

Parameterized Maximum Path Coloring

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Path Coloring Definition

❖ Path Coloring

- ❖ Example
- ❖ Known results
- ❖ Edge slicing
- ❖ Max PC
- ❖ Max PC hardness results
- ❖ DNP
- ❖ Reduction
- ❖ Reduction
- ❖ Complexity jump
- ❖ $(p\Delta, pW, pT)$ -MaxPC
- ❖ (pT) -MaxPC binary trees
- ❖ (pT) -MaxPC binary trees
- ❖ Algorithm cont'd
- ❖ Open problems

Path Coloring

Input: A graph G and a multi-set of paths on that graph

Constraint: Assign colors from $\{1, \dots, W\}$ to the paths so that paths that share an edge receive different colors.

Objective: min W

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- Instead of paths we could be given endpoints (Routing and Path Coloring)

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Path Coloring

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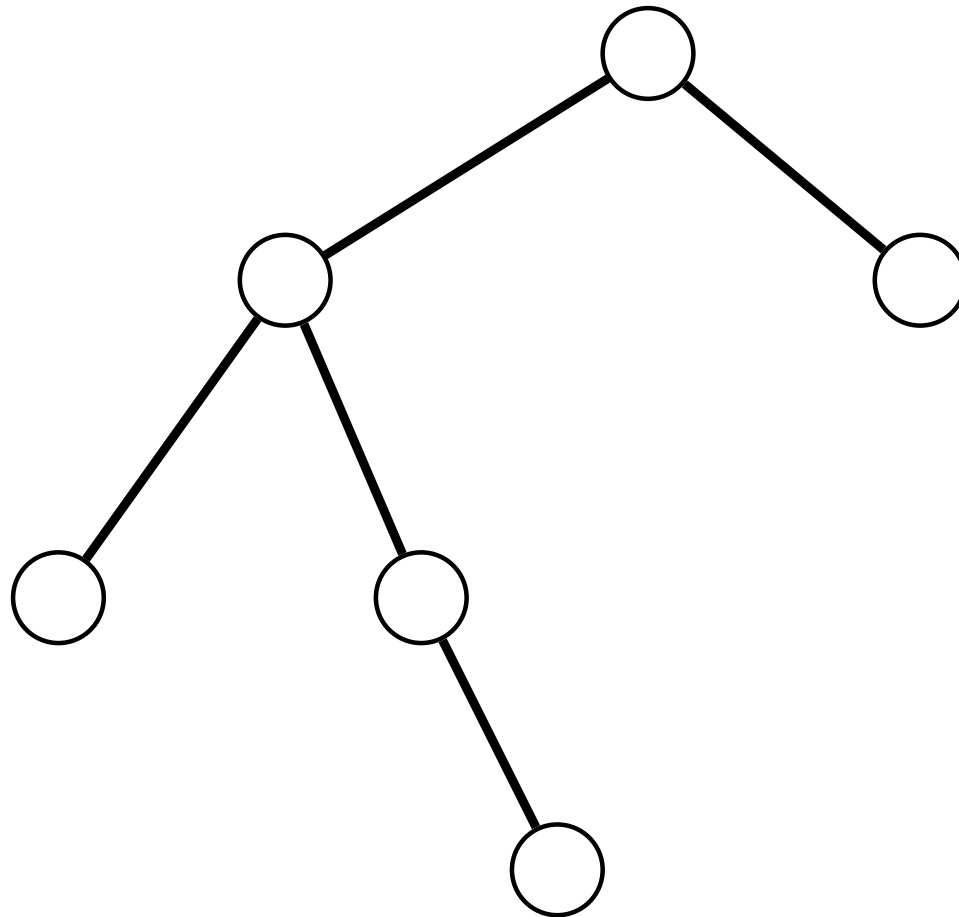
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- Graph could be undirected or bi-directed
- Instead of paths we could be given endpoints (Routing and Path Coloring)
- We'll mostly talk about trees (\rightarrow unique routing)

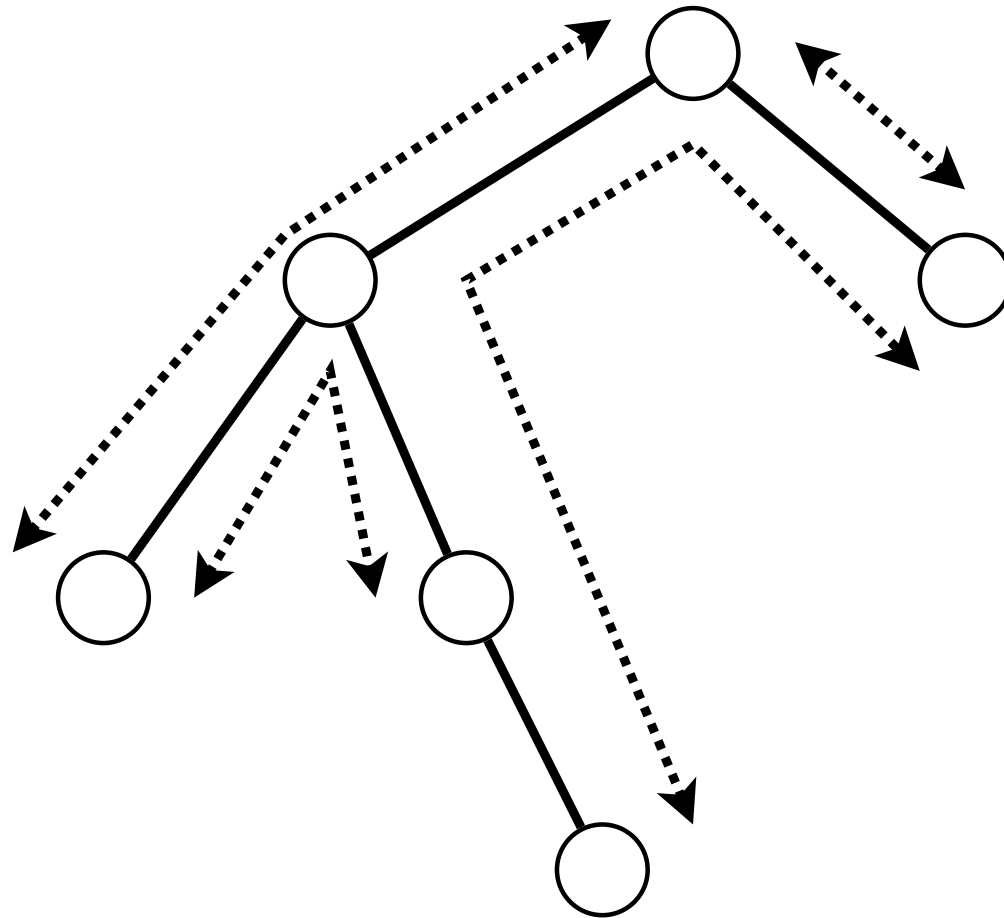
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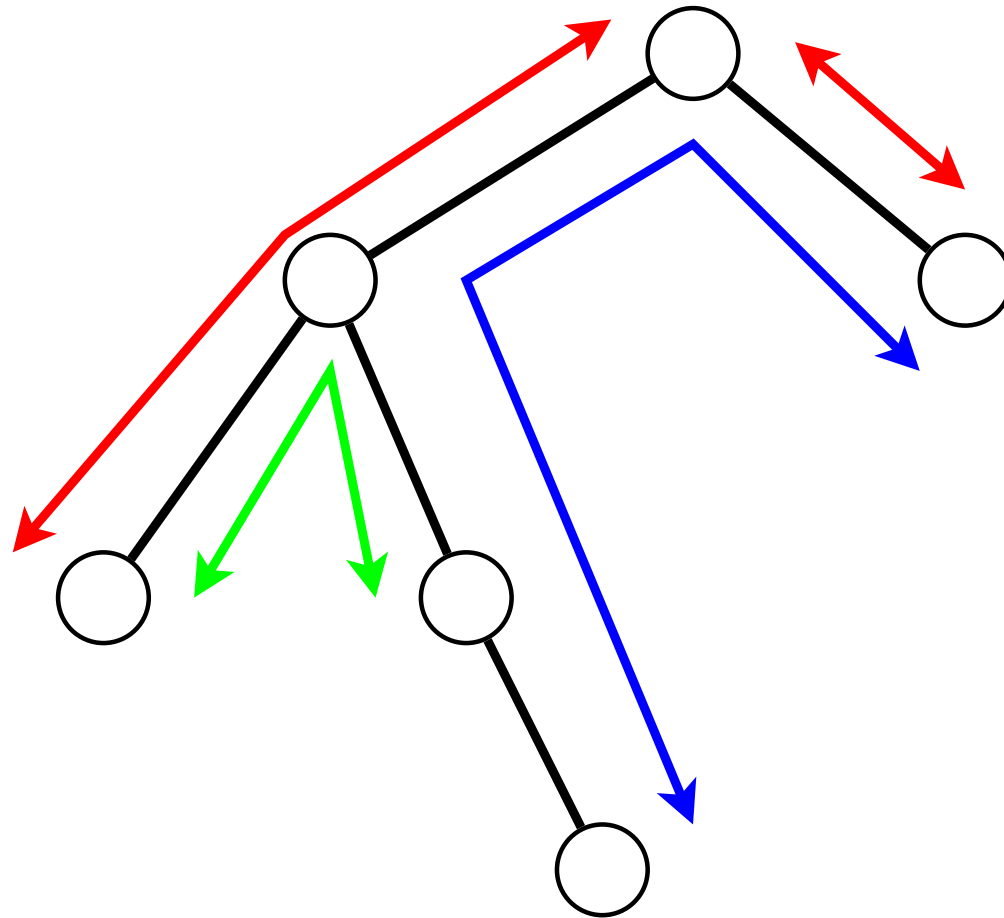
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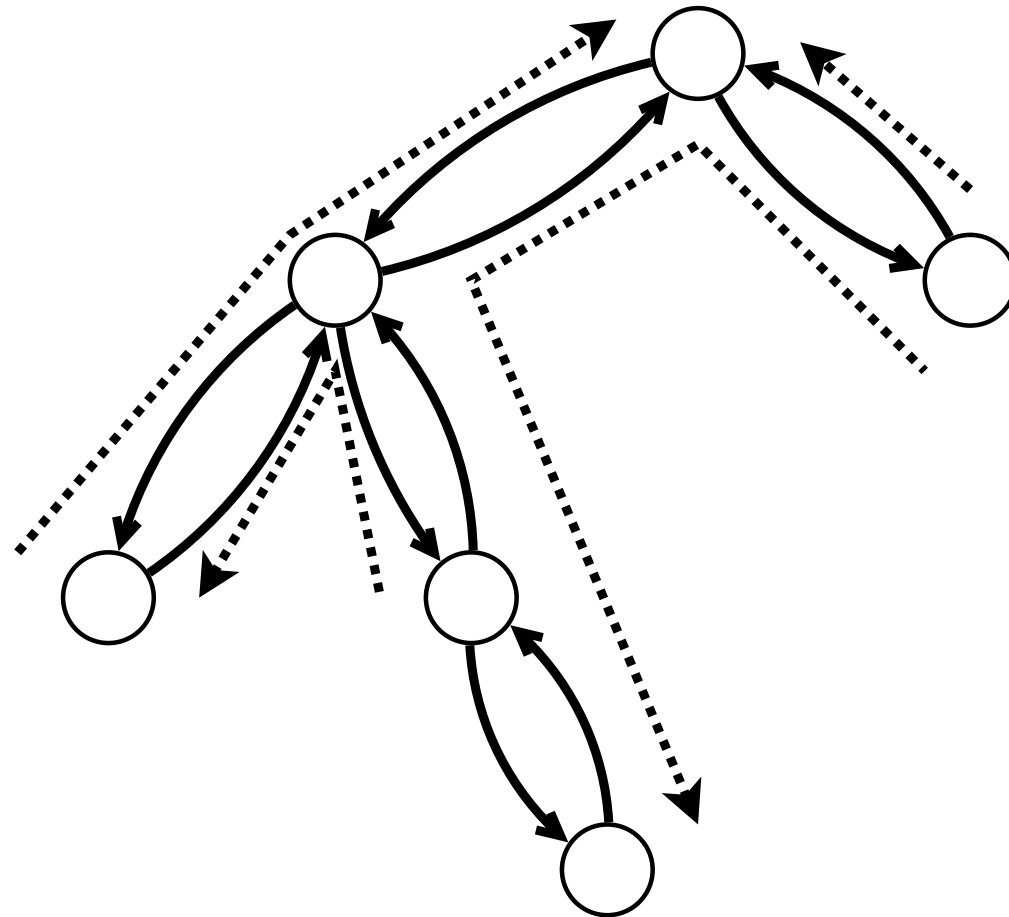
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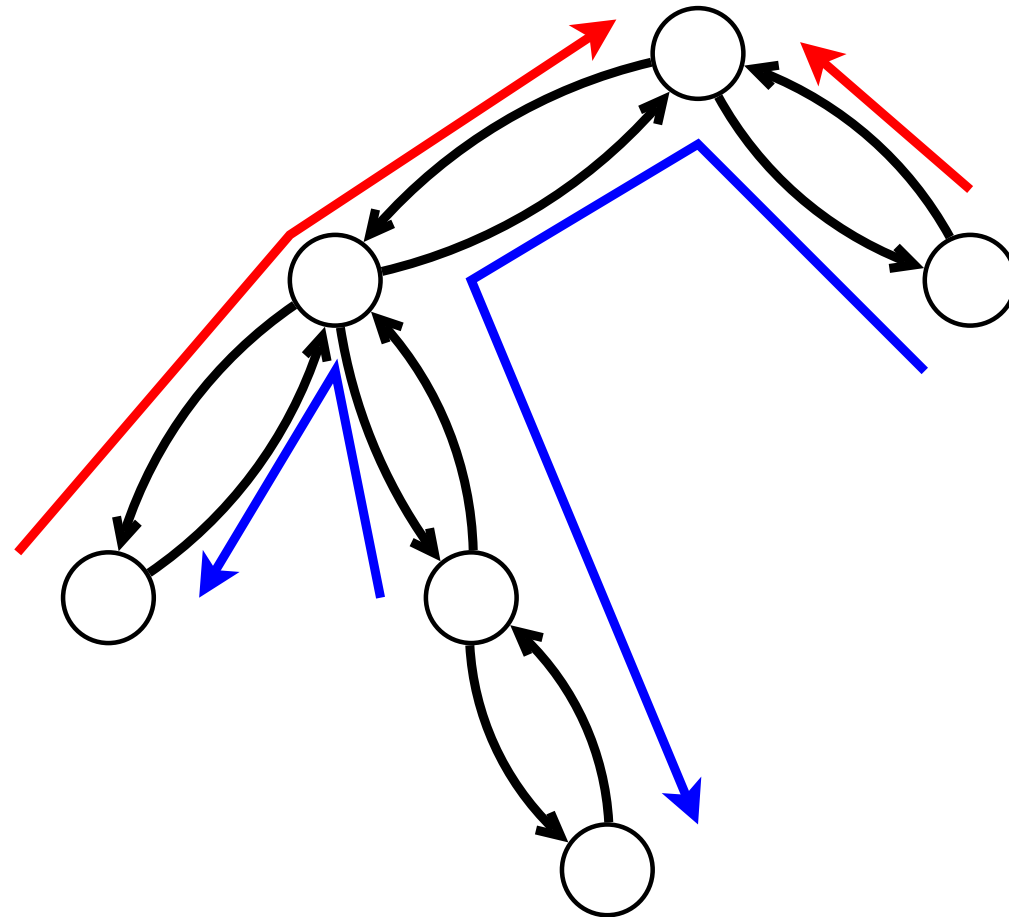
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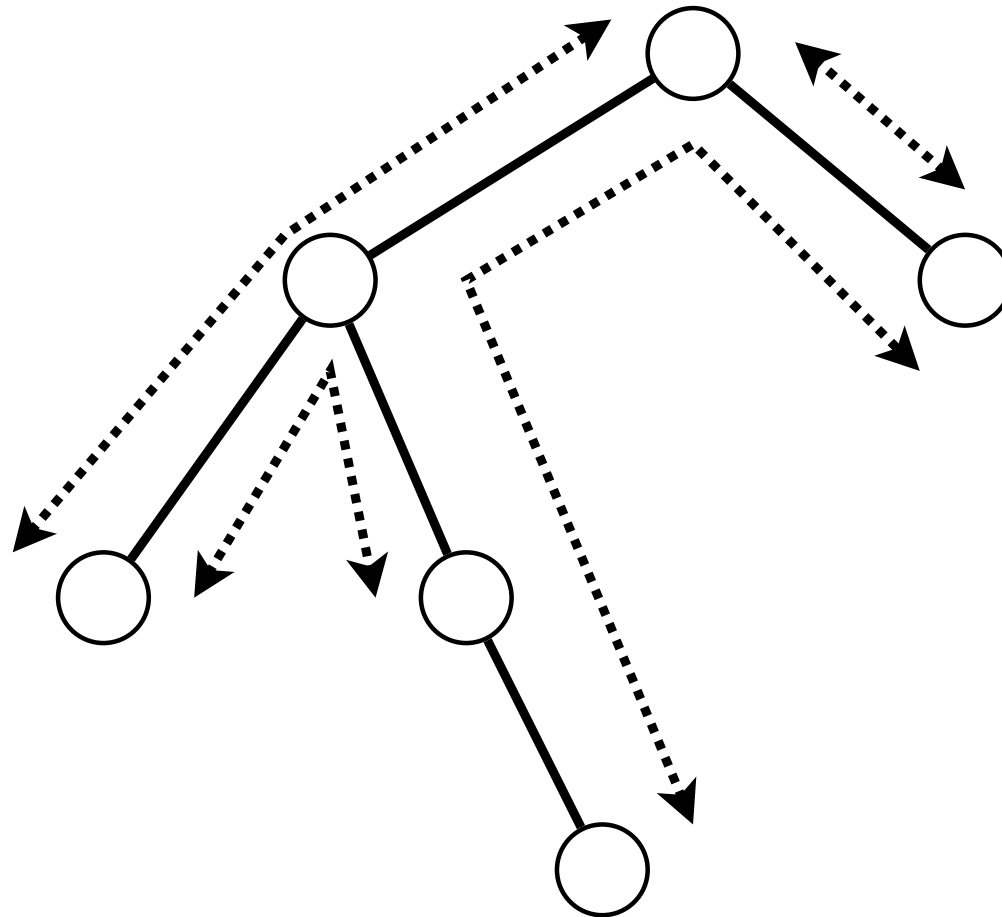
Known results

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- PC is very hard!
 - ❖ NP-hard on stars [Erlebach, Jansen 2001]
 - ❖ NP-hard on rings [Garey, Johnson, Miller, Papadimitriou 1980]
 - ❖ NP-hard on bi-directed binary trees [Kumar, Panigrahy, Russel, Sundaram 1997]
- Good news: Thanks to a simple trick undirected trees are no harder than stars.

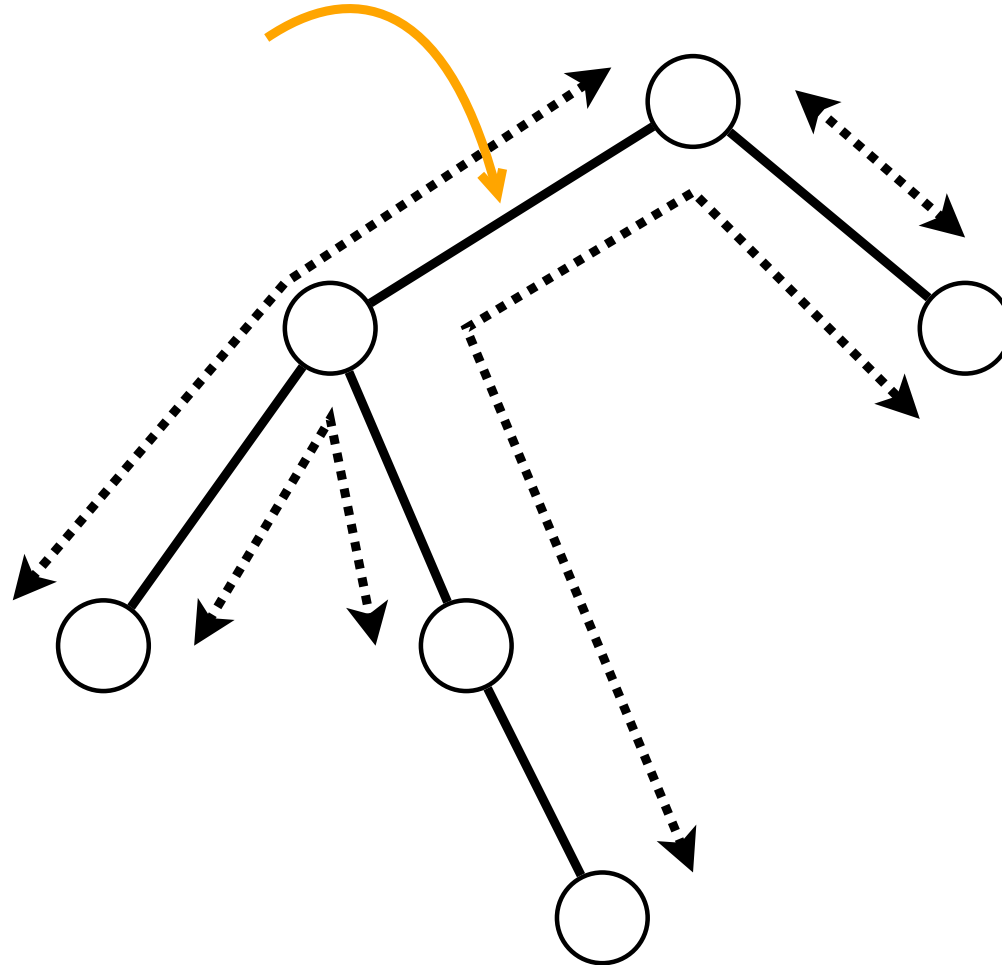
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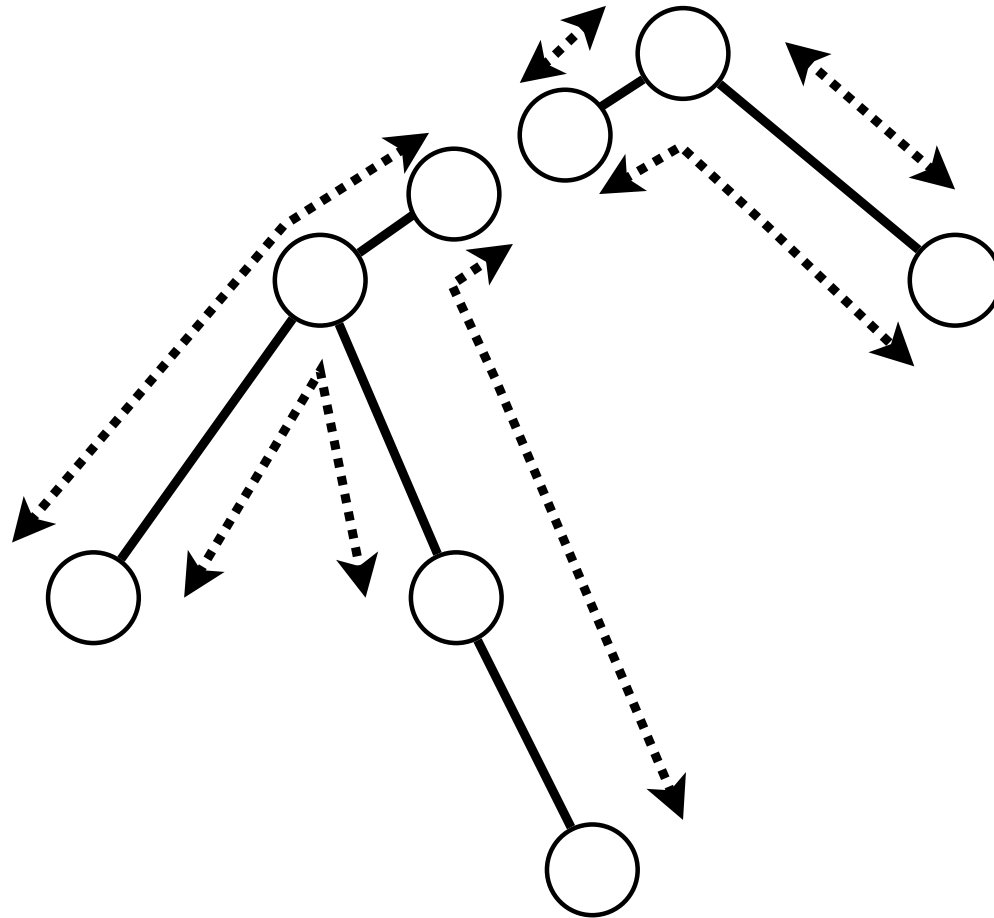
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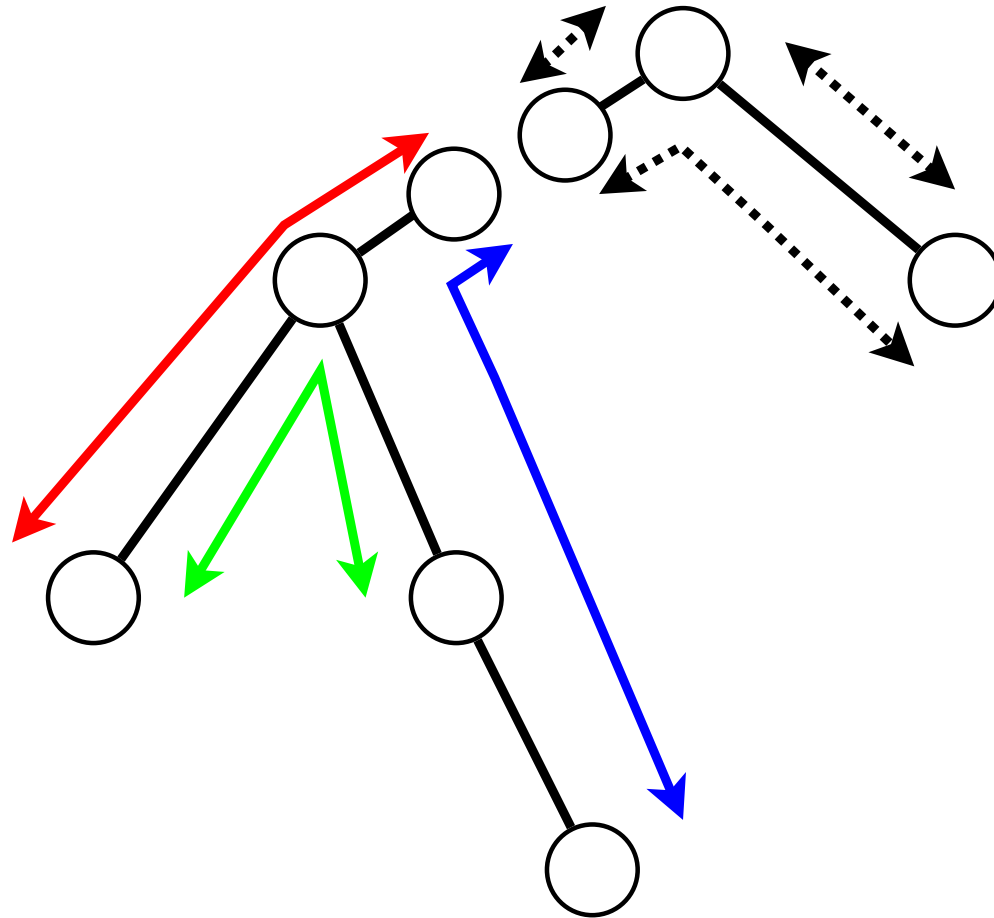
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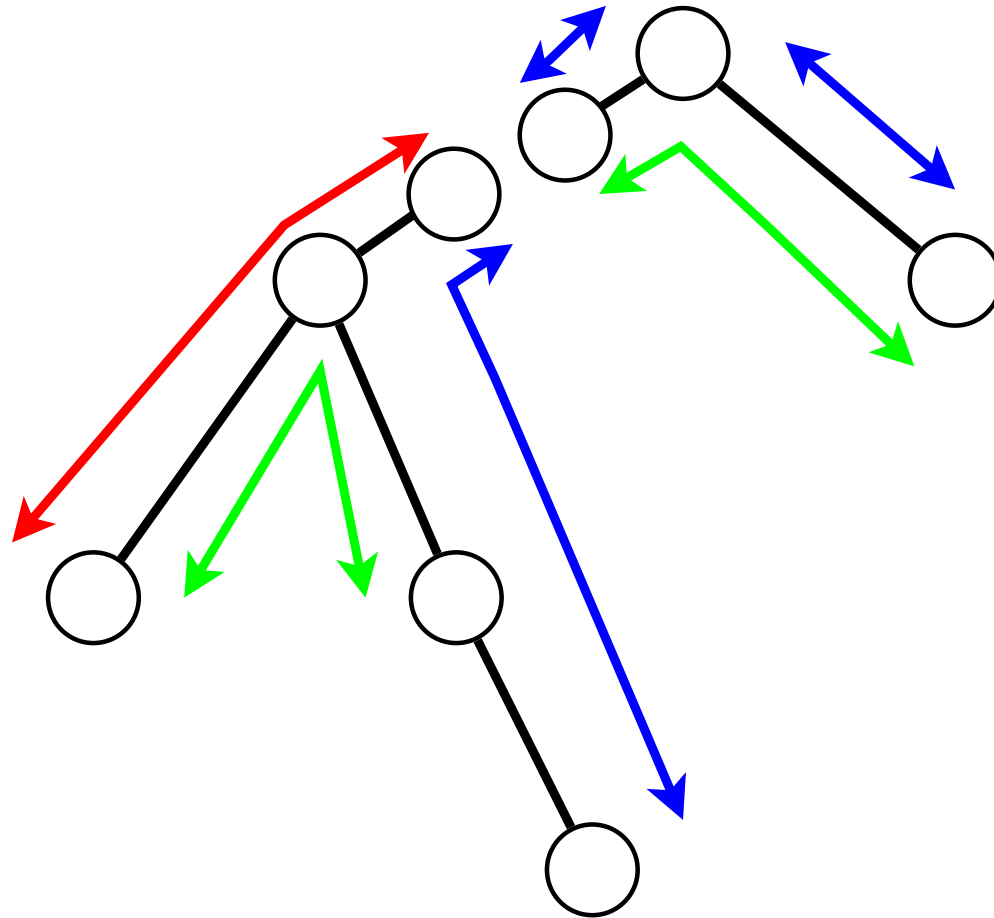
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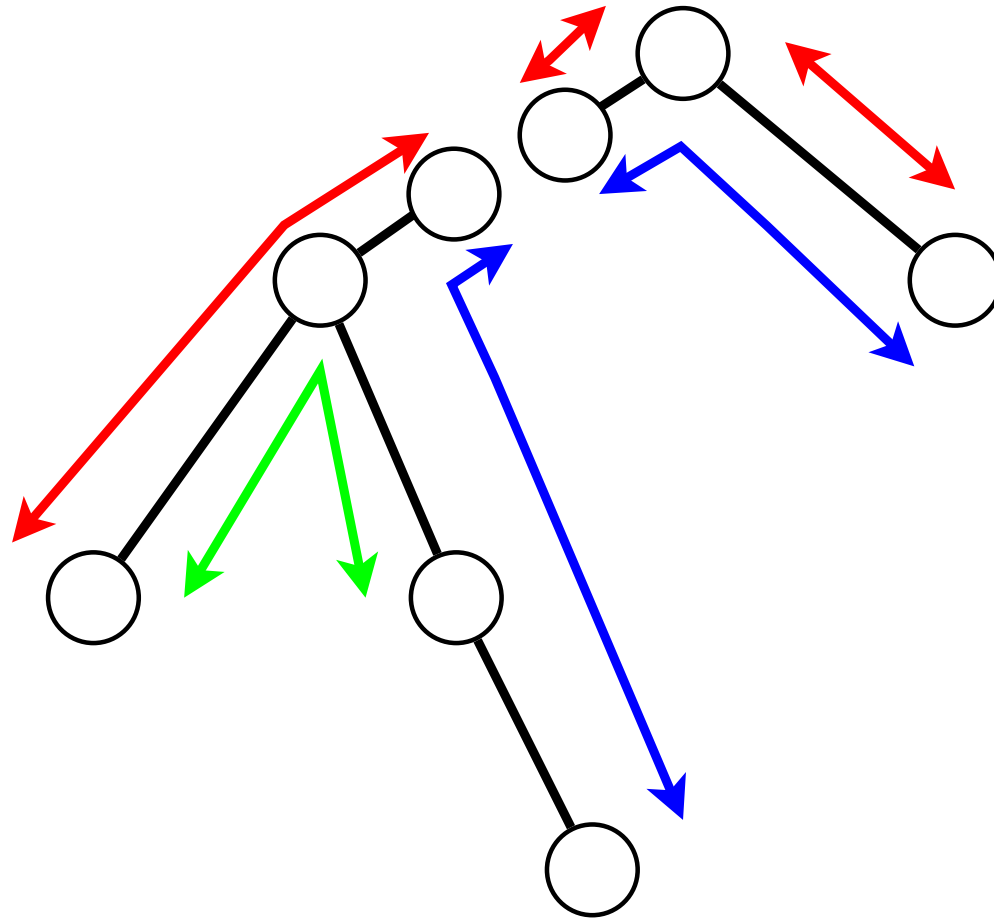
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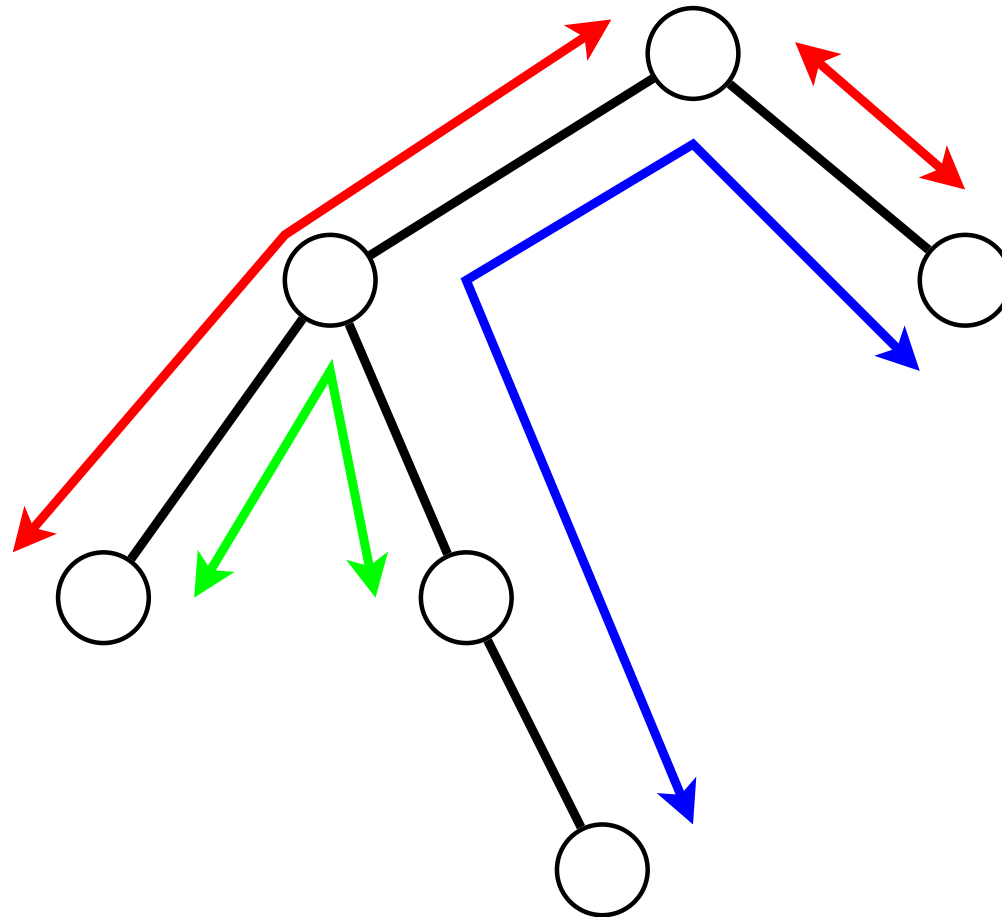
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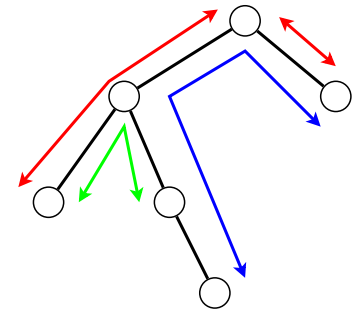
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- Repeated edge slicing can break down any undirected tree to a star
- If we could solve PC on stars \rightarrow poly-time algorithm (we can't!)
 - ❖ But FPT algorithm when parameterized by Δ . [Erlebach, Jansen 2001]
- Ironically, this doesn't work for bi-directed trees, where stars are easy.
 - ❖ But FPT algorithm when parameterized by $\Delta + W$. [Erlebach, Jansen 2001]



Max PC

Max Path Coloring

Input: A graph G and a multi-set of paths on that graph, color budget W

Constraint: Assign colors from $\{1, \dots, W\}$ to B of the paths so that paths that share an edge receive different colors.

Objective: max B

- Strict generalization of PC as a decision problem
 - ❖ \rightarrow At least as hard to solve exactly

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- Max PC is solvable in $n^{\Delta W}$ on trees. [Erlebach, Jansen 1998]
- Can we do this in FPT time for either parameter?

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Max PC hardness results

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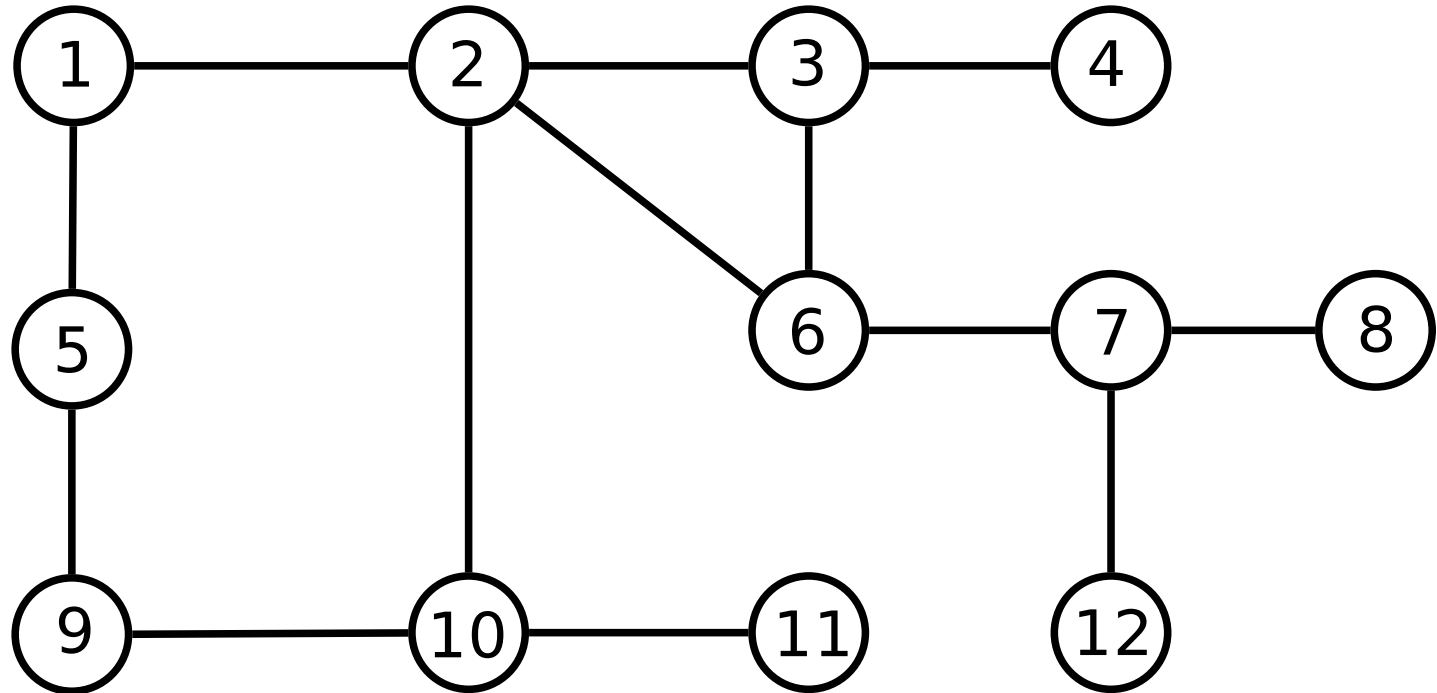
- An $n^{\Delta W}$ algorithm is known to solve Max PC exactly on trees. Can we do better?

Max PC hardness results

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- An $n^{\Delta W t}$ algorithm is known to solve Max PC exactly on trees. ($t = \text{treewidth}$)
- We show that:
 - ❖ Max PC is W -hard parameterized by W , even for trees with $\Delta = 3$.
 - ❖ Max PC is W -hard parameterized by Δ , even for trees with $W = 4$.
 - ❖ Max PC is W -hard parameterized by t , even for $\Delta = W = 4$.
- \rightarrow No $n^{o(\sqrt{\Delta W t})}$ algorithm exists (assuming ETH).
- Strategy: Ind Set \leq DNP \leq Cap Max PC \leq Max PC

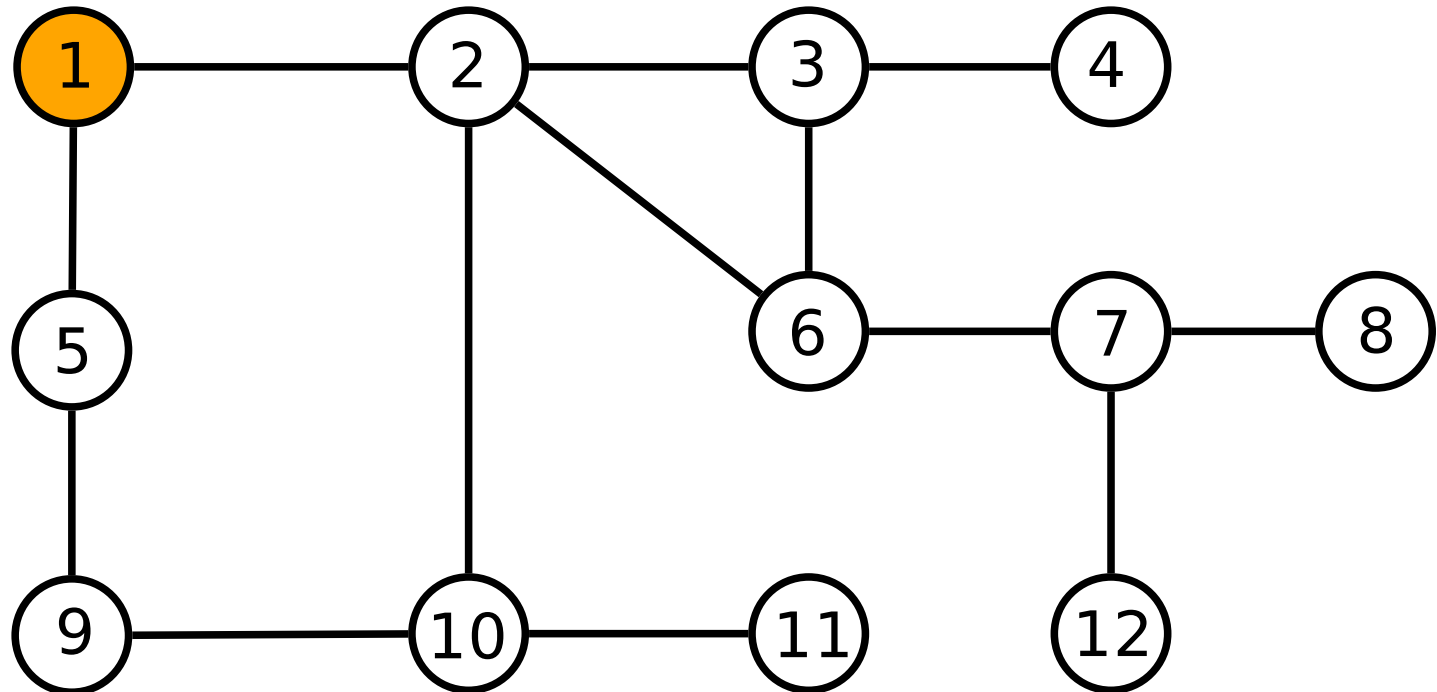
Disjoint Neighborhood Packing



In this problem we want to select a maximum-size set of vertices such that all pairs have distance > 2

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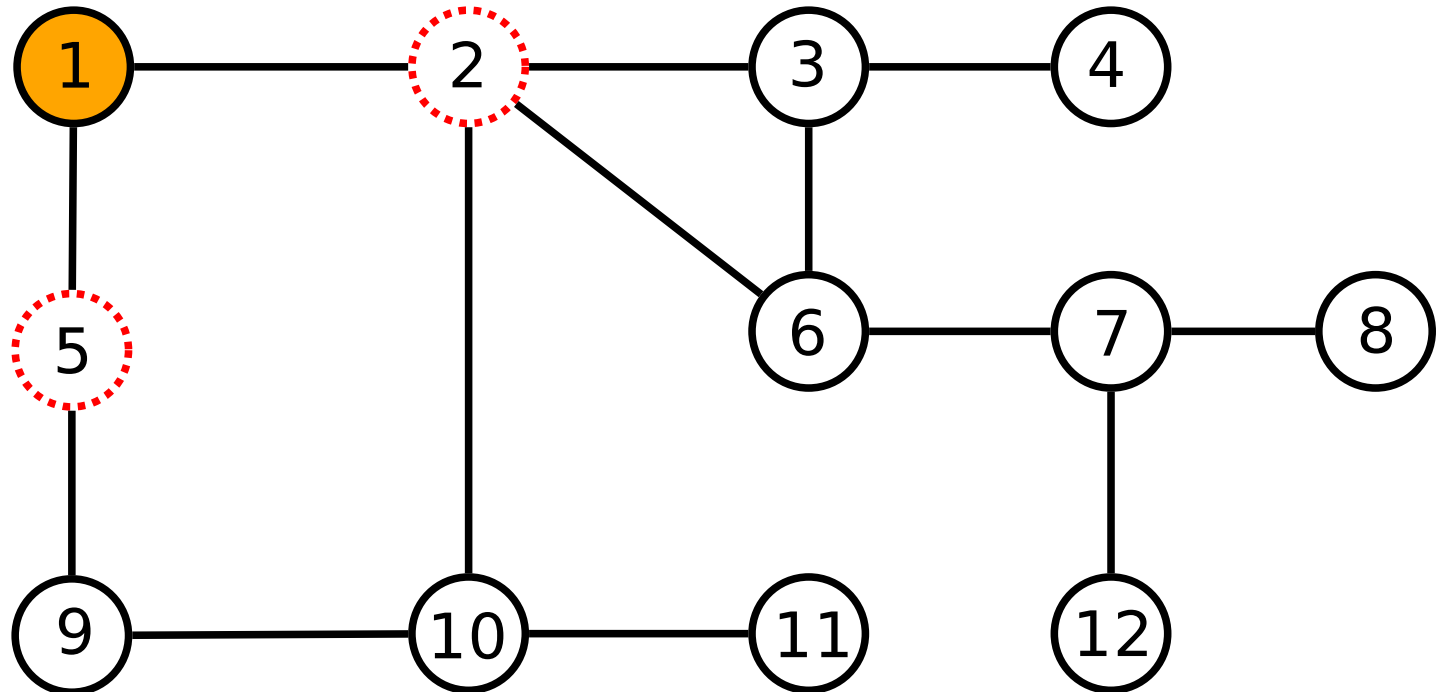
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Selecting a vertex will disqualify ...

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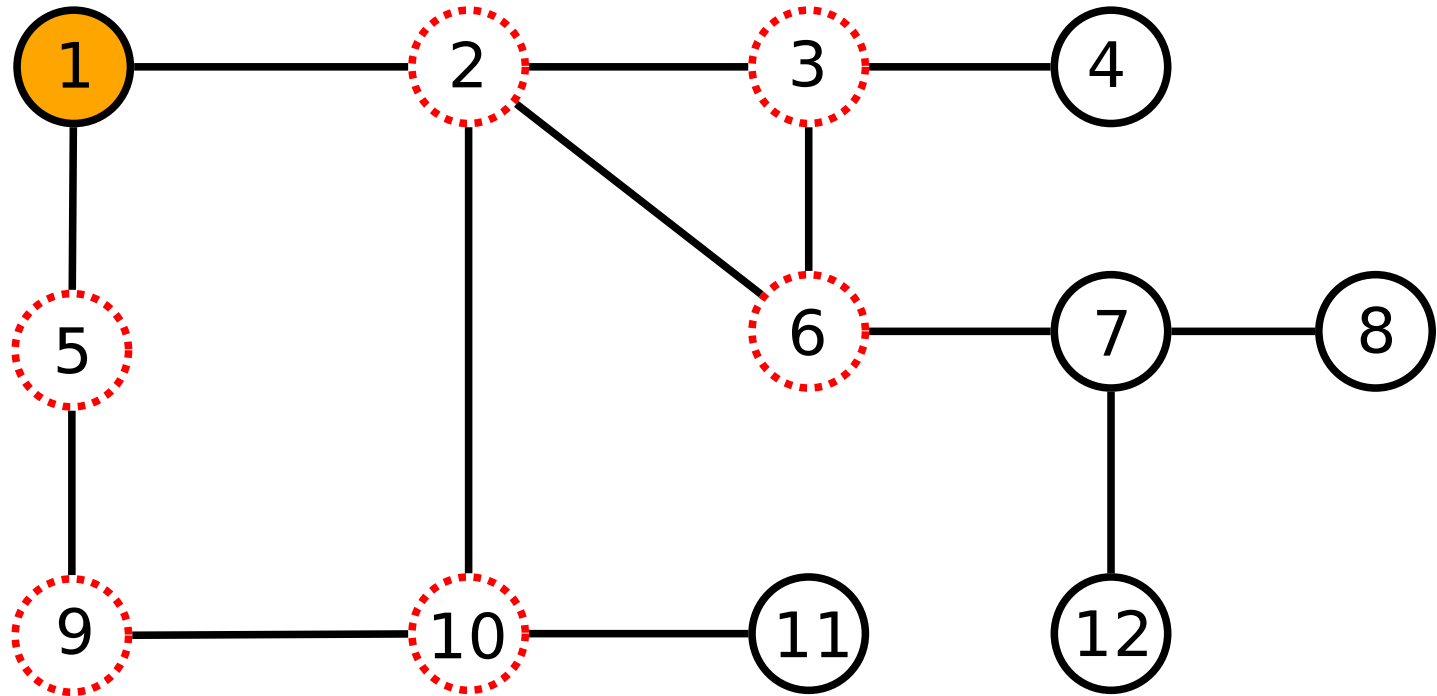
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Selecting a vertex will disqualify its neighbors ...

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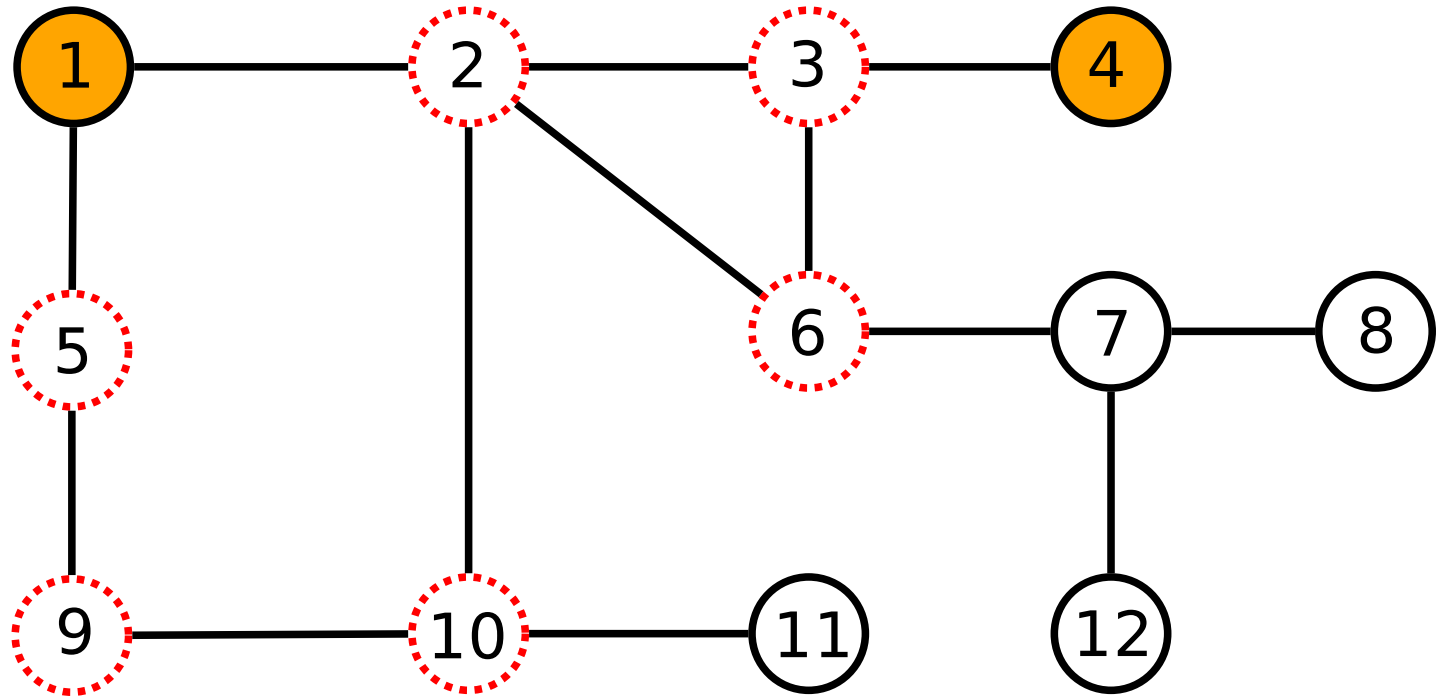
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Selecting a vertex will disqualify its neighbors *and* their neighbors from future selection

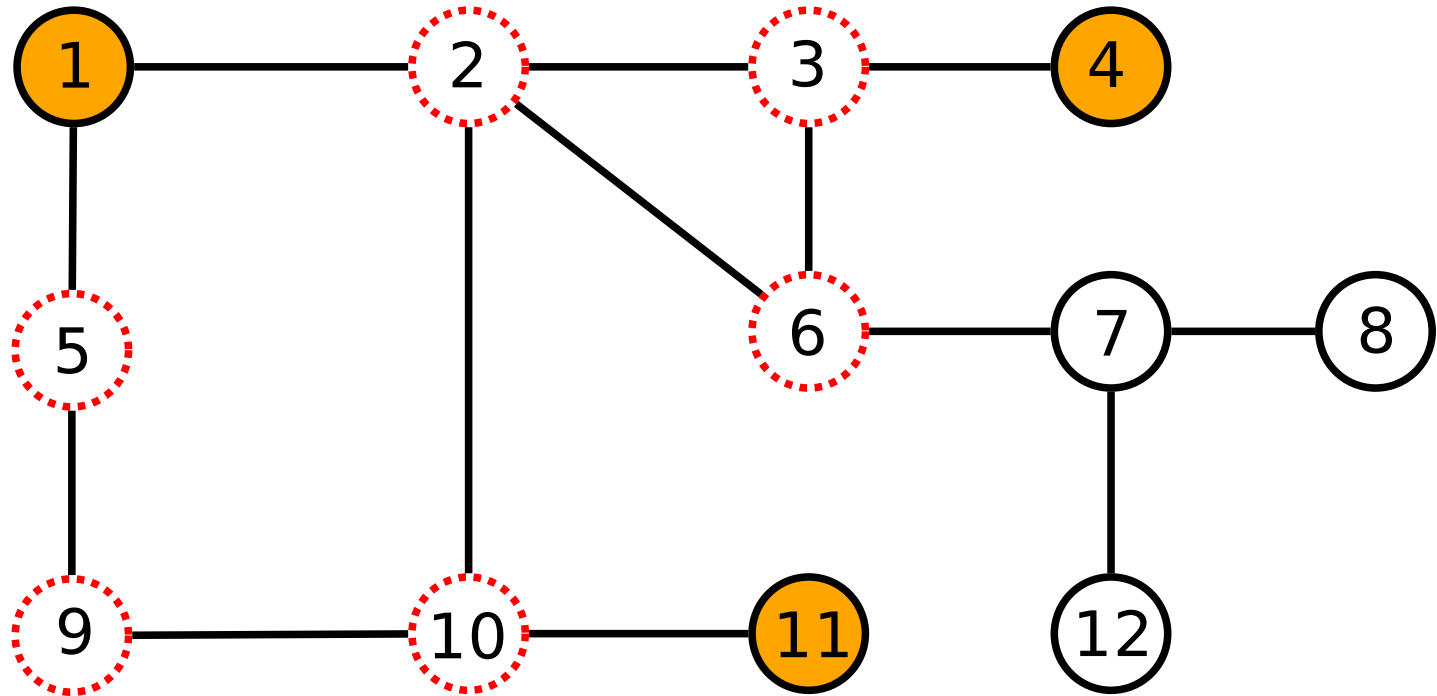
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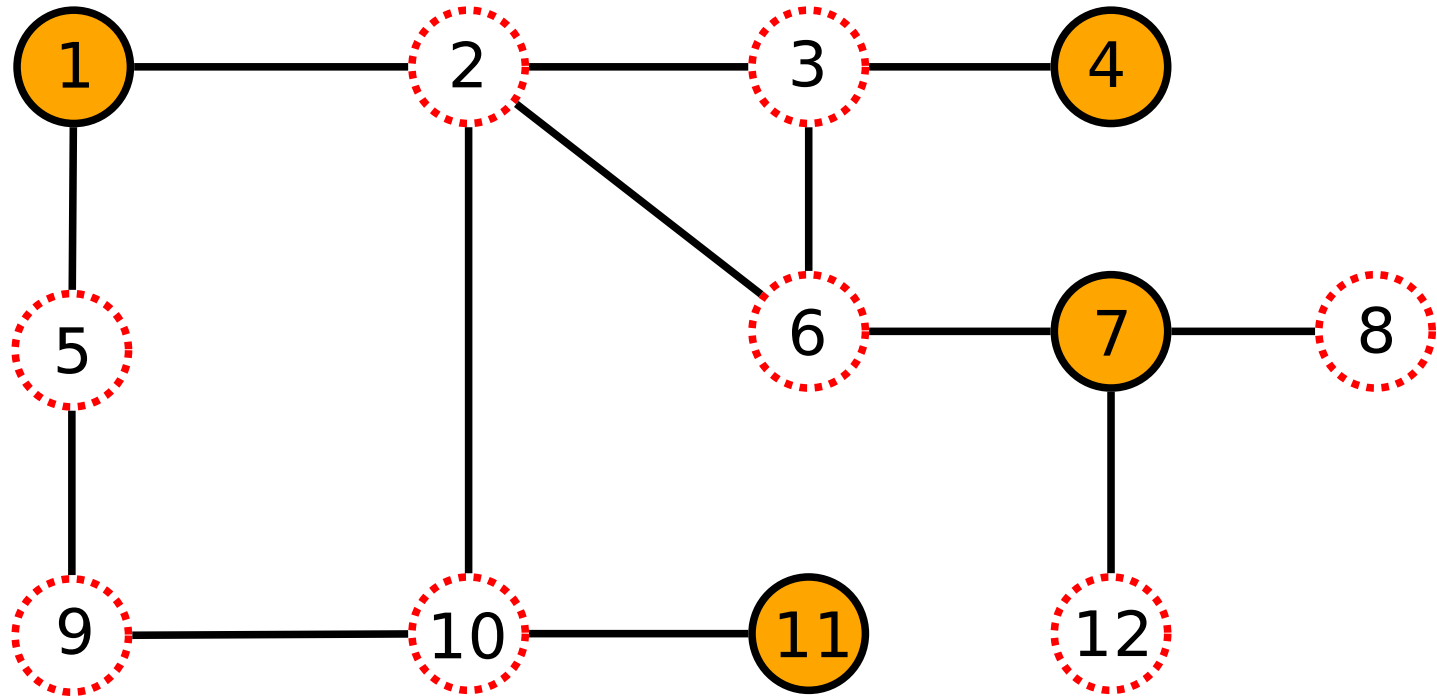
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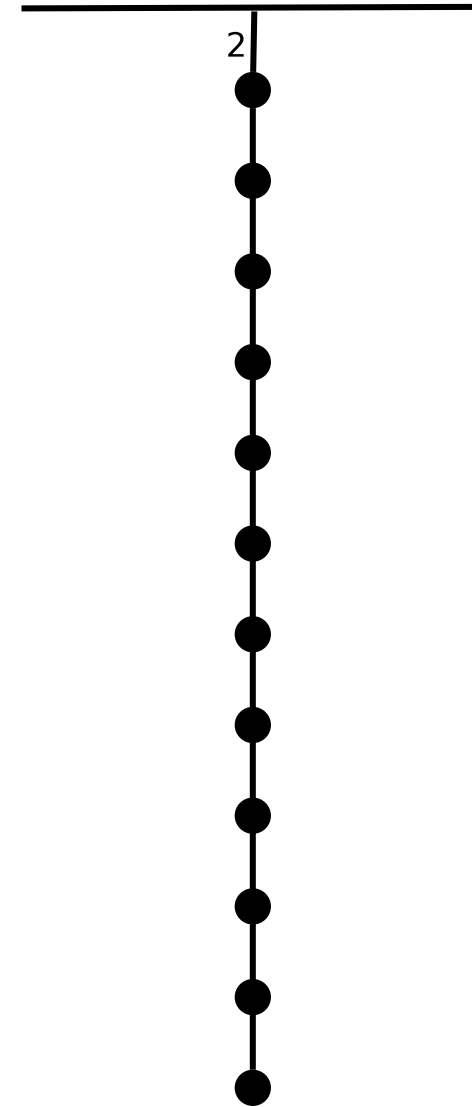
Problem is similar to Independent Set (and similarly W-hard)

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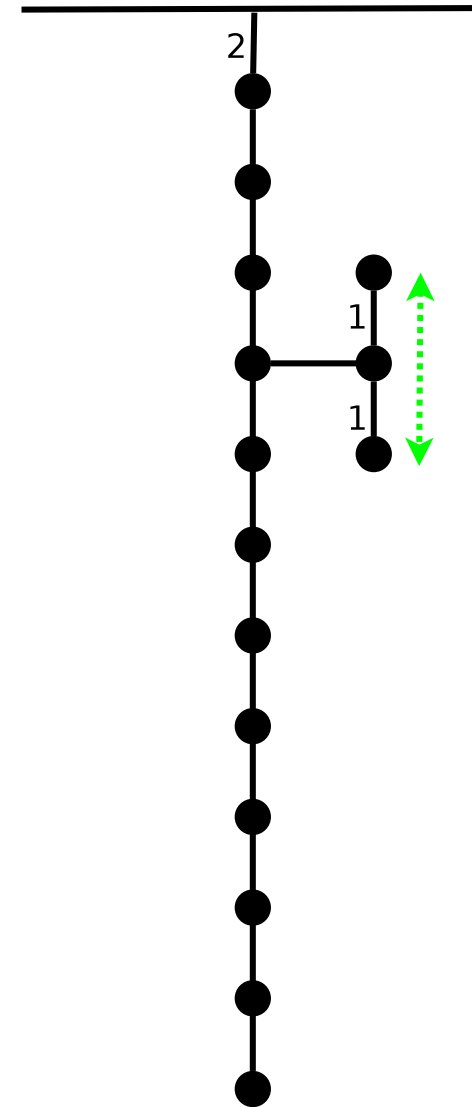
- Our basic gadget is a path on n vertices, to be attached to a “backbone” through an edge of capacity 2.



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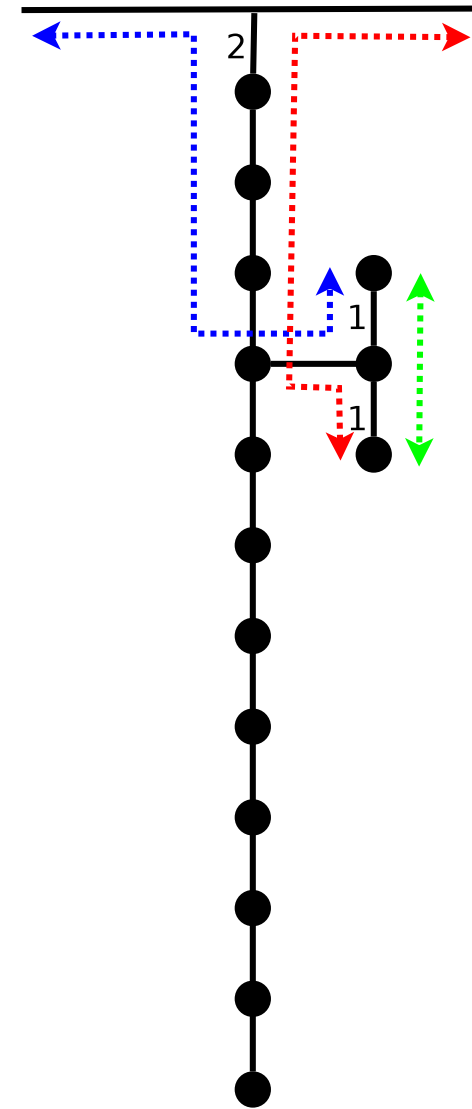
- To each vertex of a gadget we attach a short path with a local demand



Reduction

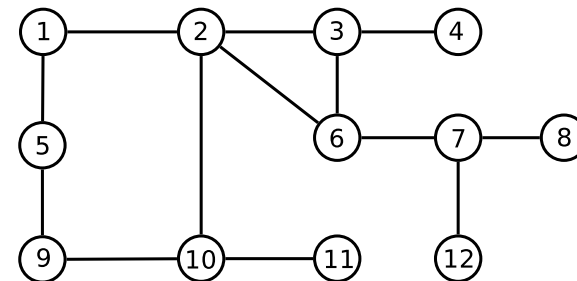
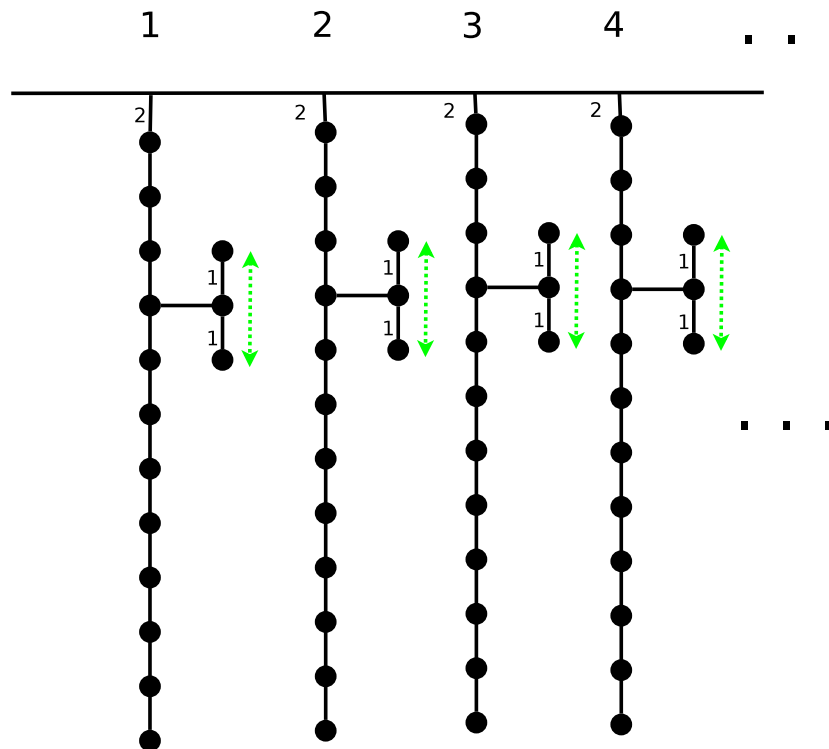
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- The local demand will overlap with two global demands so that either the local demand is selected or **both** global demands



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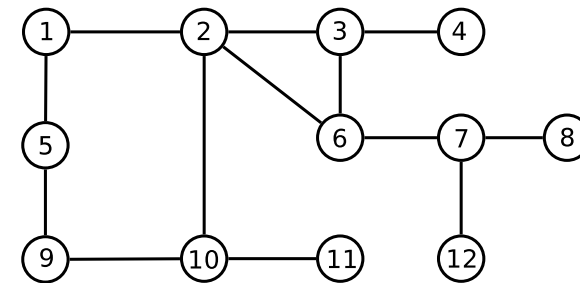
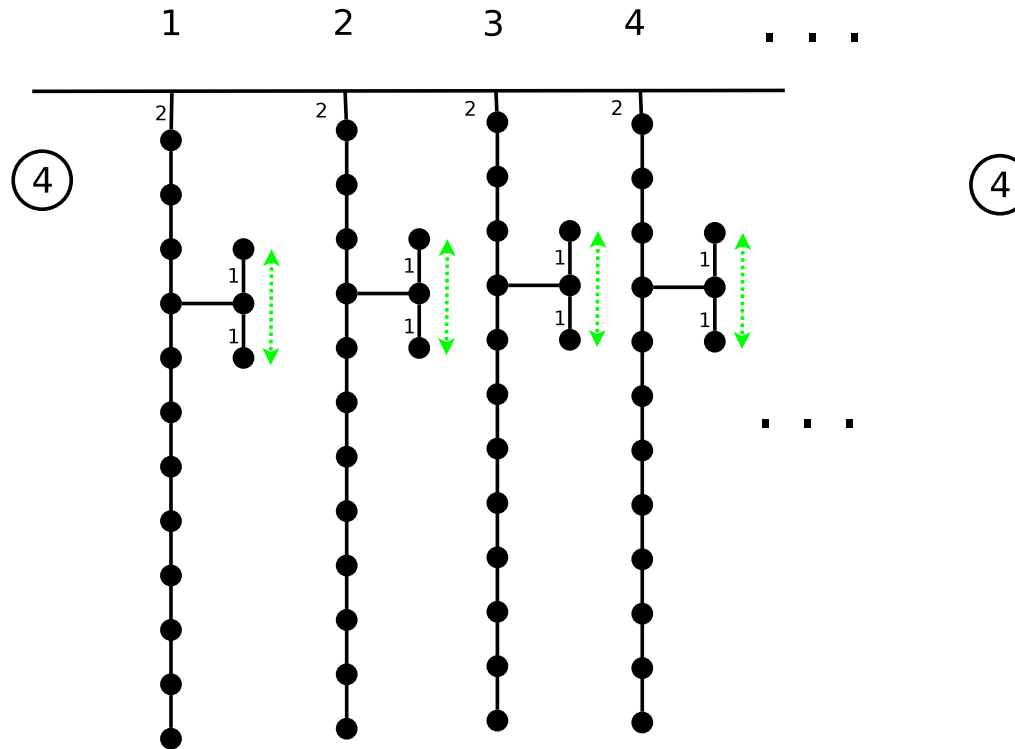
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- ❖ Known results
- ❖ Edge slicing
- ❖ Max PC
- ❖ Max PC hardness results
- ❖ DNP
- ❖ Reduction
- ❖ Reduction
- ❖ Complexity jump
- ❖ $(p\Delta, pW, pT)$ -MaxPC
- ❖ (pT) -MaxPC binary trees
- ❖ (pT) -MaxPC binary trees
- ❖ Algorithm cont'd
- ❖ Open problems



- We put n copies of the gadget on the backbone, one for each vertex.

Reduction

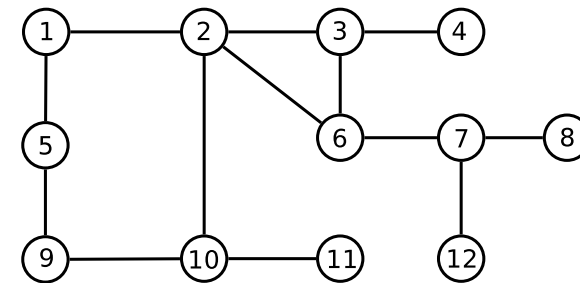
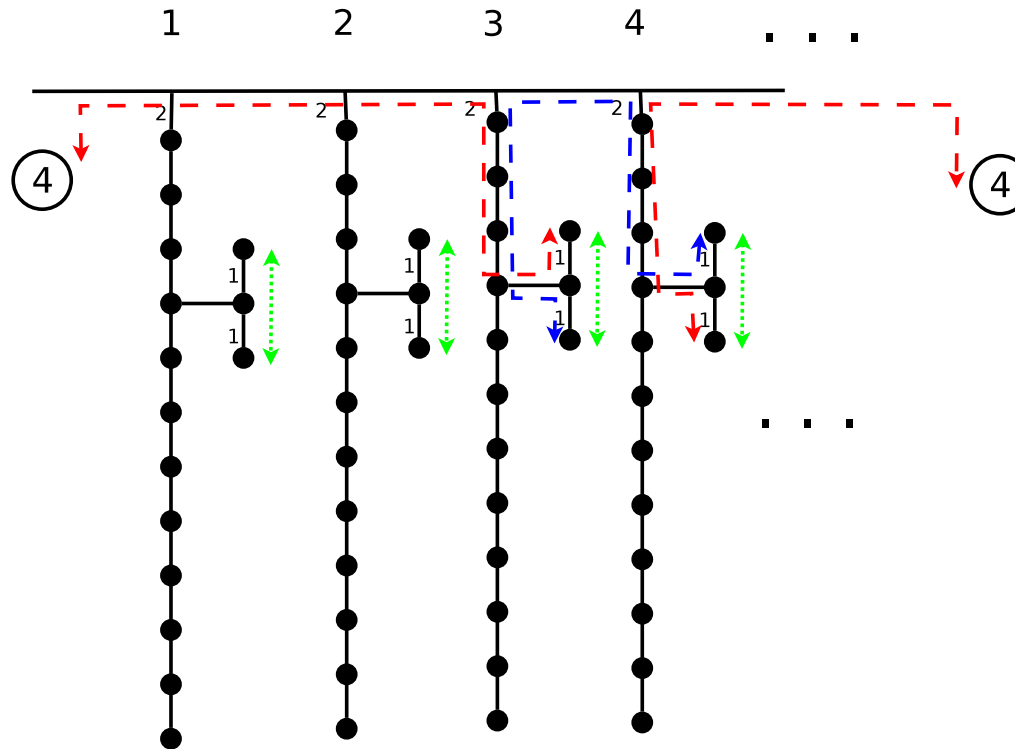
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- For each vertex of the original graph we will make a set of global demands.

Reduction

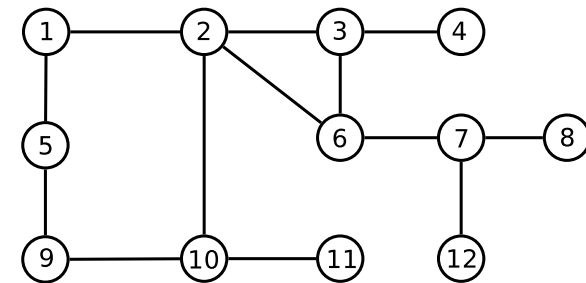
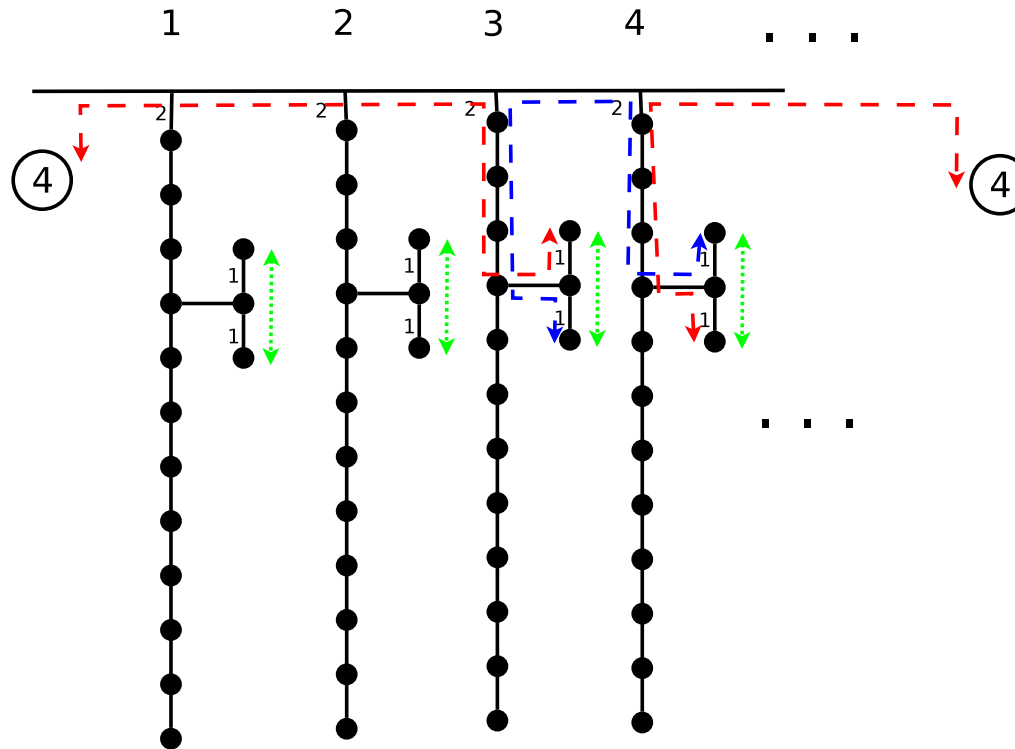
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- The global demands use up all the neighbors' branches and are enough to increase the solution by one.

Reduction

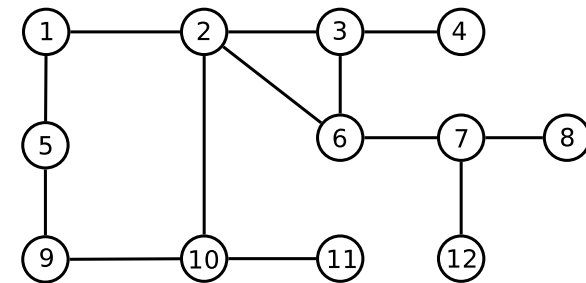
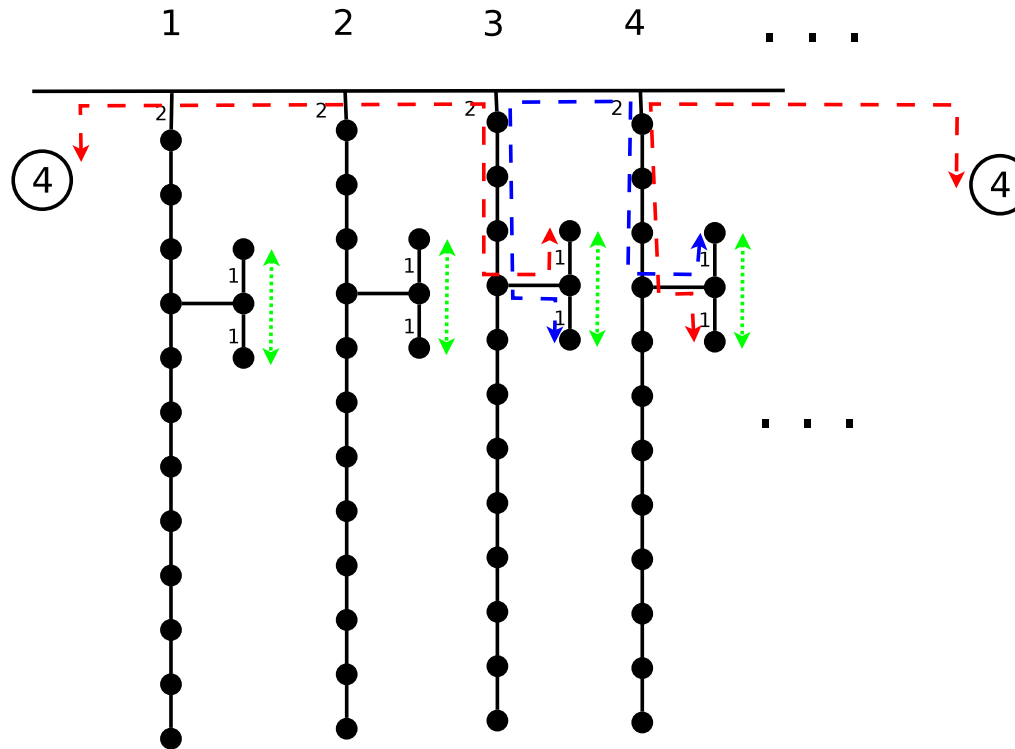
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- If we can go from n^2 to $n^2 + k$ satisfied demands then original graph has DNP of size k .
- $\Delta = 3$ and $W = 2k$.

Reduction

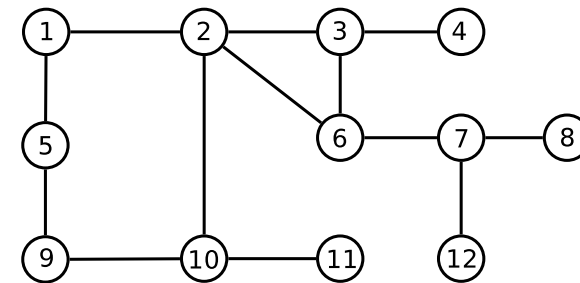
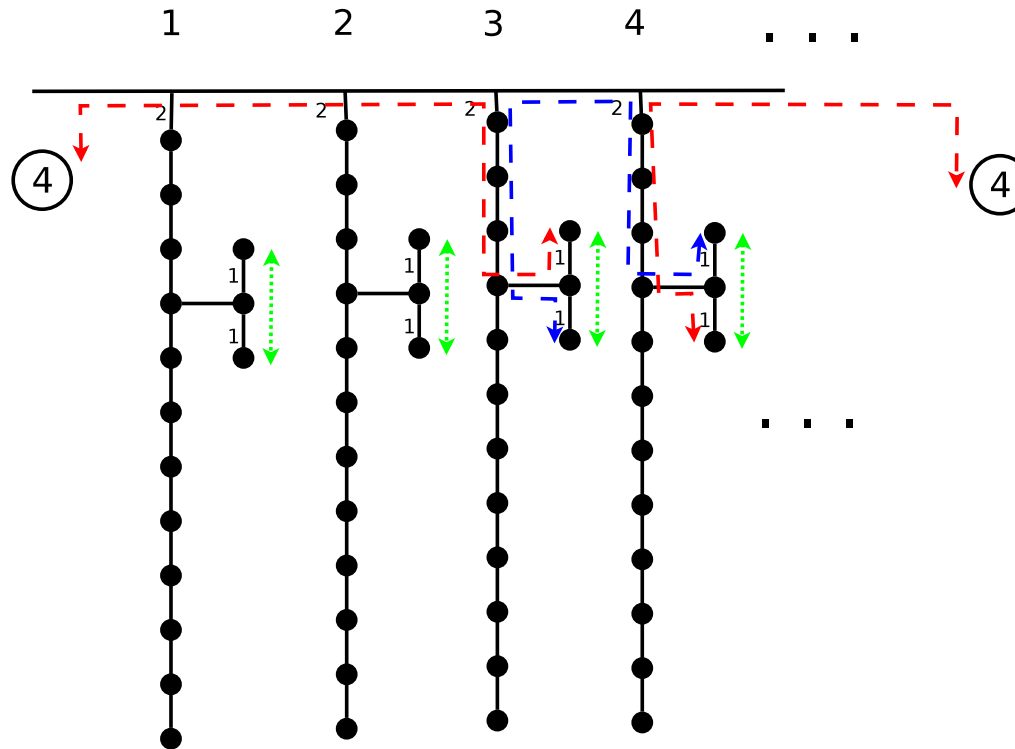
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- Reduction for treewidth: Replace backbone with a $k \times n$ grid.

Reduction

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- Reduction for Δ : Replace backbone with a vertex of degree k^2 . Use $\binom{k}{2}$ copies of this gadget to check compatibility between all pairs.

Complexity jump

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- What makes Max PC harder than PC?
 - ❖ Intuitively, we first have to decide which requests to drop, then color the rest. The first part appears to be harder.
- What if we only want to drop a small number of requests T ?

Complexity jump

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- What makes Max PC harder than PC?
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Another parameter is born...

$(p\Delta, pW, pT)$ -MaxPC

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- Recall that $(p\Delta, pW)$ -PC is FPT
 - ❖ Bottom-up dynamic programming algorithm
- So, the problem is (essentially) to pick the dropped requests
- Observation: if more than $2\Delta W + T + 1$ requests touch a vertex reject immediately
 - ❖ Even if we drop T requests one of its incident edges will have $> W$ requests going through it.
- Otherwise, do bottom-up dynamic programming again.

(pT) -MaxPC binary trees

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MaxPC on undirected binary trees

- Slice edges until we are left with stars, solve PC on each star
- Some stars are “good”, other “bad” (if all are good accept)
- If a sub-tree contains only good stars cut it off the tree
 - ❖ We can color everything there even if we don't drop any requests
- All leaf-stars are now bad

(pT) -MaxPC binary trees

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- All leaf-stars are now bad
- All of them must be touched by a dropped request
- No dropped request can touch more than two leaves
 - ❖ If more than $2T$ leaf-stars reject
- Now graph has $O(T)$ leaf-stars and internal-stars ($\Delta = 3$)
- Easy to pick one endpoint of a dropped request. If we have $O(T)$ choices for the other endpoint \rightarrow recursive $T^{O(T)}$ algorithm.

Algorithm cont'd

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- Now graph has $O(T)$ leaf-stars and internal-stars ($\Delta = 3$)
- Easy to pick one endpoint of a dropped request. If we have $O(T)$ choices for the other endpoint \rightarrow recursive $T^{O(T)}$ algorithm.
- Possible candidates are the $O(T)$ special stars and a (possible large) number of degree two stars.
 - ❖ But we can be greedy with degree two stars!
 - ❖ Pick the one that is furthest away

Algorithm cont'd

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- Possible candidates are the $O(T)$ special stars and a (possible large) number of degree two stars.
 - ❖ But we can be greedy with degree two stars!
 - ❖ Pick the one that is furthest away
- The greedy part is the only part that requires $\Delta = 3$

Open problems

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Conclusions:

- PC is easy parameterized by Δ, W , but MaxPC is hard!
- In our reductions we have to drop many requests. If we parameterize also by T things get better.

What next?

- $(p\Delta, pT)$ -MaxPC on undirected trees
- Other parameters?
- (pW) -MaxPC on rings?

The End

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Thank you!

Questions?