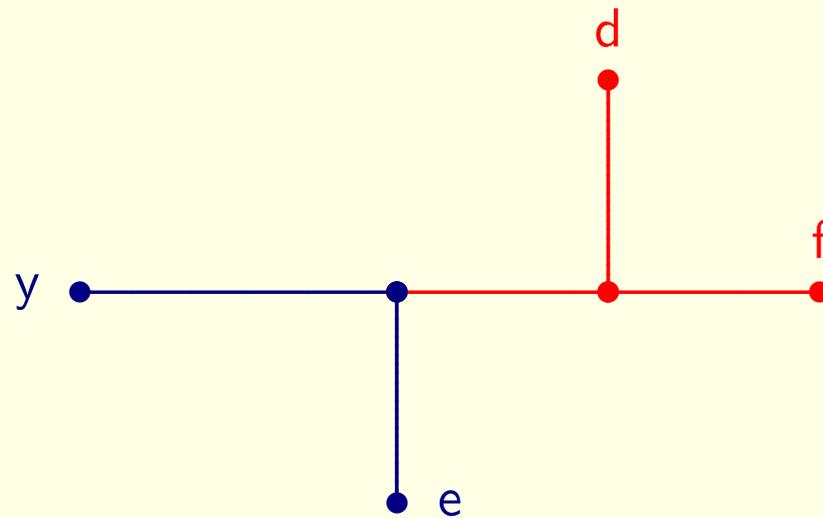
Cluster and Reduce



$$n = 5$$

# Iterative Clustering

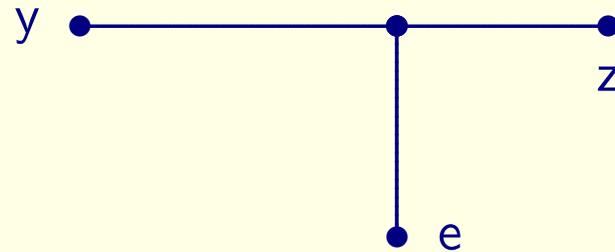
Cluster and Reduce



$$n = 4$$

# Iterative Clustering

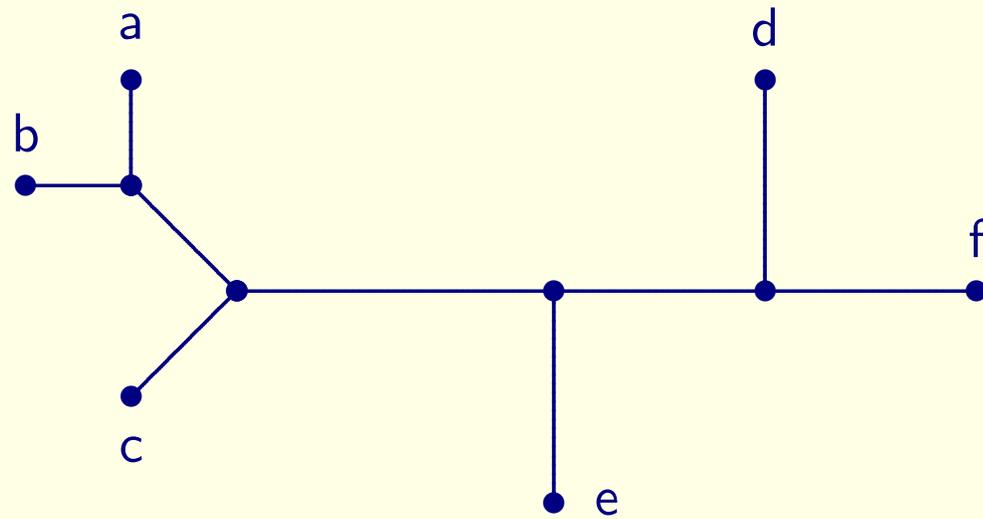
Three leaves



$$n = 3$$

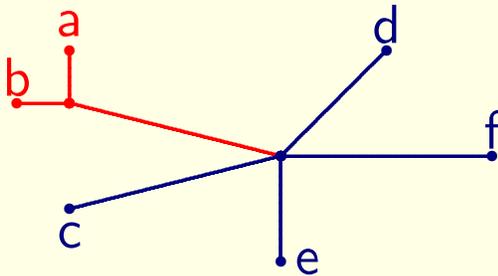
# Iterative Clustering

Resolved



# Neighbor Joining [Saitou,Nei]

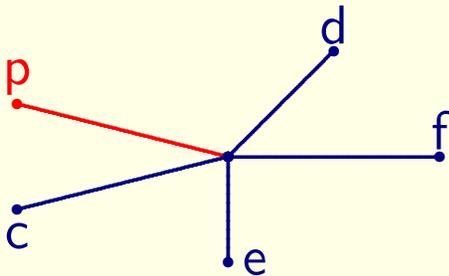
Clustering -  $O(n^2)$



$(a, b)$  is the pair minimizing

$$S_D(x, y) \triangleq (n - 2)D(x, y) - \sum_z (D(z, x) + D(z, y))$$

Reduction -  $O(n)$



Replace  $(a, b)$  by  $p$

$$D(p, x) \triangleq \frac{D(a, x) + D(b, x)}{2}$$

Total time -  $O(n^3)$

# Fast Neighbor Joining

**NJ**

$$(a, b) \leftarrow \operatorname{argmin}_{(x, y)} S_D(x, y)$$

$$D(p, x) = \frac{D(a, x) + D(b, x)}{2}$$

**FNJ**

$$(a, b) \leftarrow \operatorname{argmin}_{(x, y) \in \mathbf{V}} S_D(x, y)$$

$$D(p, x) = \frac{D(a, x) + D(b, x)}{2}$$

The minimal pair is selected from the **visible set**  $V$  of size  $O(n)$ .

	<b>Time</b>	<b>Radius</b>
<b>NJ</b>	$O(n^3)$	$\frac{\mu(T)}{2}$
<b>FNJ</b>	$O(n^2)$	$\frac{\mu(T)}{2}$

## FNJ - Detailed

### FNJ(D)

1. For each node  $a$  add  $(a, b) \leftarrow \operatorname{argmin}_{(a,y)} S_D(a, y)$  to  $V$
2. For each  $i \leftarrow 1$  to  $n - 3$  do
  - (a)  $(a, b) \leftarrow \operatorname{argmin}_{(x,y) \in V} S_D(x, y)$
  - (b) Reduce  $(a, b) \rightarrow p$  using  $D(p, x) = (D(a, x) + D(b, x))/2$
  - (c) Add  $(p, b) \leftarrow \operatorname{argmin}_{(p,y)} S_D(p, y)$  to  $V$

## The Proof

$$|D_T - D|_\infty < \frac{\mu(T)}{2} \implies \text{FNJ}(D) = T$$

**We have to prove**

$$(a, b) \leftarrow \operatorname{argmin}_{(x,y) \in V} S_D(x, y) \implies (a, b) \text{ are siblings in } T$$

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**We know** NJ has radius  $\frac{\mu(T)}{2}$ .

**We show** that FNJ behaves as NJ on nearly additive input.

**In each iteration the same sibling pair is chosen.**

# Proof Sketch

- |   |        |
|---|--------|
| 1. For each node $a$ add $(a, b) \leftarrow \operatorname{argmin}_{(a,y)} S_D(a, y)$ to $V$ | Part 1 |
| 2. For each $i \leftarrow 1$ to $n - 3$ do  |        |
| (a) $(a, b) \leftarrow \operatorname{argmin}_{(x,y) \in V} S_D(x, y)$                       | Part 2 |
| (b) Reduce $(a, b) \rightarrow p$ using $D(p, x) = (D(a, x) + D(b, x))/2$                   |        |
| (c) Add $(p, b) \leftarrow \operatorname{argmin}_{(p,y)} S_D(p, y)$ to $V$                  | Part 1 |

**Part 1** If  $a$  has sibling  $b$  then  $(a, b) \leftarrow \operatorname{argmin}_{(a,x) \in V} S_D(a, x)$ .

$\implies V$  contains all sibling pairs

**Part 2** If  $(c, d)$  is not a sibling pair  $\implies \exists(a, b)$  s.t.  $S_D(a, b) < S_D(c, d)$ .

$\implies$  the minimum over  $V$  is a sibling pair

## The Additive Case [Atteson]

I will show the additive case,

$$\text{FNJ}(\mathbf{D}_T) = \mathbf{T}$$

## The Additive Case [Atteson]

$$D_T(x, y) = \sum_{e \in \text{path}(x, y)} l(e)$$

$$S_D(x, y) \triangleq (n - 2)D(x, y) - \sum_z (D(z, x) + D(z, y))$$

$$S_{D_T}(x, y) = \sum_{e \in E(T)} \mathbf{w}_e(\mathbf{x}, \mathbf{y}) l(e), \text{ where}$$

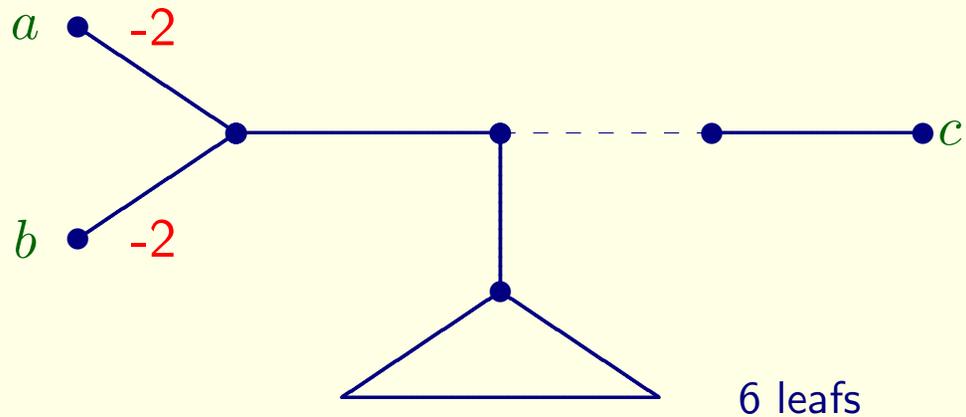
$$w_e(x, y) = \begin{cases} -2 & \text{if } e \in \text{path}(x, y) \\ -2|L(T) \setminus \mathcal{L}_T(x, e)| & \text{otherwise.} \end{cases}$$

## Part 1. The Additive Case (cont.)

$$S_{D_T}(x, y) = \sum_{e \in E(T)} w_e(x, y) l(e), \text{ where}$$

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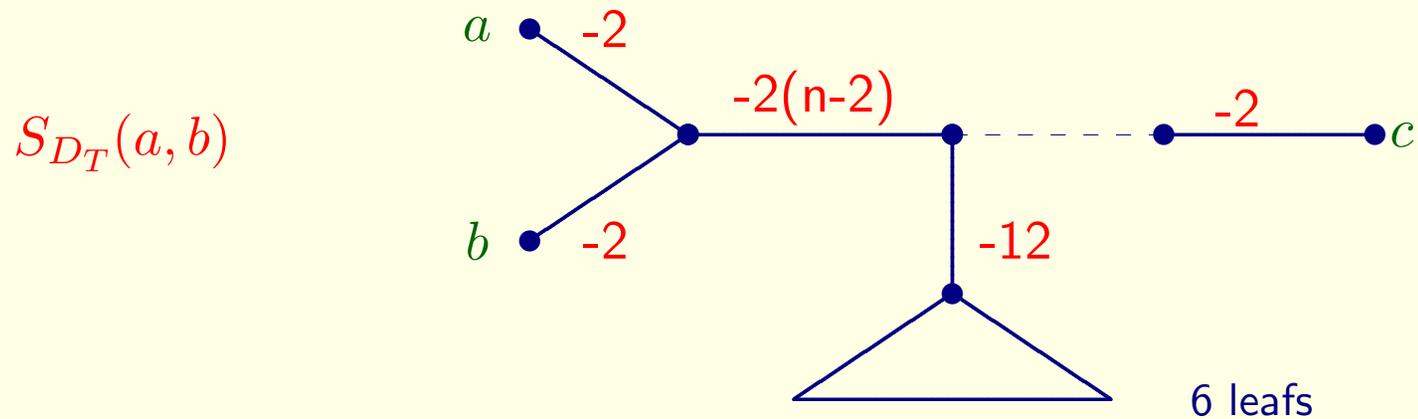
$S_{D_T}(a, b)$



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## Proof Sketch (cont.)

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**Part 2** If  $(x, y)$  is not a sibling pair  $\implies \exists (a, b)$  s.t.  $S_D(a, b) < S_D(x, y)$ .

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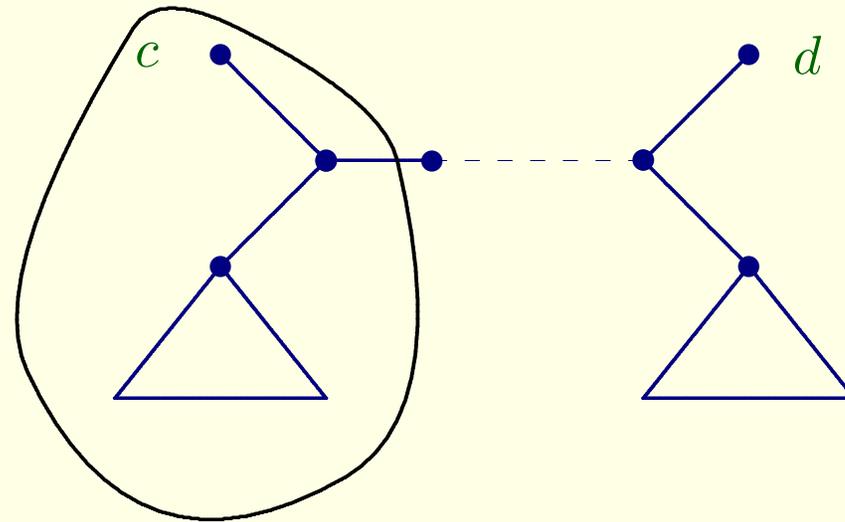
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## Part 2. The Additive Case

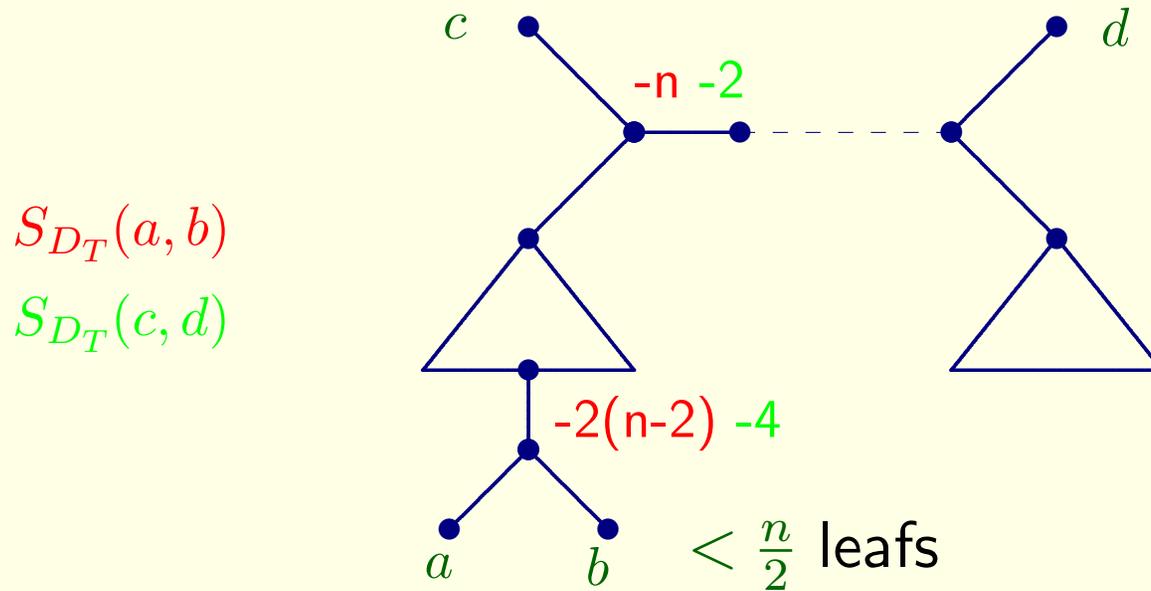
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$< \frac{n}{2}$  leafs

## Part 2. The Additive Case

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$$S_{D_T}(c, d) - S_{D_T}(a, b) > 3(n - 4)\mu(\mathbf{T})$$

# Results

	Time	Radius	Our contribution
<b>NJ</b>	$O(n^3)$	$\frac{\mu(T)}{2}$	simplify the proof
<b>FNJ</b>	$O(n^2)$	$\frac{\mu(T)}{2}$	new fast algorithm

Most real input is far from being nearly additive.

FNJ is very fast and works well in practice!

## New Directions

- BioNJ and Weighbor can be changed in the same way.
- FNJ as a subroutine in the fast converging Disk-Covering Method  
 $O(n^5) \rightarrow O(n^4)$ .

# Acknowledgments

Dr. Luay Nakhleh  
and  
Prof. Tandy Warnow

**Thanks!**